

EUROPEAN MICROWAVE WEEK 2019

SIX DAYS · THREE CONFERENCES · ONE EXHIBITION

PORTE DE VERSAILLES PARIS, FRANCE
29TH SEPTEMBER - 4TH OCTOBER 2019

Exhibition Hours:
Tuesday, 1st October 9.30 - 18.00
Wednesday 2nd October 9.30 - 17.30
Thursday 3rd October 9.30 - 16.30
www.eumweek.com



WS WTh-02 (EuMC/EuRAD)

Implementing Radar Target Stimulation on an Automotive Testbed

M. Gadringer^{#1}, M. Vorderderfler^{#1}, H. Schreiber^{#1}, S. Metzner^{#2}, W. Bösch^{#1}

^{#1} Institute of microwave and photonic engineering, Graz University of Technology, Austria

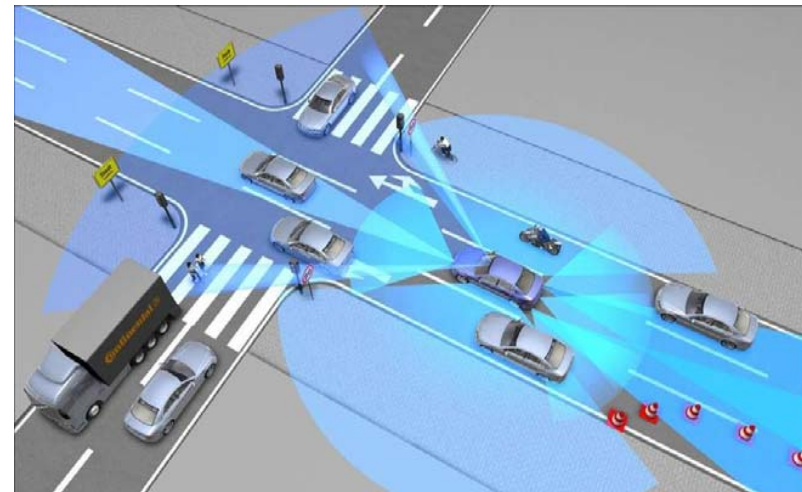
^{#2}AVL List GmbH, Graz

{¹michael.gadringer, ²michael.vorderderfler, ³helmut.schreiber, ⁵wbosch}@tugraz.at,
⁴Steffen.Metzner@avl.com



Why Radar Target Stimulation

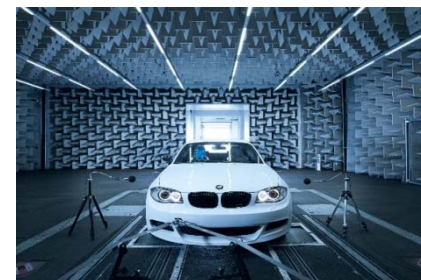
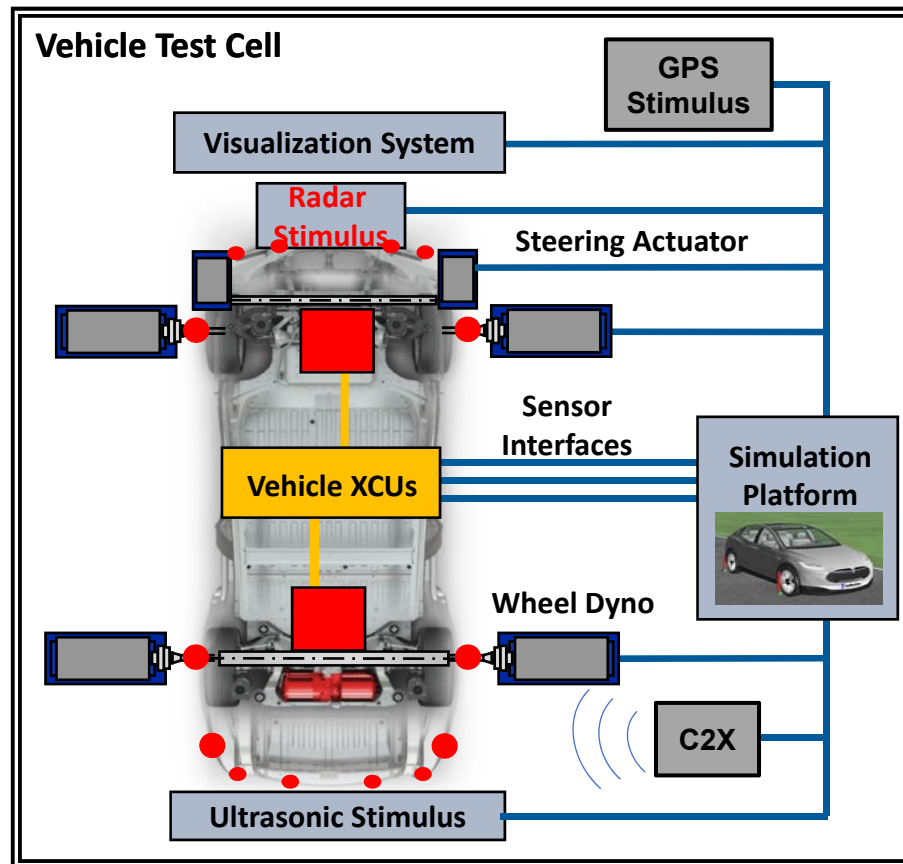
- Increasing functionality of Advanced Driving Assistance Systems (ADAS) depend on radar sensors
- Supports early adoption of Autonomous Driving (AD)
- Reliability during interference needs to be studied
- Verification of ADAS and AD in complex scenarios
- Millions of real world test kilometers are not affordable



from: <http://articles.sae.org/10794/>

Vehicle Stimulation

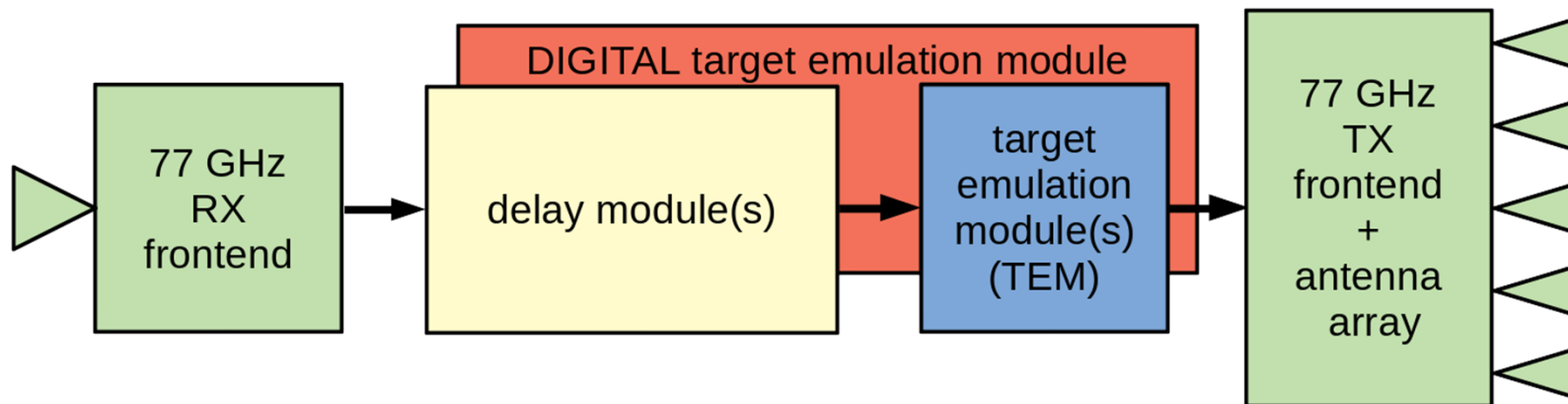
- Torque
- Ultrasonic sensors
- Steering actuator
- Camera
- Car2X
- GPS
- Radar sensor
- LiDAR





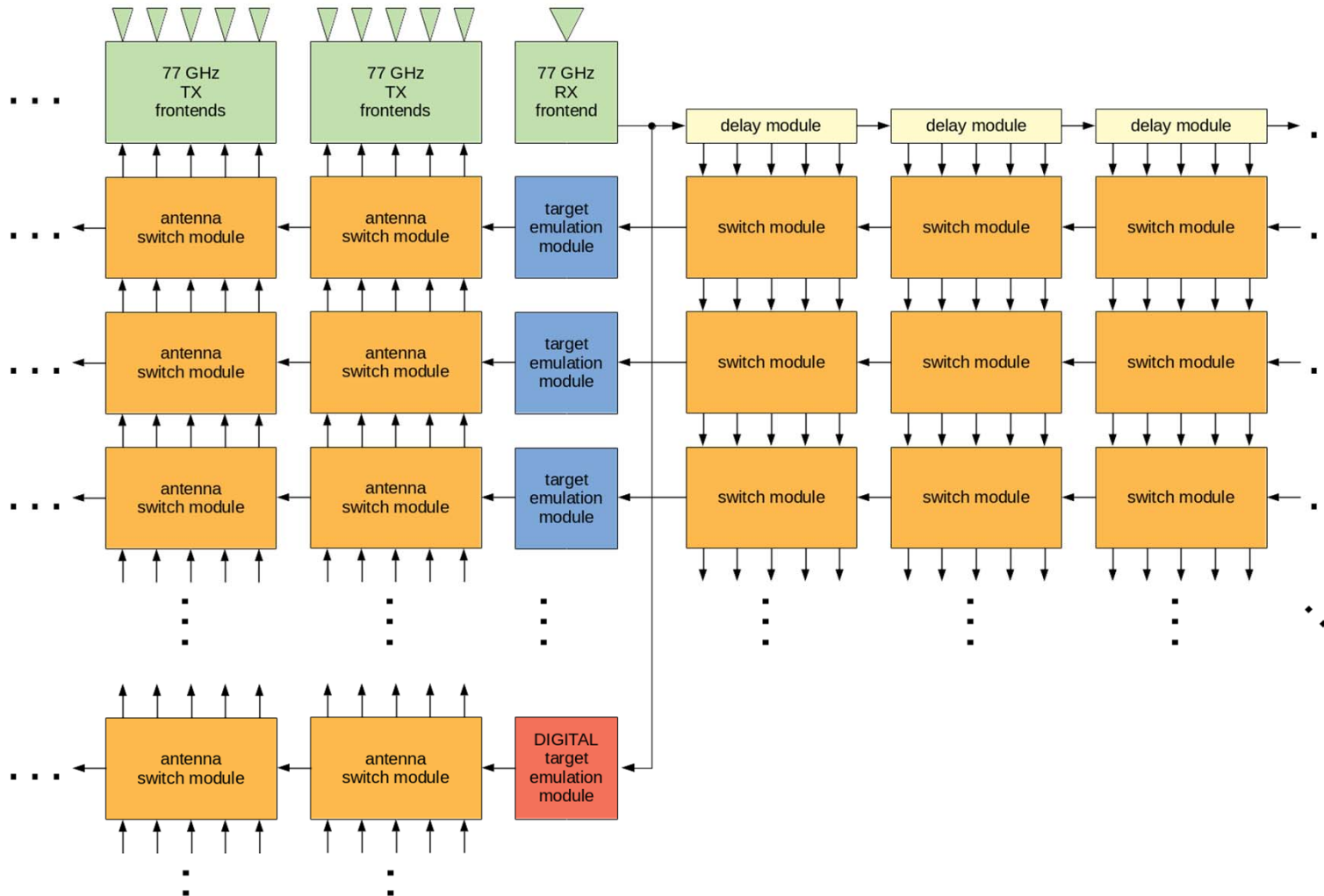
Basic Concept

- Processing at intermediate frequency (2 GHz)
- Modular design
- Scalability
- Addition of interference signals possible





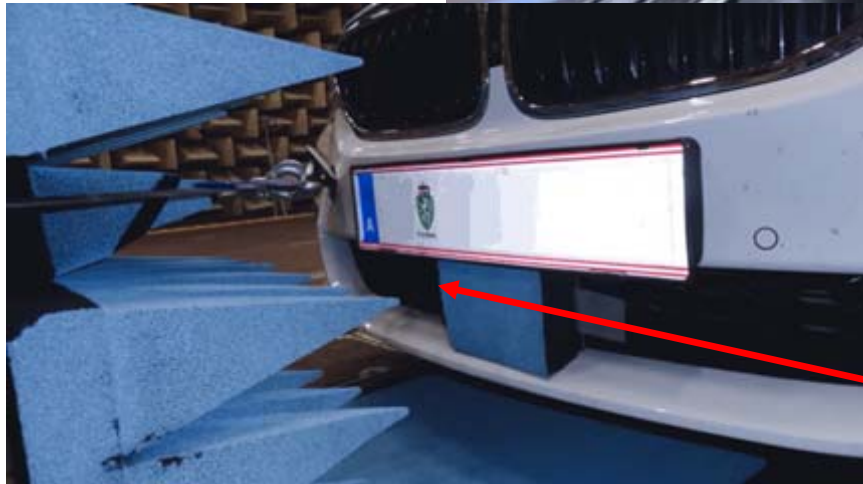
Overall Concept



Demo On a Dyno Testbed

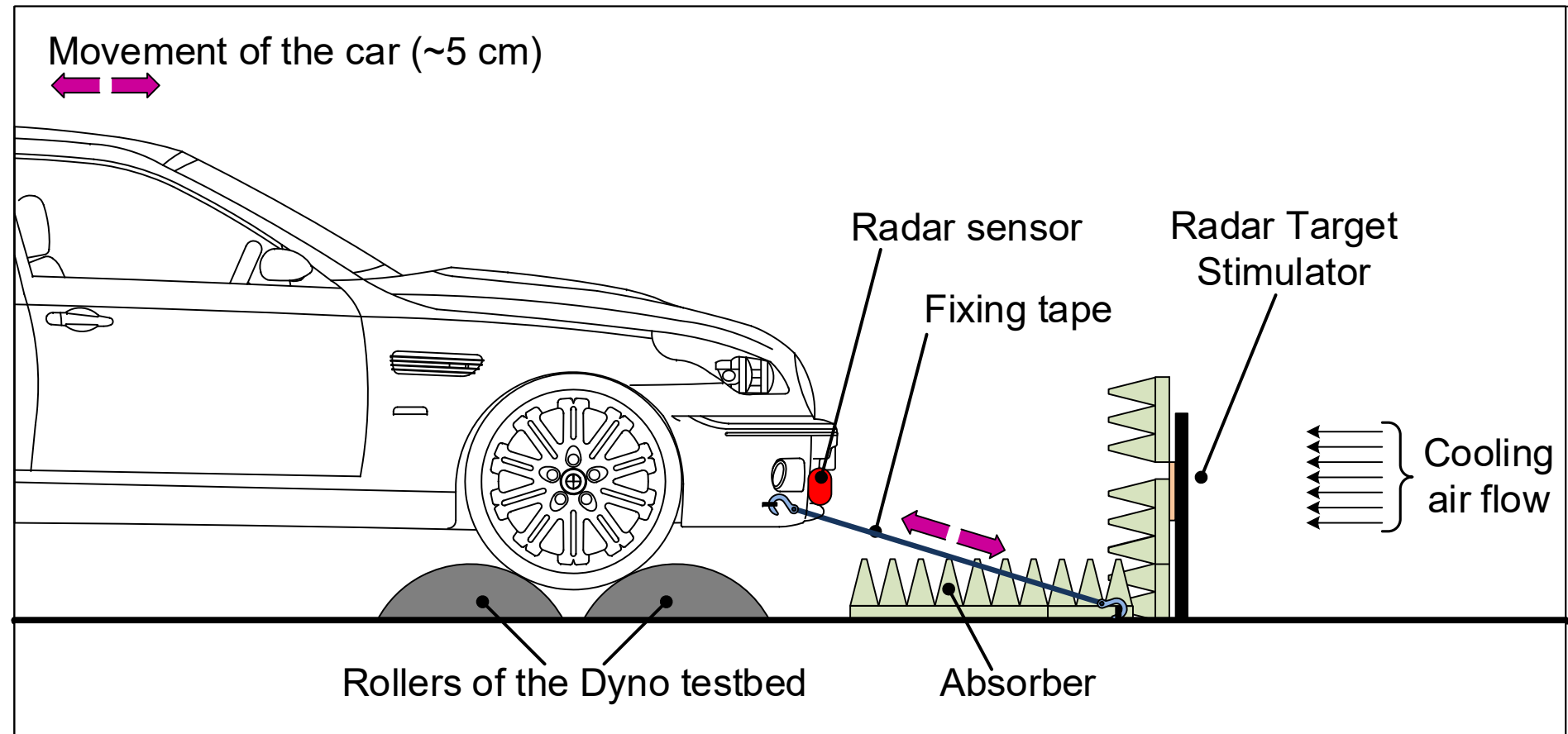


What Did We Avoid To Tell You?

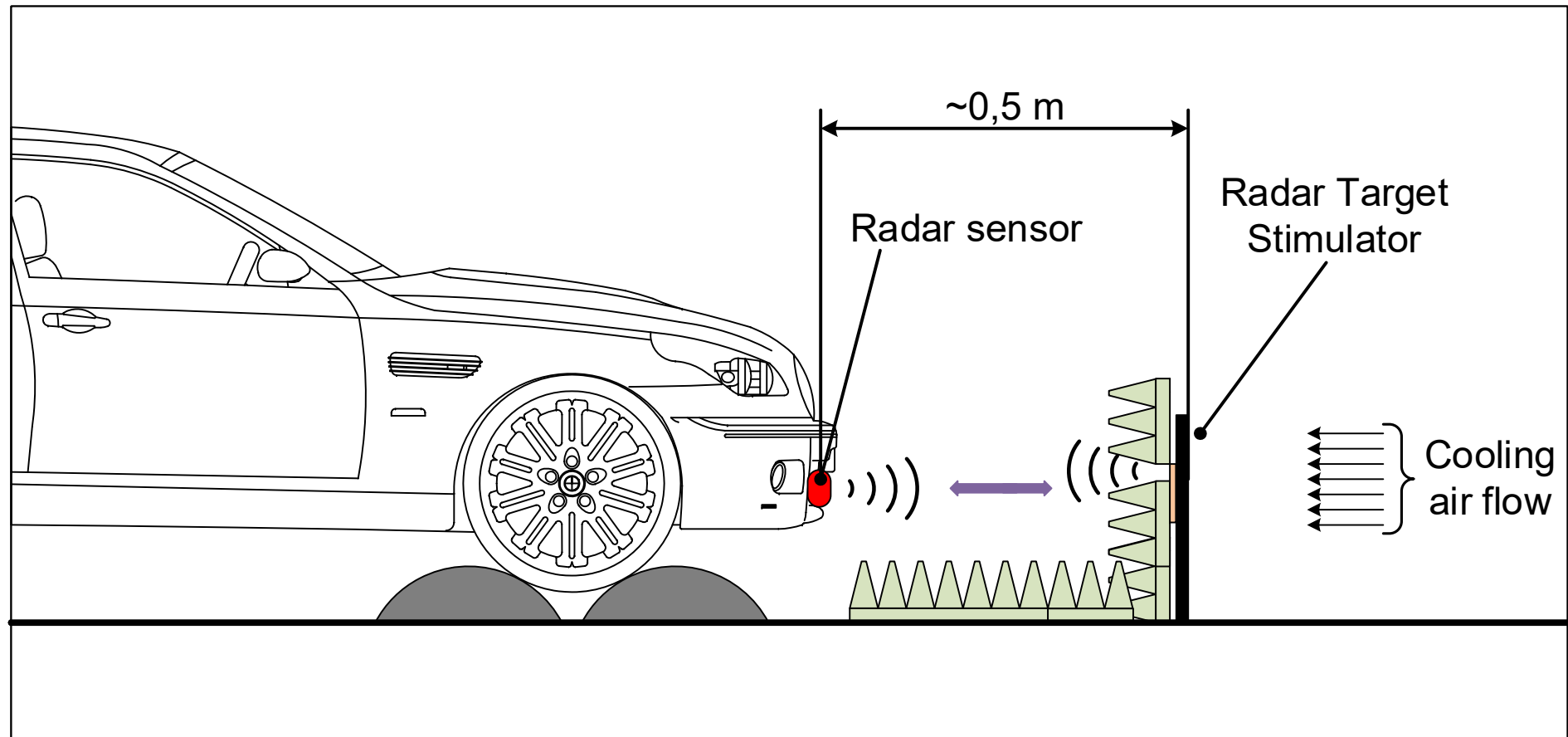


BMW mounted on a Dyno testbed
Radar Target Stimulator (RTS) mounted in front
of the sensor

Car On a Dyno Testbed



Car On a Dyno Testbed Radar Wave Propagation





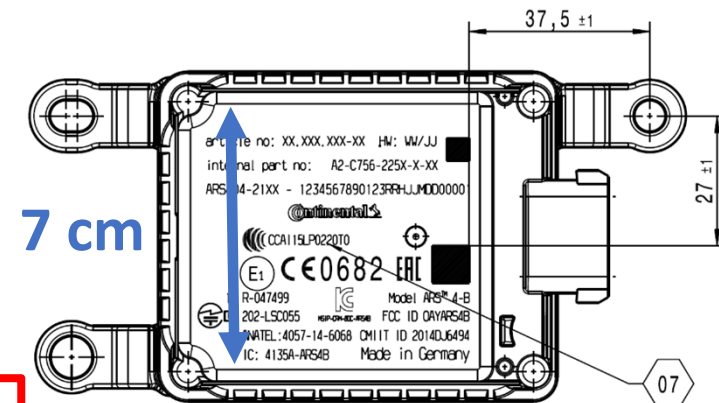
Fraunhofer Distance for a Radar Sensor

estimated for a Continental ARS-408 based on 7 cm max. antenna dimension

Fraunhofer distance @ 80 GHz:

$$\frac{2D^2}{\lambda} = 2,6 \text{ m}$$

At a distance of 0.5 m to the RTS we will recognize an influence of the antennas



Taken from:
Short Description ARS 408-21 (Premium) Long Range Radar Sensor 77 GHz Technical Data Version 1.03 en



Car On a Dyno Testbed

Interaction Sensor vs. Stimulator

Testbed environment:

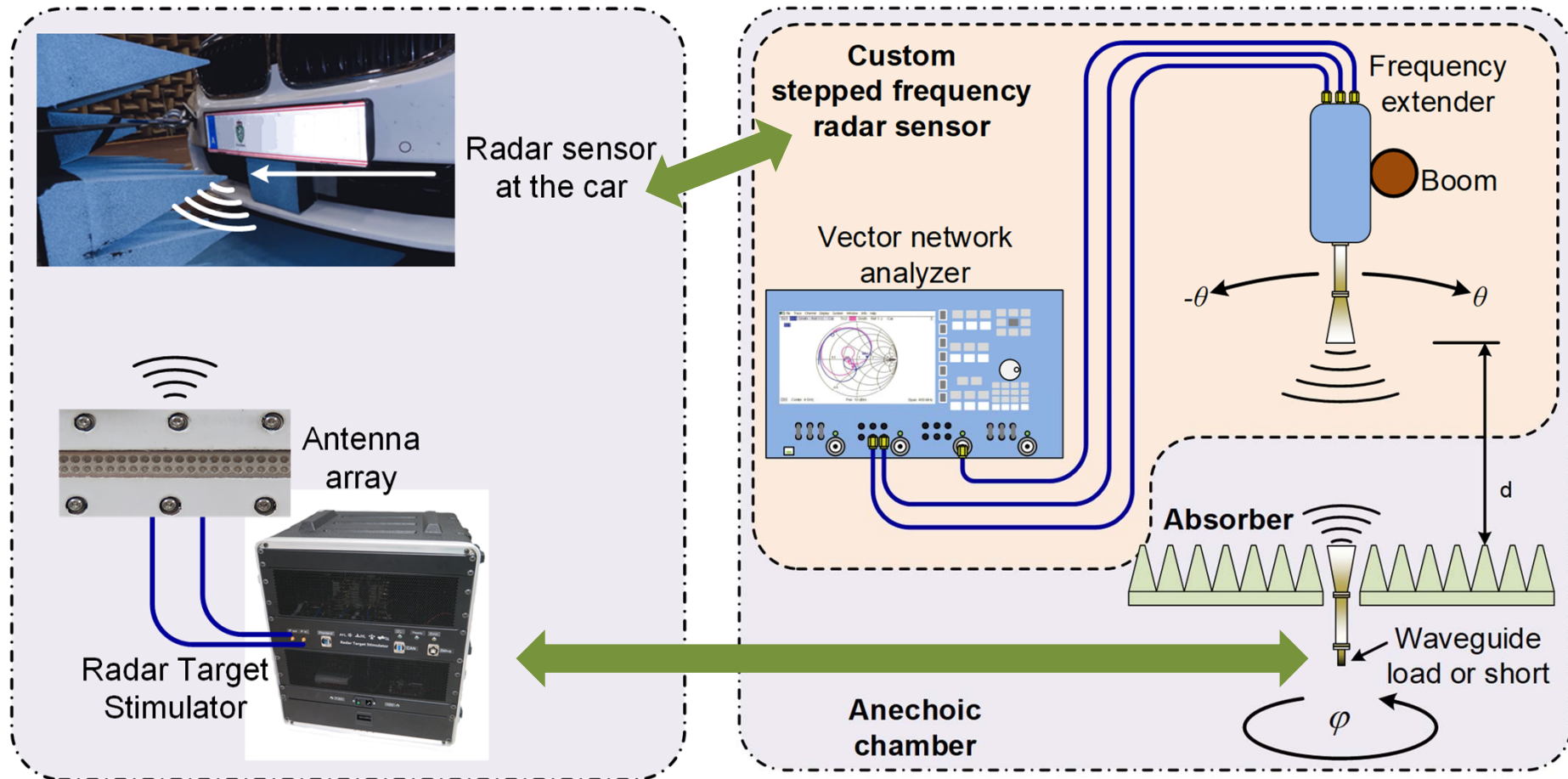
- Industrial environment with limited space
- Close stimulation distance desired

Questions imposed:

- Do sensor and the stimulator antennas influence each other?
- Does the clutter introduced by the stimulator antenna distort the sensor?
- Influence of the stimulator antenna pattern?

⇒ **Measurement of the interaction between sensor vs. stimulator desired**

Interaction Sensor vs. Stimulator Resulting measurement setup

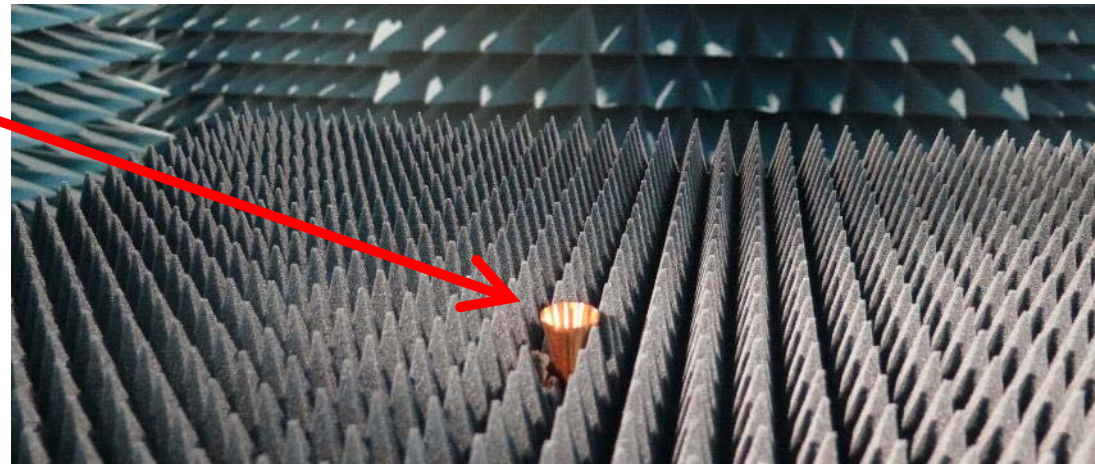
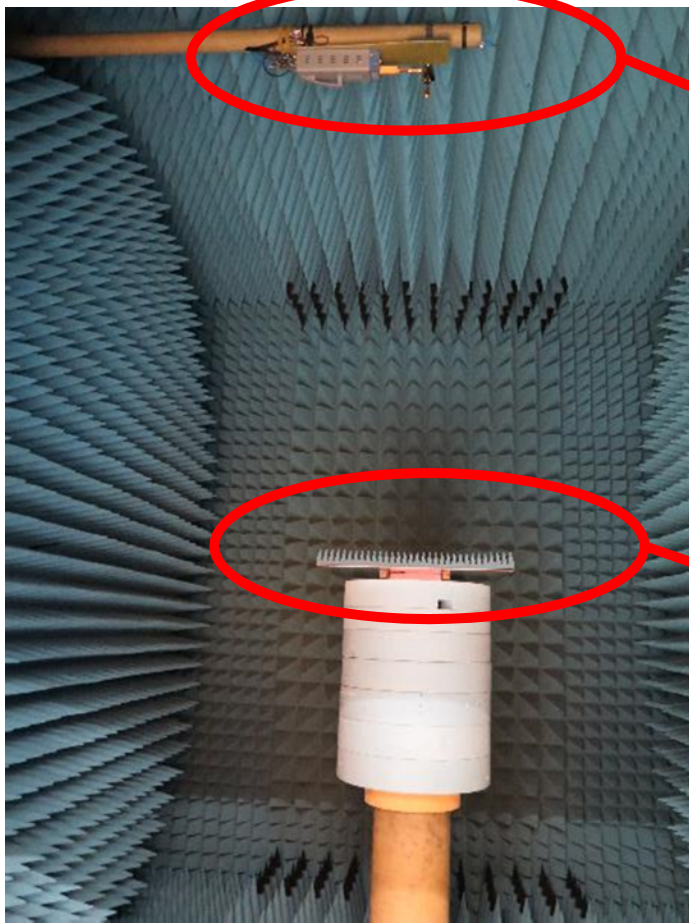




Custom radar sensor Requirements

- Flexible configurable sensor
 - Capable of conducting high dynamic measurements
 - Capable of conducting wideband measurements
 - Full control of the gathered data
- ➔ Using a vector network analyzer (VNA) as a custom radar sensor
- ➔ Locate the measurement setup in an anechoic chamber

Interaction Sensor vs. Stimulator Resulting measurement setup





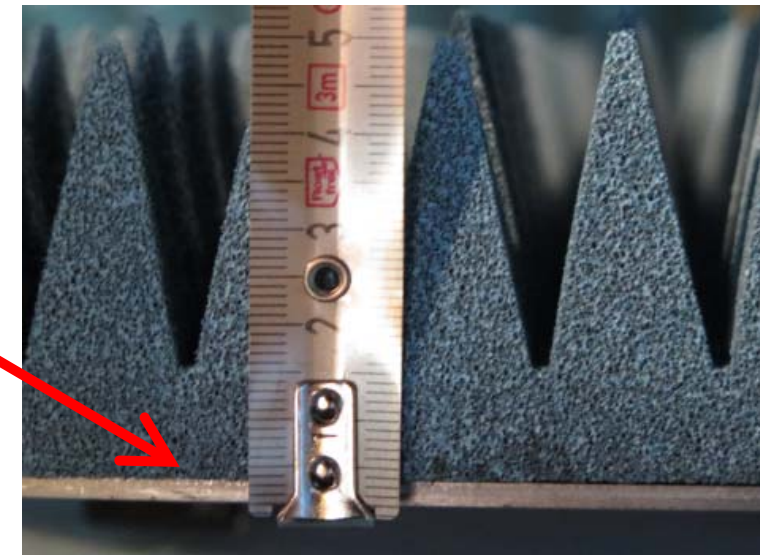
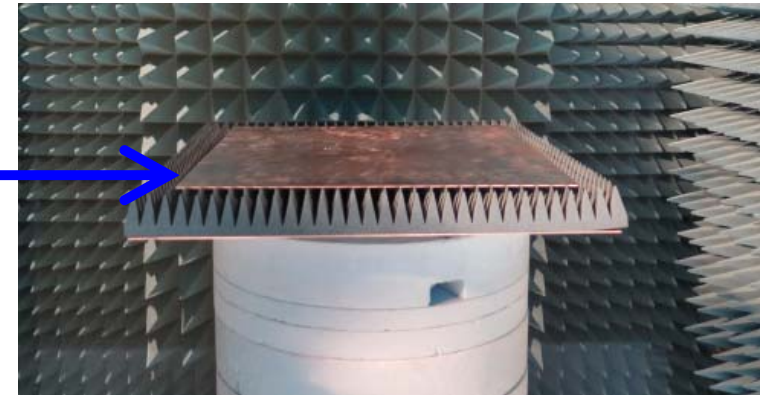
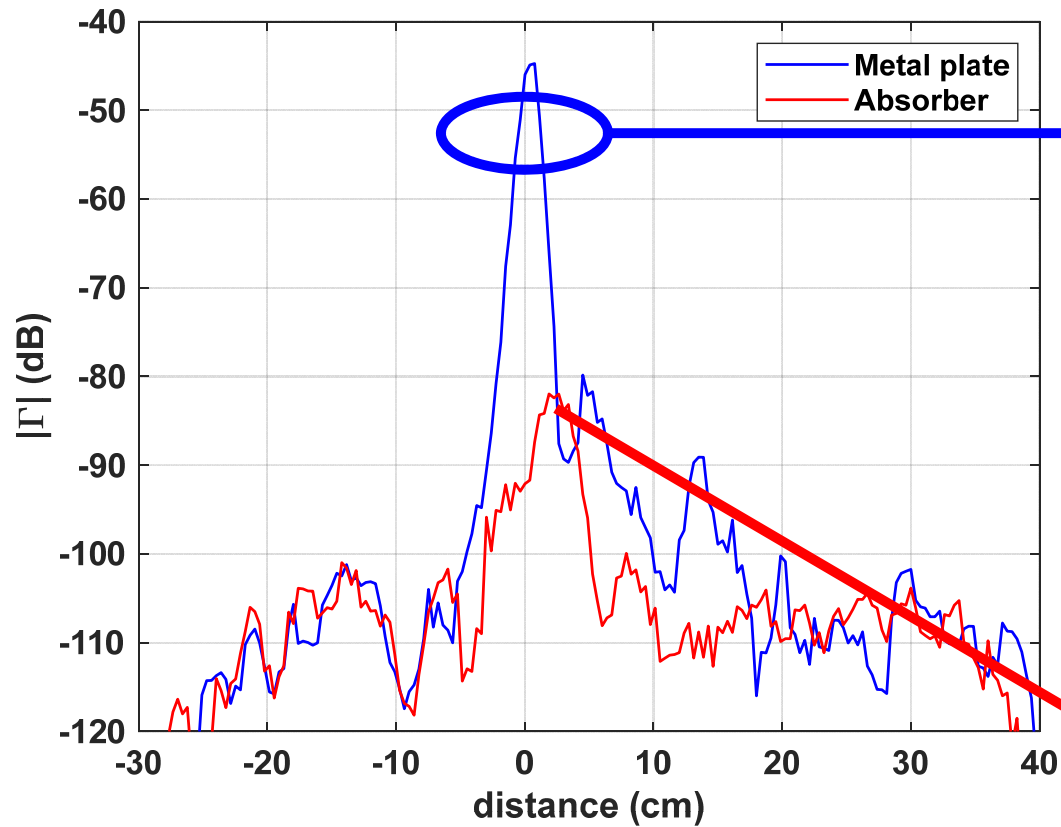
Measurement setup parameters

- Reference horn: Quinstar E-Band, 20dBi
- Frequency range: 70 – 90 GHz, step size 10 MHz
- Calibration: E-Band waveguide SOL calibration at the reference horn flange
- Analyze the measurement results in the time domain (synthetic range profile)
- Measurement distance resolution (free space)

$$\Delta d = \frac{c_0}{2B} = 7.5 \text{ mm}$$

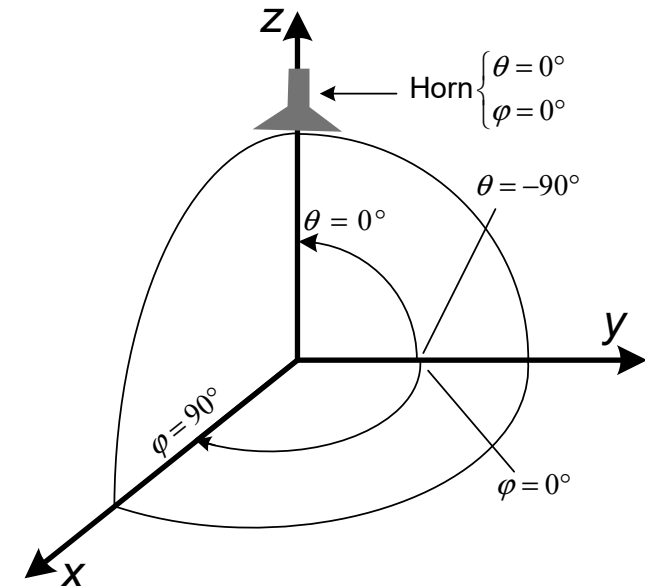
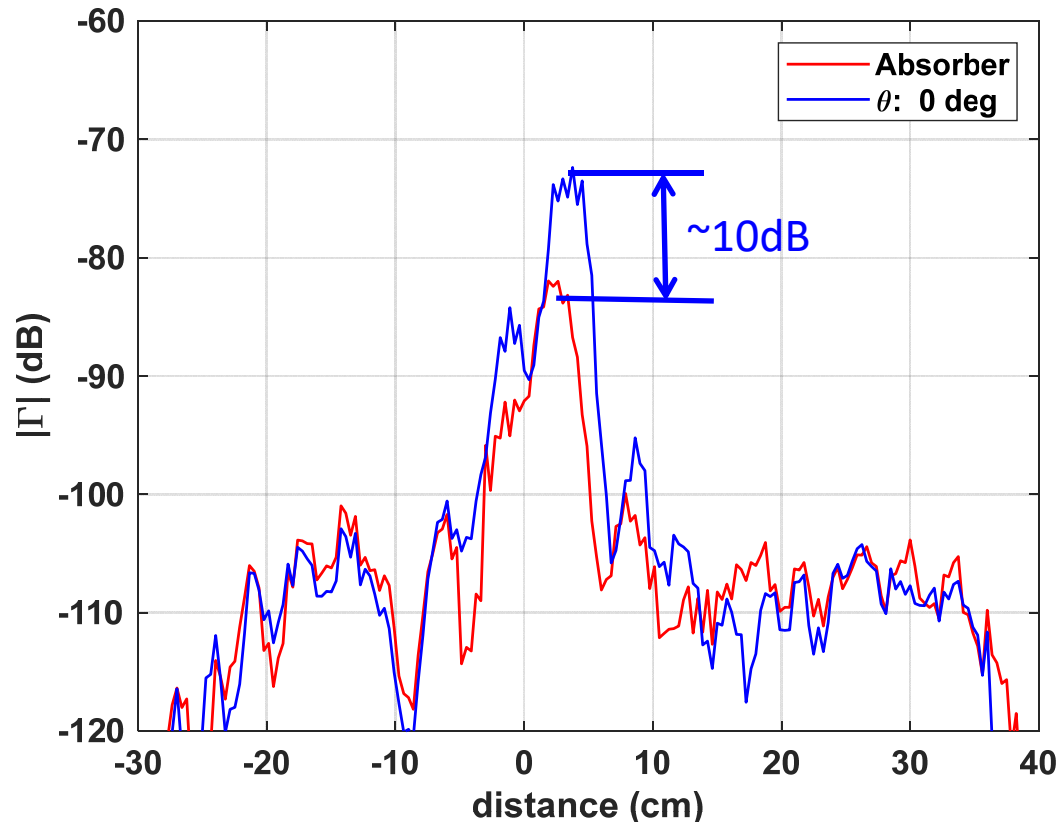
- Unambiguous range: 15m

Chamber characterization

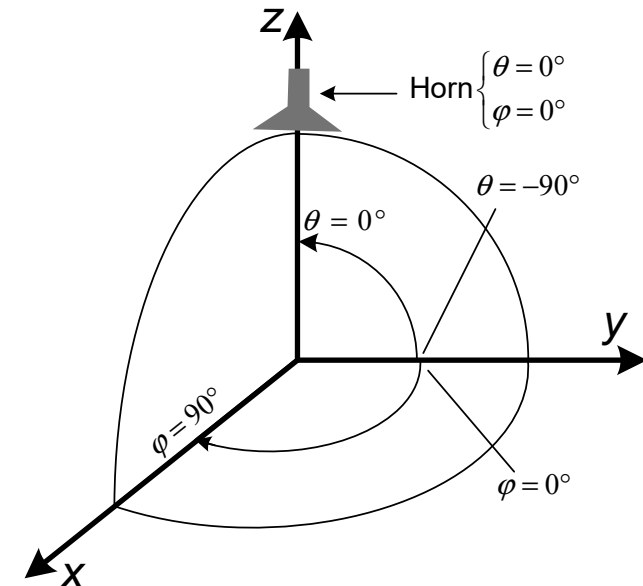
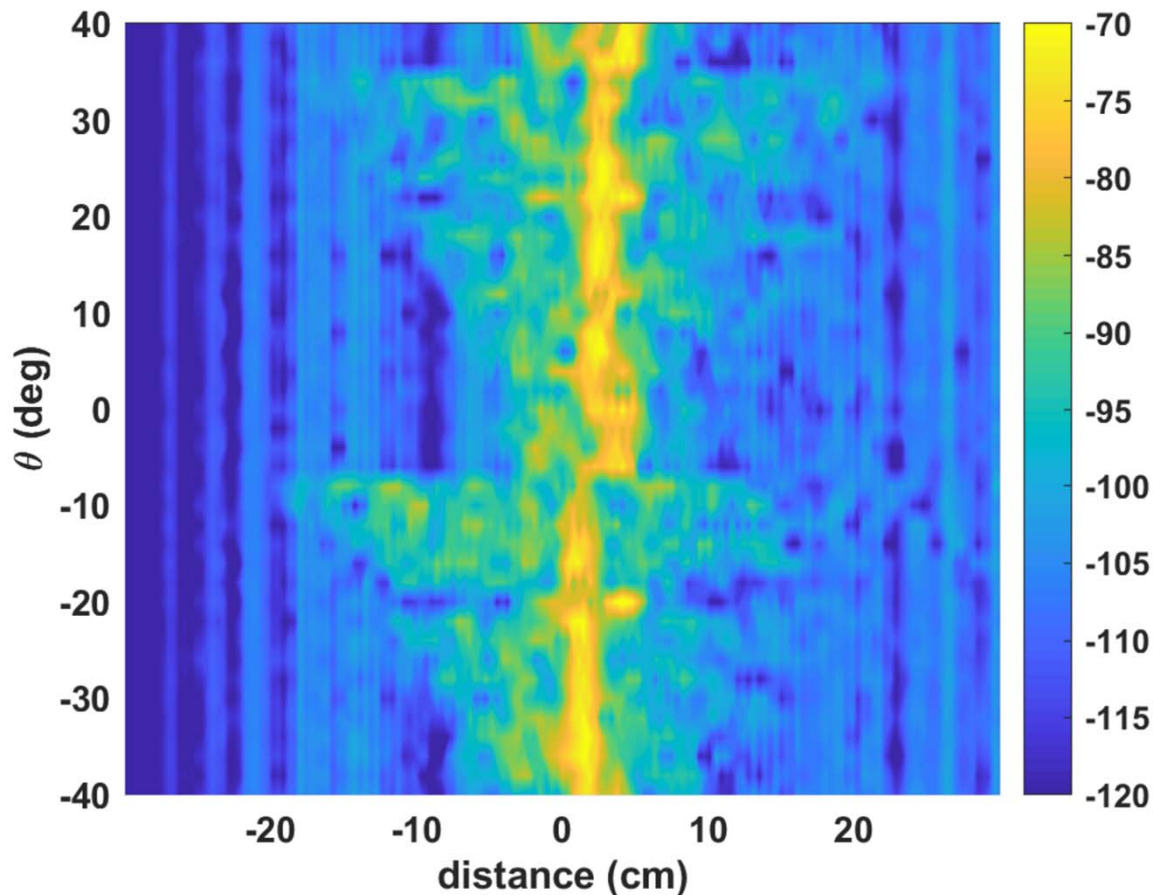


RTS horn antenna measurement

- Waveguide output terminated
- co-polarized



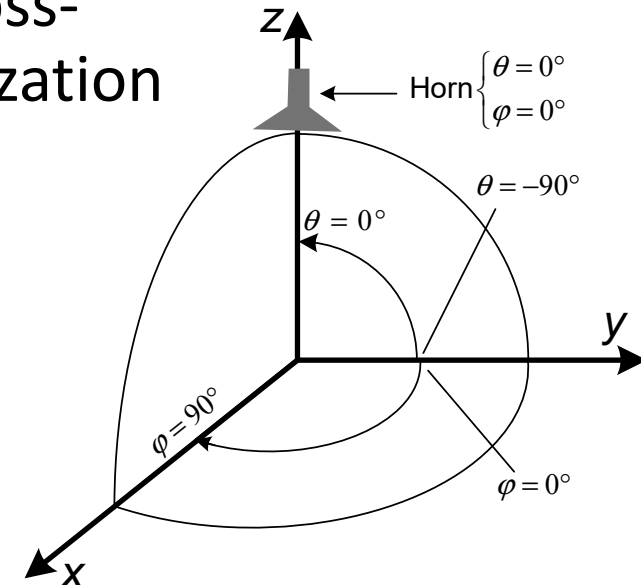
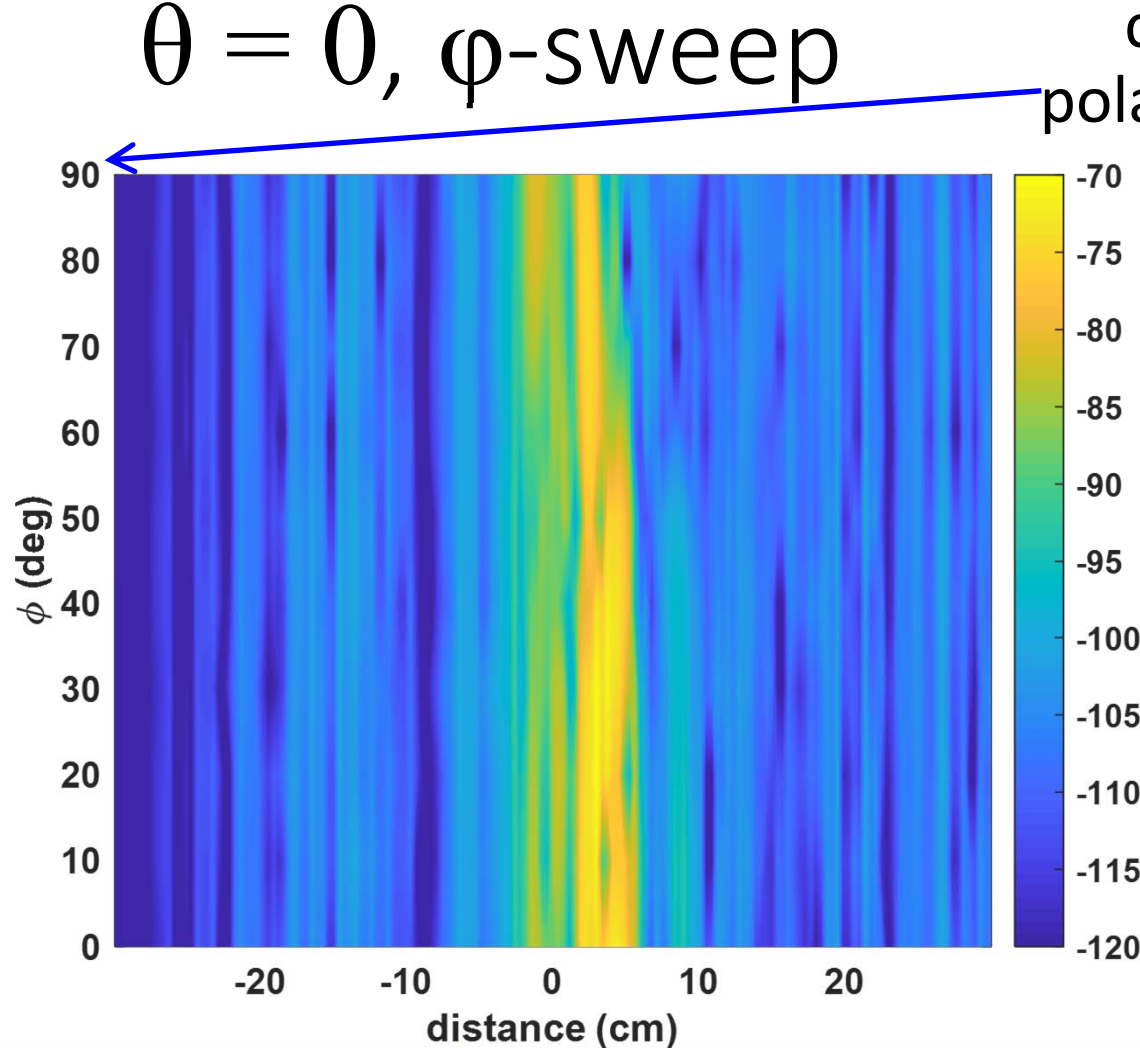
RTS horn antenna measurement θ -sweep





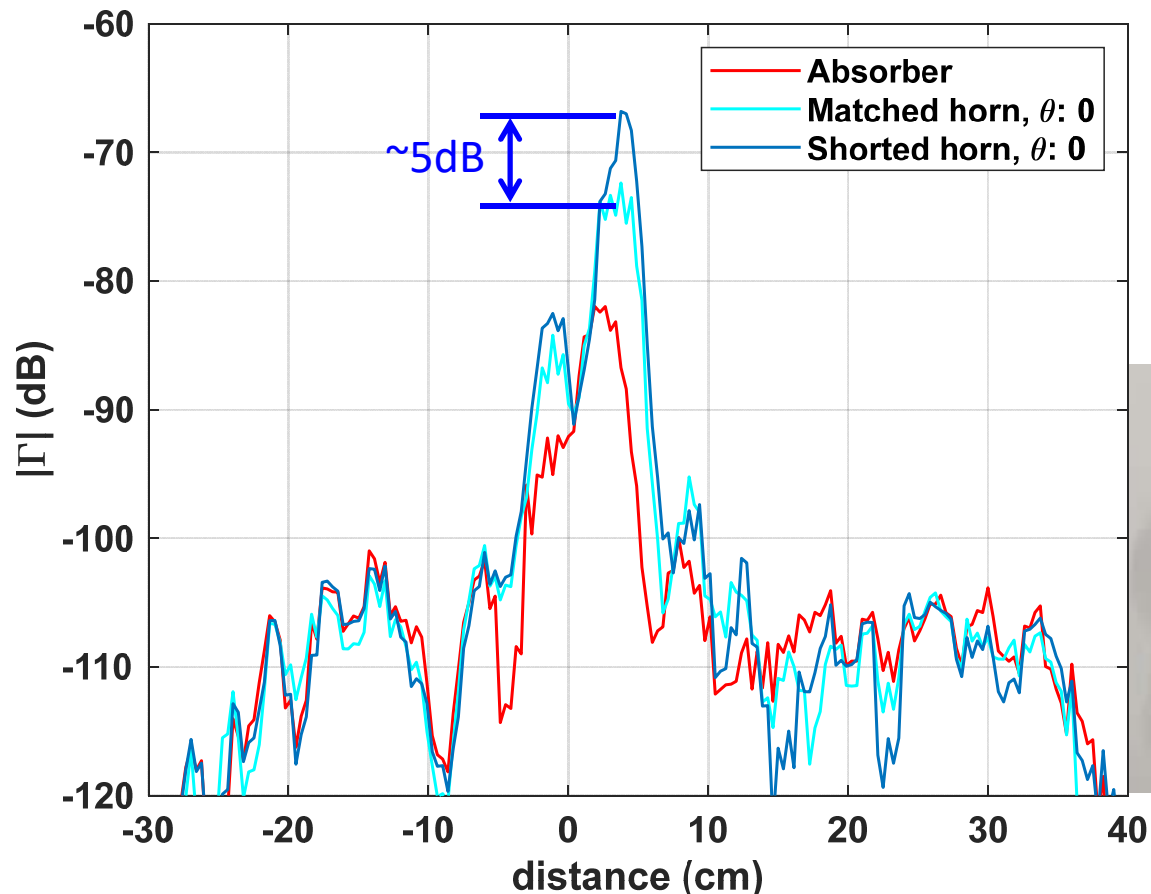
RTS horn antenna measurement

$\theta = 0, \varphi$ -sweep



RTS horn antenna measurement

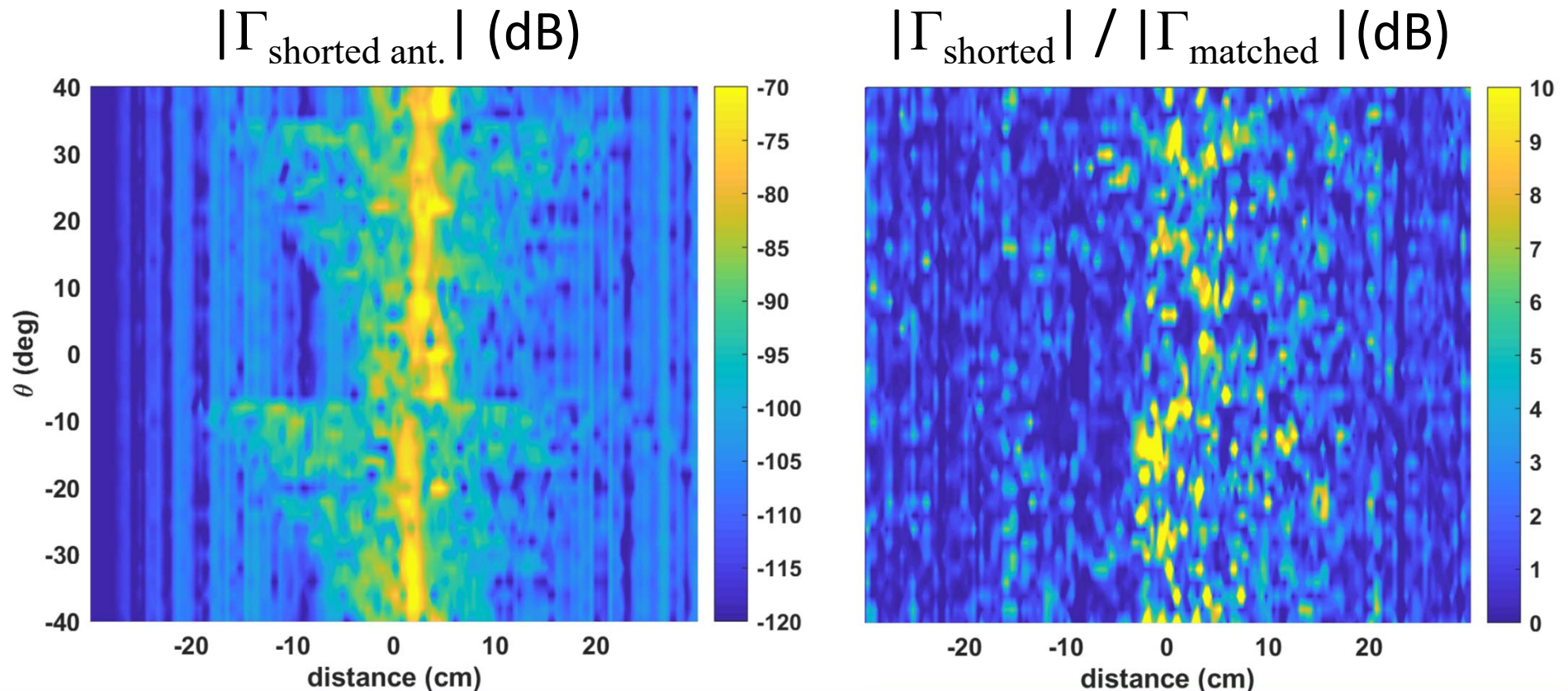
Shorted waveguide input



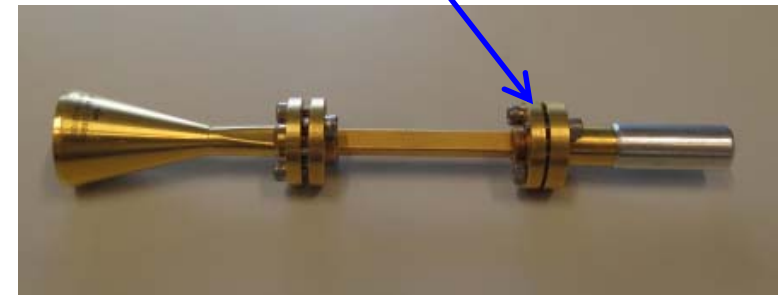
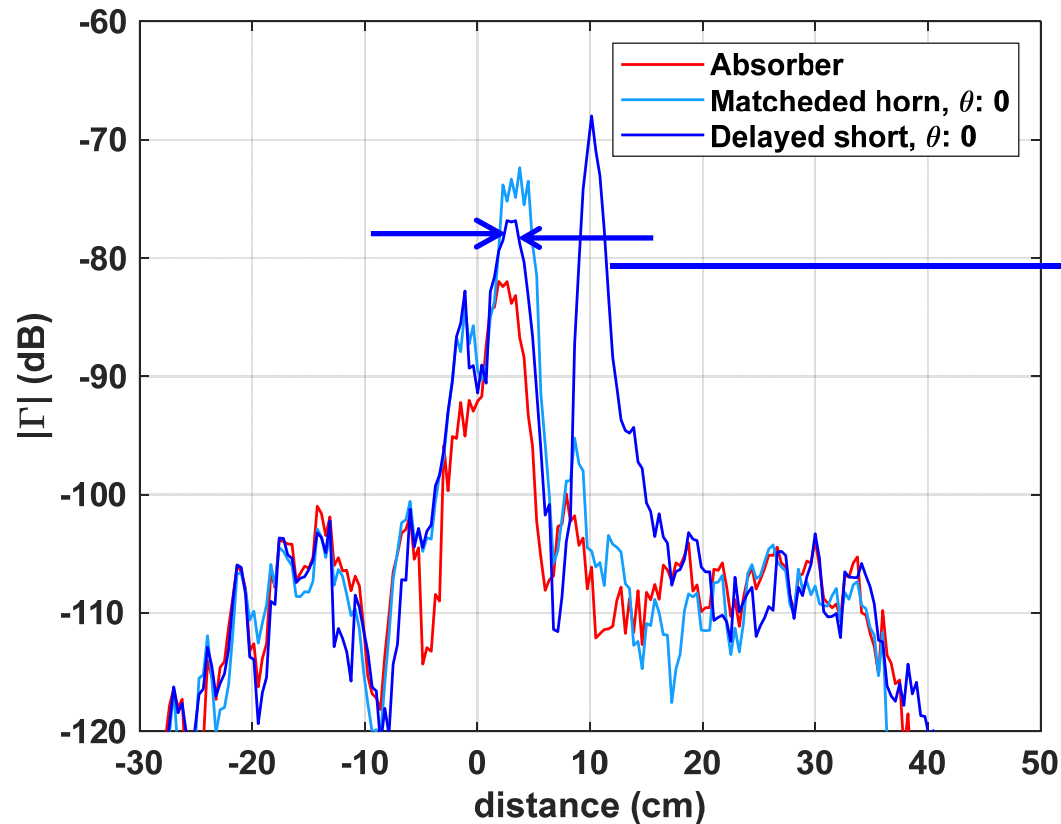


RTS horn antenna measurement

Shorted waveguide input

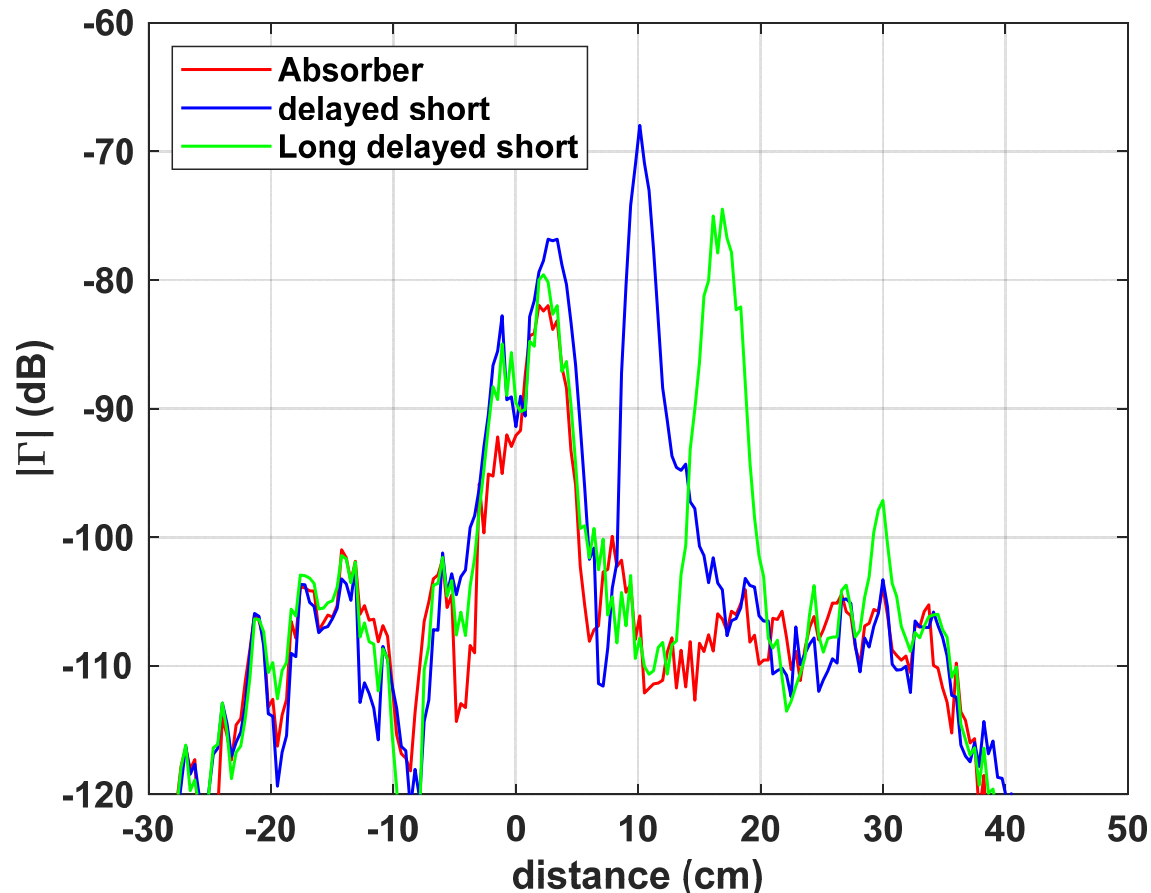


RTS horn antenna measurement Delayed short





RTS horn antenna measurement Short + two waveguides



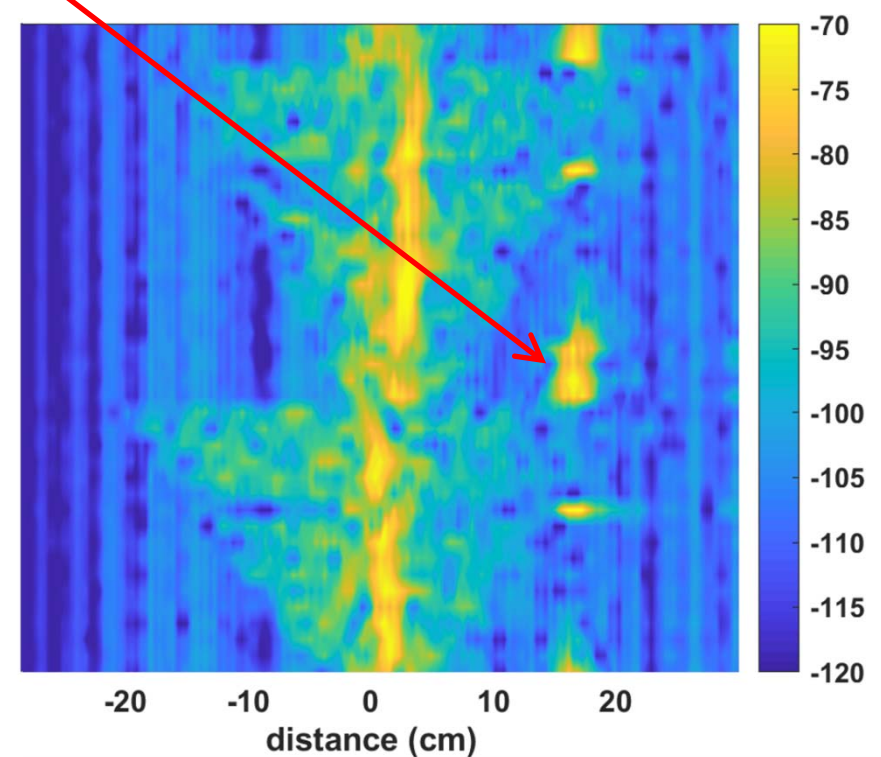
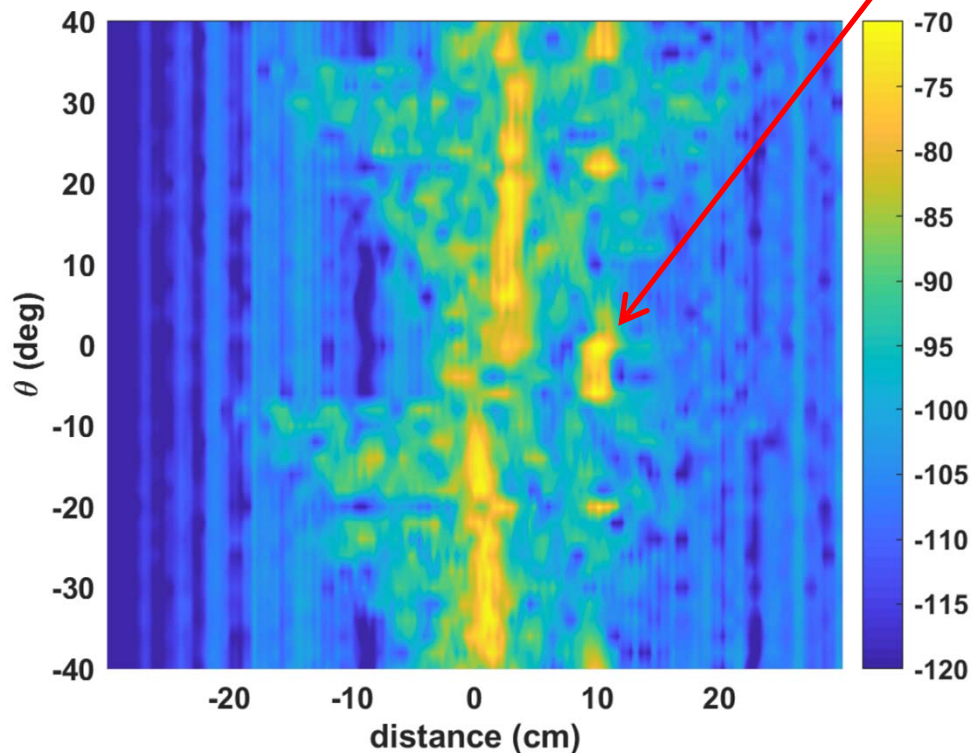


RTS horn antenna measurement Shorted waveguide input comp.

delayed response

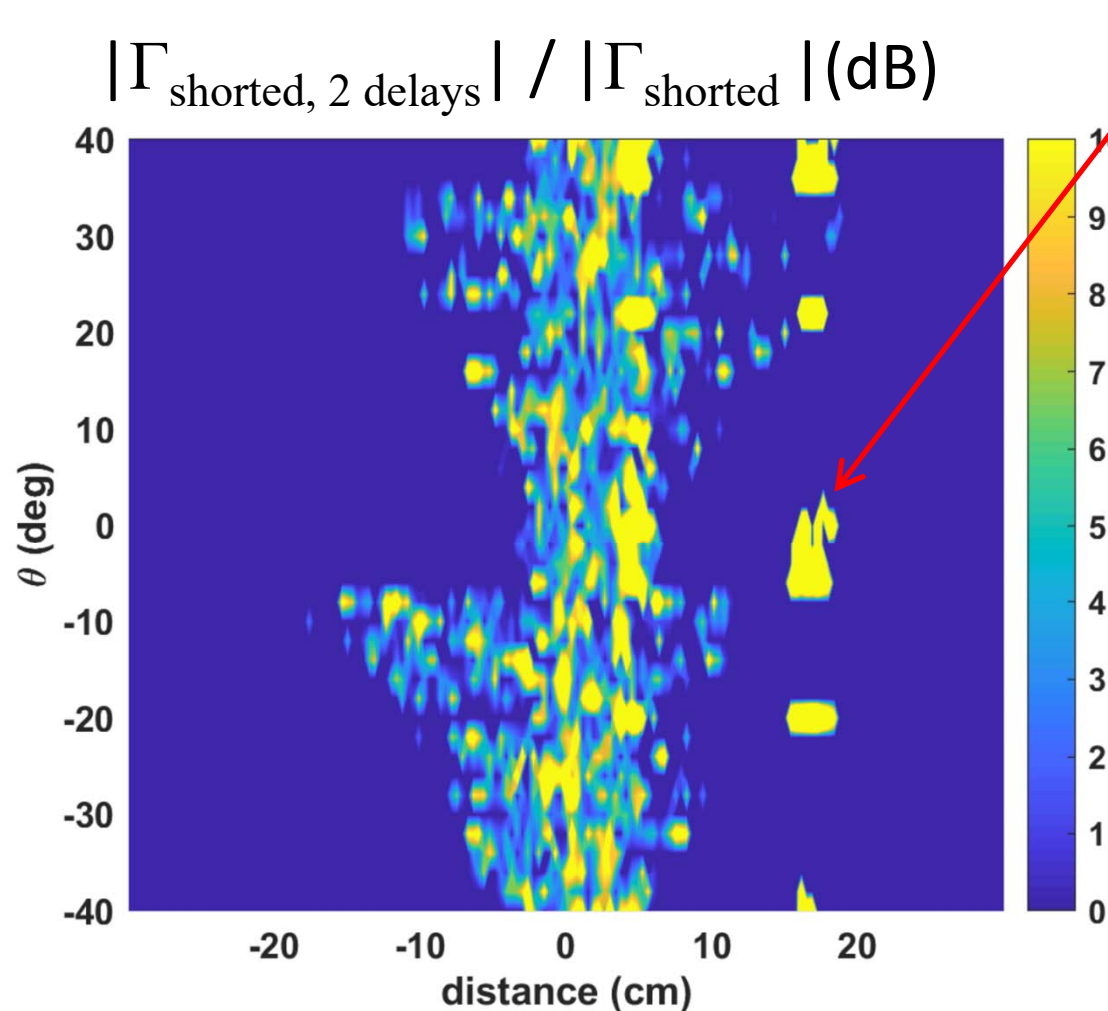
One waveguide section

Two waveguide sections





RTS horn antenna measurement



delayed response

Limit for the calculation:

$$\left. \begin{array}{l} |\Gamma_{\text{shorted, 2 delays}}| \\ |\Gamma_{\text{shorted}}| \end{array} \right\} > -95 \text{ dB}$$



Conclusion & Future Challenges

Conclusion:

- RTS antennas and surrounding absorbers are important to minimize clutter
- Antenna acts as a scatterer and as waveguide interface

Future challenges:

- RTS antenna design with low radar cross-section
- Multi-target objects to trigger object classification of the radar sensor
- Frequency & bandwidth



Any questions?

WTh-02 Test Procedures & Solutions...

3. October 2019

Speaker contact:

michael.gadringer@tugraz.at

