

On the Information Dimension of Random Variables and Stochastic Processes

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Joint work with Tobias Koch



Authors and Funders



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Rényi Information Dimension¹

X is L -dimensional and real-valued

$$d(X) \triangleq \lim_{m \rightarrow \infty} \frac{H([X]_m)}{\log m}$$

where

$$[X]_m \triangleq \frac{\lfloor mX \rfloor}{m}$$

and

$$H(Z) \triangleq - \sum_z \mathbb{P}(Z = z) \log \mathbb{P}(Z = z).$$

¹Rényi, "On the Dimension and Entropy of Probability Distributions", 1959



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(we assume throughout that the limit exists and is finite)

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Properties of Information Dimension^{2,3,4}

- ▶ Bounded:

$$0 \leq d(X) \leq L$$

²Rényi, "On the Dimension and Entropy of Probability Distributions", 1959

³Wu and Verdú, "Rényi Information Dimension: Fundamental Limits of Almost Lossless Analog Compression", 2010

⁴Wu, "Shannon Theory for Compressed Sensing", 2011



Properties of Information Dimension^{2,3,4}

- ▶ Bounded:

$$0 \leq d(X) \leq L$$

- ▶ Lipschitz Maps: (\Rightarrow Scale & Translation Invariance)

$$d(f(X)) \leq d(X)$$

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$$d(f(X)) \leq d(X)$$

- ▶ Subadditive:

$$d(X, Y) \leq d(X) + d(Y)$$

with equality if $X \perp Y$

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The Discrete, the Continuous, and the Singular⁵

- ▶ If X has a discrete distribution, then $d(X) = 0$.

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The Discrete, the Continuous, and the Singular⁵

- ▶ If X has a discrete distribution, then $d(X) = 0$.
- ▶ If X has an absolutely continuous distribution, then $d(X) = L$.

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The Discrete, the Continuous, and the Singular⁵

- ▶ If X has a discrete distribution, then $d(X) = 0$.
- ▶ If X has an absolutely continuous distribution, then $d(X) = L$.
- ▶ “It can be shown that $[d(X) = K < L]$ for absolutely continuous probability distributions on sufficiently smooth K -dimensional manifolds lying in \mathbb{R}^L .”

⁵Rényi, “On the Dimension and Entropy of Probability Distributions”, 1959



Gaussian Case

Theorem

If X is Gaussian and has covariance matrix C_X , then

$$d(X) = \text{rank}(C_X).$$



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Theorem

If X has covariance matrix C_X , then

$$d(X) \leq \text{rank}(C_X)$$

with equality if X is Gaussian.



Information Dimension is Relevant:

Communications & Information Theory:

- ▶ Rate-distortion theory^{6,7}
- ▶ Almost lossless analog compressed sensing⁸
- ▶ DoF of Gaussian interference channels^{9,10}

Dynamical Systems Theory:

- ▶ Characterization of Chaotic Attractors¹¹

⁶Kawabata and Dembo, "The rate-distortion dimension of sets and measures", 1994

⁷Koch, "The Shannon Lower Bound Is Asymptotically Tight", 2016

⁸Wu and Verdú, "Rényi Information Dimension: Fundamental Limits of Almost Lossless Analog Compression", 2010

⁹Wu, Shamai (Shitz), and Verdú, "Information Dimension and the Degrees of Freedom of the Interference Channel", 2015

¹⁰Stotz and Bölcskei, "Degrees of Freedom in Vector Interference Channels", 2016

¹¹Farmer, Ott, and Yorke, "The dimension of chaotic attractors", 1983



Generalization to Stochastic Processes

$\{\mathbf{X}_t, t \in \mathbb{Z}\}$ is an *L-variate*, real-valued, stationary process

$$d(\{\mathbf{X}_t\}) \triangleq \lim_{m \rightarrow \infty} \frac{\overline{H}(\{[\mathbf{X}_t]_m\})}{\log m}$$

where

$$\overline{H}(\{[\mathbf{X}_t]_m\}) \triangleq \lim_{n \rightarrow \infty} \frac{H([\mathbf{X}_1]_m, \dots, [\mathbf{X}_n]_m)}{n}.$$



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Properties of Information Dimension Rate

- ▶ Bounded:

$$0 \leq d(\{\mathbf{X}_t\}) \leq \lim_{n \rightarrow \infty} \frac{d(\mathbf{X}_1, \dots, \mathbf{X}_n)}{n} \leq d(\mathbf{X}_1) \leq L$$



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- ▶ Lipschitz Maps: (\Rightarrow Scale & Translation Invariance)

$$d(\{f_t(\mathbf{X}_t)\}) \leq d(\{\mathbf{X}_t\})$$



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- ▶ Lipschitz Maps: (\Rightarrow Scale & Translation Invariance)

$$d(\{f_t(\mathbf{X}_t)\}) \leq d(\{\mathbf{X}_t\})$$

- ▶ Subadditive:

$$d(\{\mathbf{X}_t, \mathbf{Y}_t\}) \leq d(\{\mathbf{X}_t\}) + d(\{\mathbf{Y}_t\})$$

with equality if $\{\mathbf{X}_t\} \perp \{\mathbf{Y}_t\}$



The Discrete, the Continuous, and the Bandlimited

Consider a scalar ($L = 1$) process $\{X_t\}$:

- ▶ If $\{X_t\}$ is discrete-valued, then $d(\{X_t\}) = 0$.



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The Discrete, the Continuous, and the Bandlimited

Consider a scalar ($L = 1$) process $\{X_t\}$:

- ▶ If $\{X_t\}$ is discrete-valued, then $d(\{X_t\}) = 0$.
- ▶ If $\{X_t\}$ is continuous-valued and i.i.d., then $d(\{X_t\}) = 1$.
- ▶ If $\{X_t\}$ is Gaussian with bandlimited power spectral density S_X , is there a connection between $d(\{X_t\})$ and the bandwidth?



Gaussian Process

Corollary

If $\{X_t\}$ is a *scalar*, Gaussian process with power spectral density S_X , then

$$d(\{X_t\}) = \lambda(\{\theta: S_X(\theta) > 0\}).$$



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Example

Let $\{X_t\}$ be Gaussian and have power spectral density $S_X: [-\frac{1}{2}, \frac{1}{2}] \rightarrow \mathbb{R}^+$ positive on $[-\frac{1}{4}, \frac{1}{4}]$ and zero elsewhere (low-pass process). Then,

$$d(\{X_t\}) = \frac{1}{2}.$$

Gaussian Process (cont'd)

Theorem

If $\{\mathbf{X}_t\}$ is Gaussian and has power spectral density $S_{\mathbf{X}}$, then

$$d(\{\mathbf{X}_t\}) = \int_{-1/2}^{1/2} \text{rank}(S_{\mathbf{X}}(\theta)) d\theta.$$

$$\left(\mathbb{E}(\mathbf{X}_{t+\tau} \mathbf{X}_t^T) - \mathbb{E}(\mathbf{X}_{t+\tau}) \mathbb{E}(\mathbf{X}_t^T) = \int_{-1/2}^{1/2} S_{\mathbf{X}}(\theta) e^{-i2\pi\tau\theta} d\theta \right)$$

Gaussian Process (cont'd)

Theorem

If $\{\mathbf{X}_t\}$ has power spectral density $S_{\mathbf{X}}$, then

$$d(\{\mathbf{X}_t\}) \leq \int_{-1/2}^{1/2} \text{rank}(S_{\mathbf{X}}(\theta)) d\theta$$

with equality if $\{\mathbf{X}_t\}$ is Gaussian.

$$\left(\mathbb{E}(\mathbf{X}_{t+\tau} \mathbf{X}_t^T) - \mathbb{E}(\mathbf{X}_{t+\tau}) \mathbb{E}(\mathbf{X}_t^T) = \int_{-1/2}^{1/2} S_{\mathbf{X}}(\theta) e^{-i2\pi\tau\theta} d\theta \right)$$



Lebesgue Decomposition

Corollary

If $\{\mathbf{X}_t\}$ has spectral distribution function

$$F_{\mathbf{X}}(\theta) = F_{\mathbf{X}}^{ac}(\theta) + F_{\mathbf{X}}^d(\theta) + F_{\mathbf{X}}^s(\theta)$$

then

$$d(\{\mathbf{X}_t\}) = d(\{\mathbf{X}_t^{ac}\})$$

where $\{\mathbf{X}_t^{ac}\}$ has spectral distribution function $F_{\mathbf{X}}^{ac}$.

$$\left(\mathbb{E} \left(\mathbf{X}_{t+\tau} \mathbf{X}_t^T \right) - \mathbb{E} \left(\mathbf{X}_{t+\tau} \right) \mathbb{E} \left(\mathbf{X}_t^T \right) = \int_{-1/2}^{1/2} e^{-i2\pi\tau\theta} dF_{\mathbf{X}}(\theta) \right)$$



Information Dimension Rate is Relevant, too:

Communications & Information Theory:

- ▶ Rate-distortion theory
- ▶ $\lim_{n \rightarrow \infty} \frac{d(\mathbf{X}_1, \dots, \mathbf{X}_n)}{n}$ is a necessary rate for almost error-free compressed sensing¹²
- ▶ $d(\{\mathbf{X}_t\})$ is a sufficient rate for asymptotically distortion-free compressed sensing^{13,14}
- ▶ Fact $d(\{\mathbf{X}_t\}) < \lim_{n \rightarrow \infty} \frac{d(\mathbf{X}_1, \dots, \mathbf{X}_n)}{n}$ for, e.g., bandlimited Gaussian processes reveals fundamental difference between error-free and distortion-free compressed sensing

Dynamical Systems Theory:

- ▶ Causality? (back-up slides)

¹²Wu and Verdú, "Optimal Phase Transitions in Compressed Sensing", 2012

¹³Jalali and Poor, "Universal Compressed Sensing for Almost Lossless Recovery", 2017

¹⁴Rezagah et al., "Compression-Based Compressed Sensing", 2017



Conclusions

- ▶ Information dimension for stochastic processes
- ▶ Intricately connected with bandwidth
- ▶ Relevant quantity in asymptotically distortion-free compressed sensing
- ▶ Generalization to causality measure currently unclear

Proofs, results for non-existing limits:

1702.00645



Conclusions

- ▶ Information dimension for stochastic processes
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Proofs, results for non-existing limits:

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Thanks for your attention!



Potential Connection to Causality

$$d(\{\mathbf{X}_t\}|\{\mathbf{Y}_t\}) \triangleq \lim_{m \rightarrow \infty} \lim_{n \rightarrow \infty} \frac{H([\mathbf{X}_1]_m, \dots, [\mathbf{X}_n]_m | \{\mathbf{Y}_t\})}{n \log m}$$

$$d(\{\mathbf{X}_t\}||\{\mathbf{Y}_t\}) \triangleq \lim_{m \rightarrow \infty} \lim_{n \rightarrow \infty} \frac{H([\mathbf{X}_1]_m, \dots, [\mathbf{X}_n]_m | \{\mathbf{Y}_t, t \leq n\})}{n \log m}$$

(we are not sure what proper definitions should look like!)

Conjecture

$$d(\{\mathbf{X}_t\}|\{\mathbf{Y}_t\}) \leq d(\{\mathbf{X}_t\}||\{\mathbf{Y}_t\})$$

with equality if $\mathbf{X}_t = f(\mathbf{Y}_t, \mathbf{Y}_{t-1}, \dots) + \mathbf{E}_t$.



Potential Connection to Causality (cont'd)

Open Questions:

- ▶ Proper definitions of $d(\{\mathbf{Y}_t\}|\{\mathbf{X}_t\})$ and $d(\{\mathbf{Y}_t\}||\{\mathbf{X}_t\})$
- ▶ Investigating the Gaussian case
- ▶ Connections with causal/non-causal Wiener filters in the Gaussian case?
- ▶ Connections with directed information/transfer entropy?