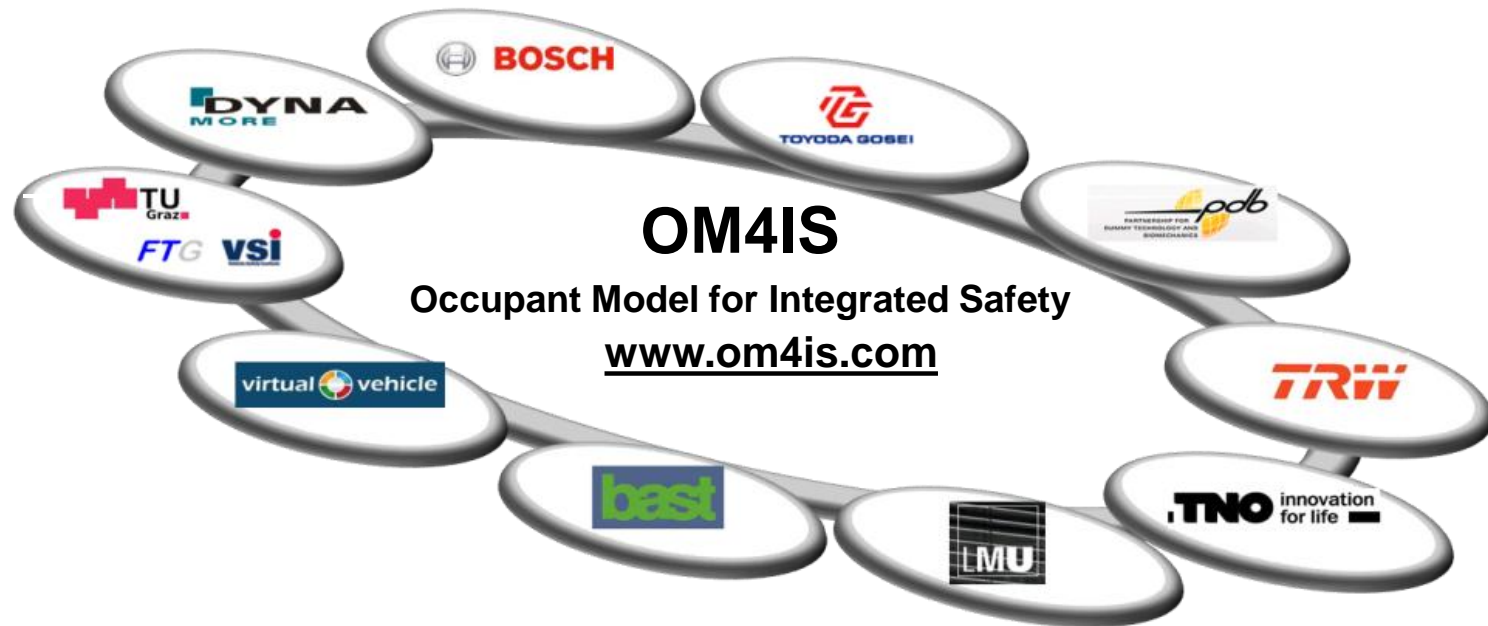


# Validation data for reactive human body models in the pre-collision phase



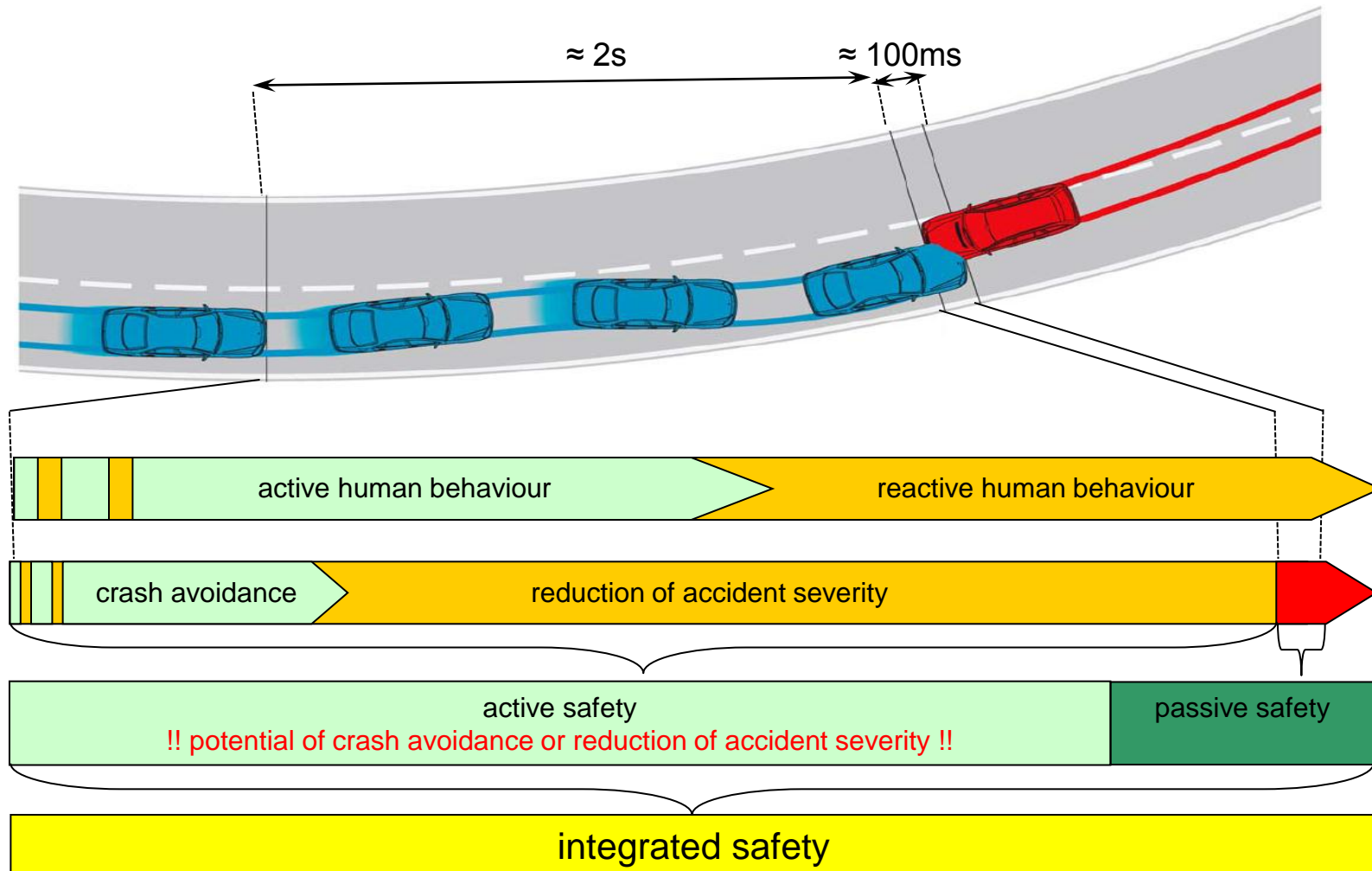
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## Content

- **General information**
- **Project task**
- **Testing**
  - Sled tests
  - Vehicle tests
- **Simulation**
- **Conclusions / Outlook**

Strategic focus: Pre-crash time window ( $\approx 2s$ ) and reactive human patterns



## Objectives

### ➤ Testing:

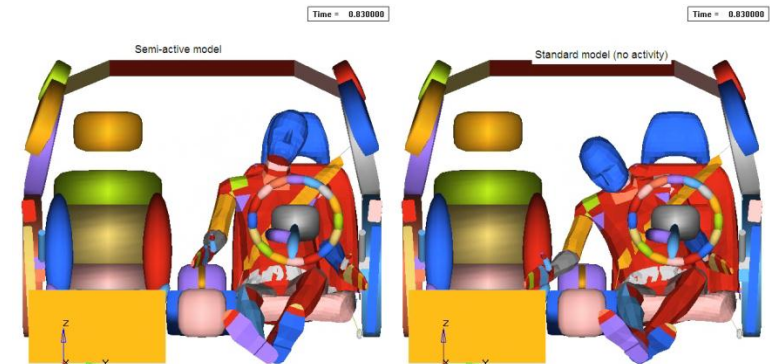
- Different load cases
- Significant number of volunteer
- Accurate kinematic information
- Danger for volunteer

### ➤ Simulation: **Several FE/MBS models on the market**

- Marginal possibility to modify the control system of the existing models
- Marginal information about the validation of the models

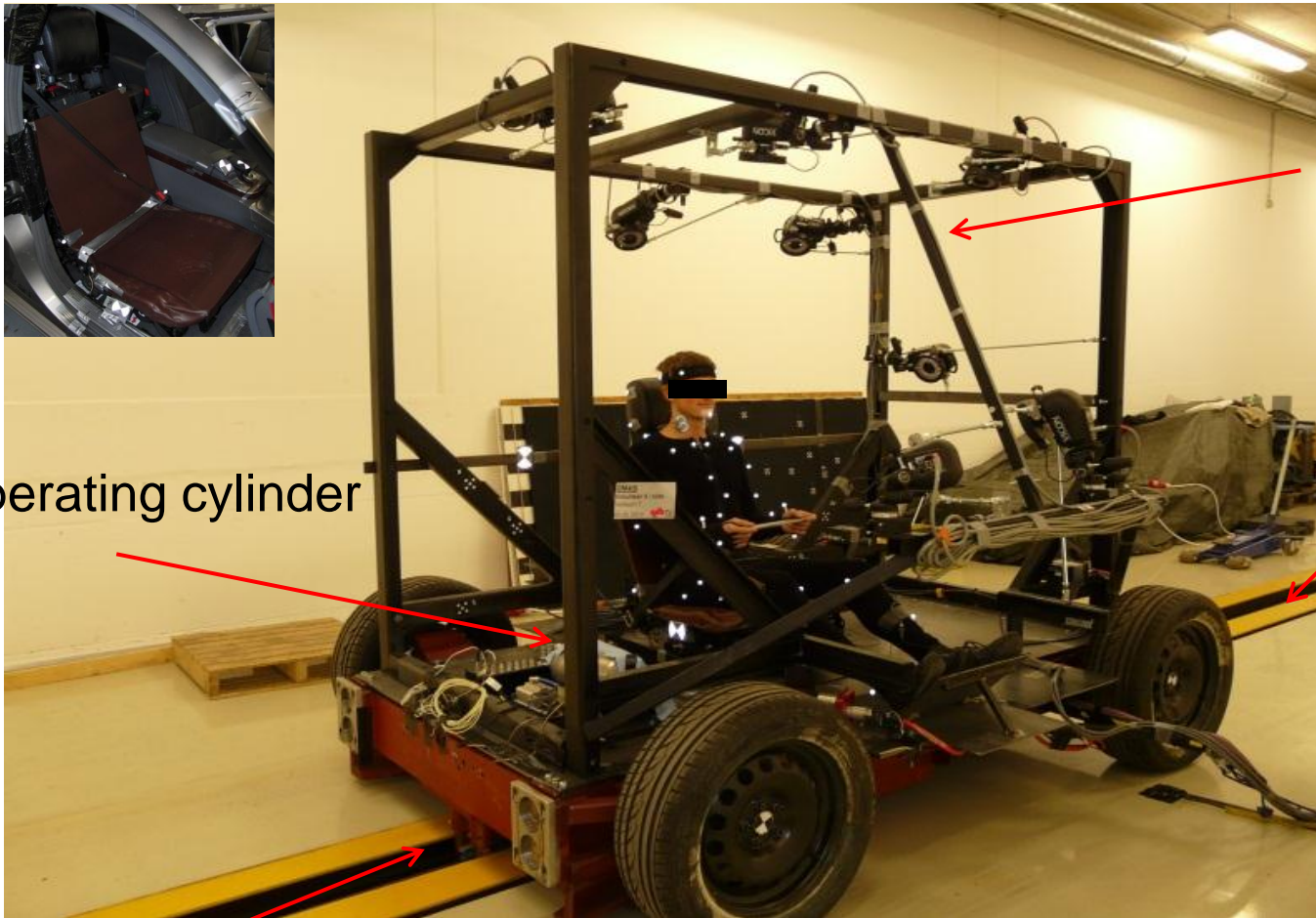
### ➤ Project tasks

- Development and improvement of models and methods for the representation of reactive behavior in **numeric human body models**
- Characterization of **reactive behavior** in low load **pre-crash phase**
- Specification of behavior patterns based on existing and new **experimental methods** and integration into a numeric human body model





# Sled test set up



Reference seat (only lap belt)

Brake operating cylinder

Cable guided sled

VICON Camera system

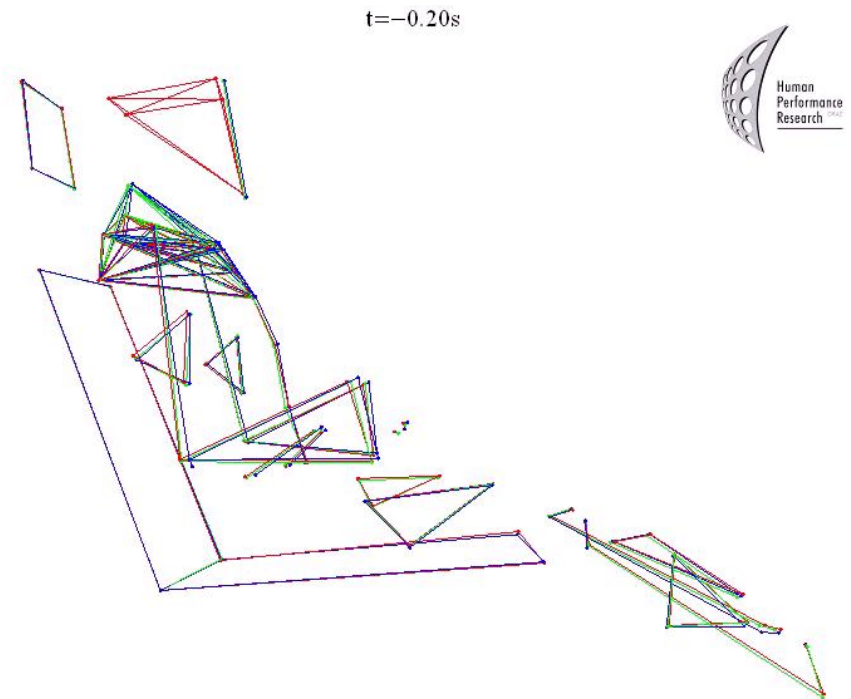
Crash track

## Video high speed camera



For detailed information refer to:  
**Detailed Analysis of 3D Occupant Kinematics and Muscle Activity during the Pre-crash Phase as Basis for Human Modeling Based on sled tests**  
13.06.2011 ESV Washington DC

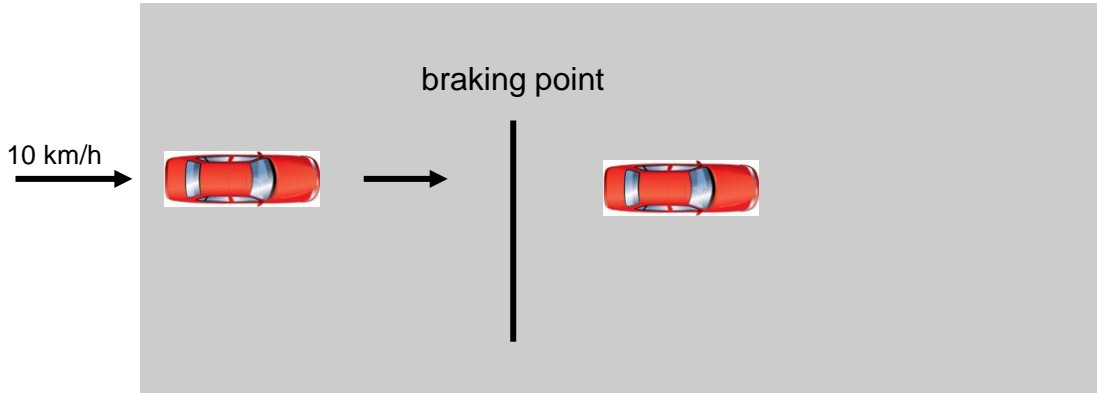
## Video infrared camera



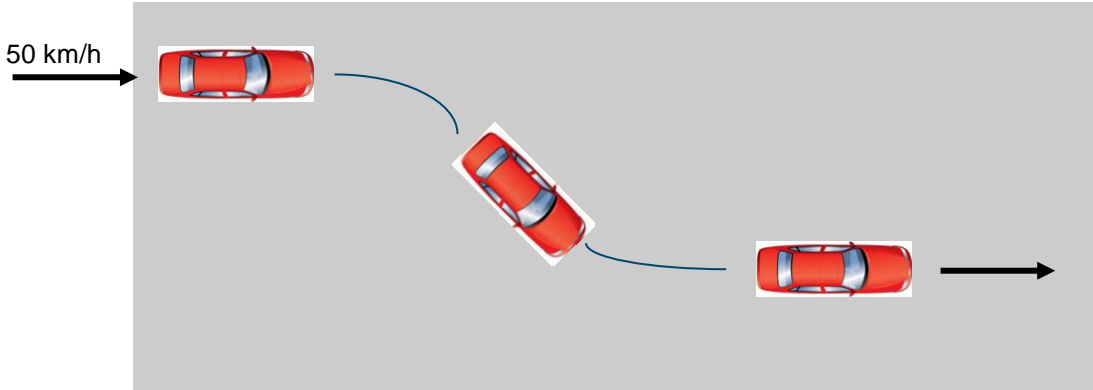
### Analyses:

- Large inter-subject variability
- Large intra-subject variability (less movement upon repeated trial)

## 1. Case: Front braking maneuver 10 km/h



## 2. Case: Lane change 50 km/h



### ➤ Two different seats

- I. Production-model seat
- II. Reference seat OM4IS

### ➤ 3 possibilities for belt system (front and side):

- A.) Belt .... 3 point safety belt
- B.) Active belt .... belt retractor
- C.) Lap belt ....only lap belt

### ➤ Six different maneuvers

- 1a.) Front **unaware**: the volunteer does not know the maneuver or the location
- 1b.) Front **anticipated**: the volunteer can anticipate the maneuver and the location
- 1c.) Front **informed**: the volunteer is told where and when the maneuver happens
- 2a.) Side **unaware**: the volunteer does not know the maneuver or the location
- 2b.) Side **anticipated**: the volunteer can anticipate the maneuver and location
- 2c.) Side **informed**: the volunteer is told where and when the maneuver happens

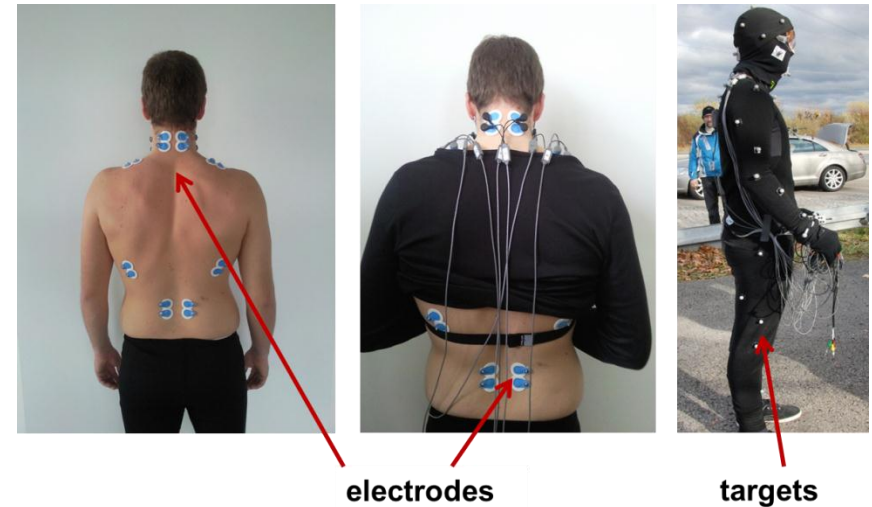




## Measurement systems

- Vehicle data
- Kinematic volunteer (Vicon)
- Surface EMG

30 volunteers according to  
50% male HIII dummy





Video Front **unaware** ~10km/h, peak acceleration ~ 1g

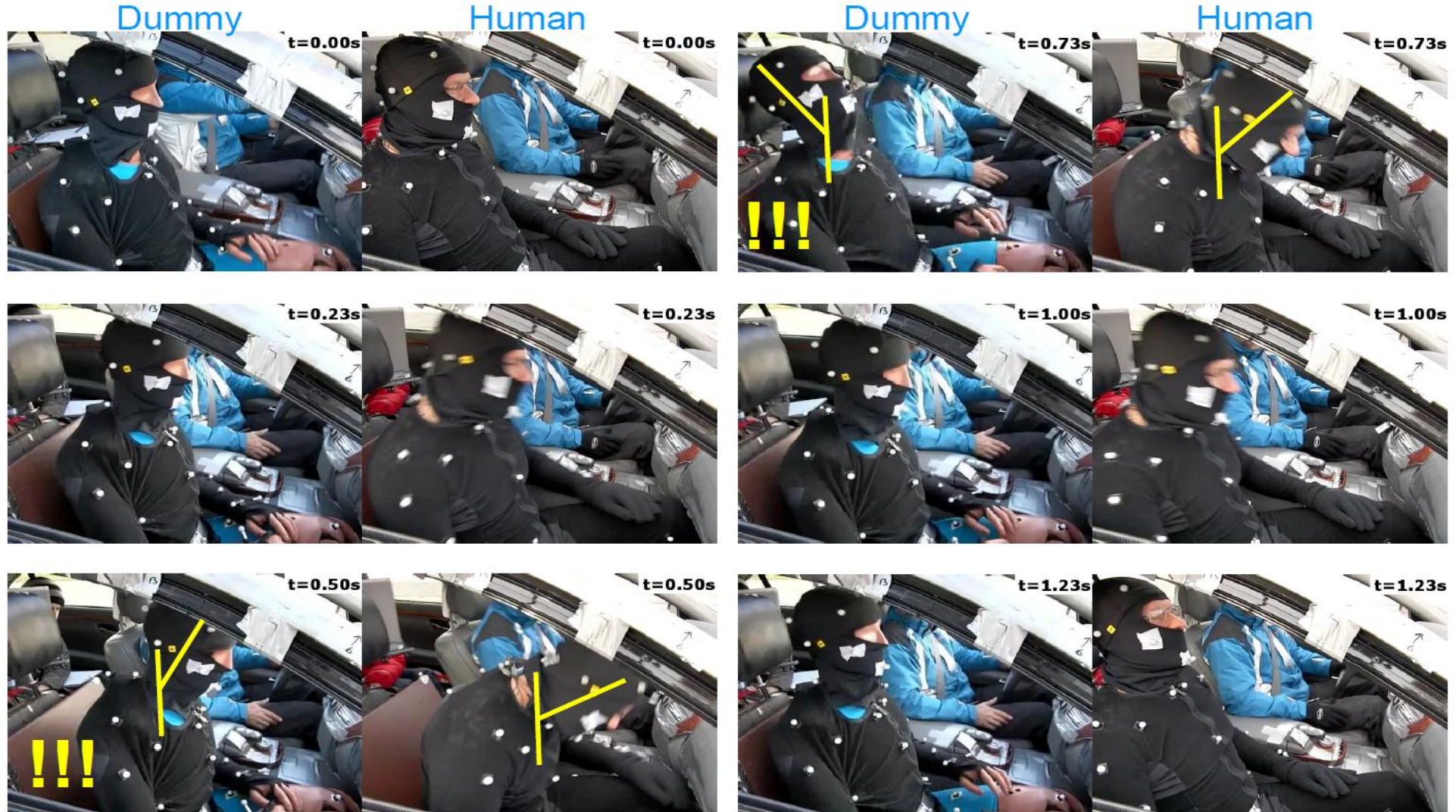


Video Front **unaware** ~10km/h, peak acceleration ~ 1g

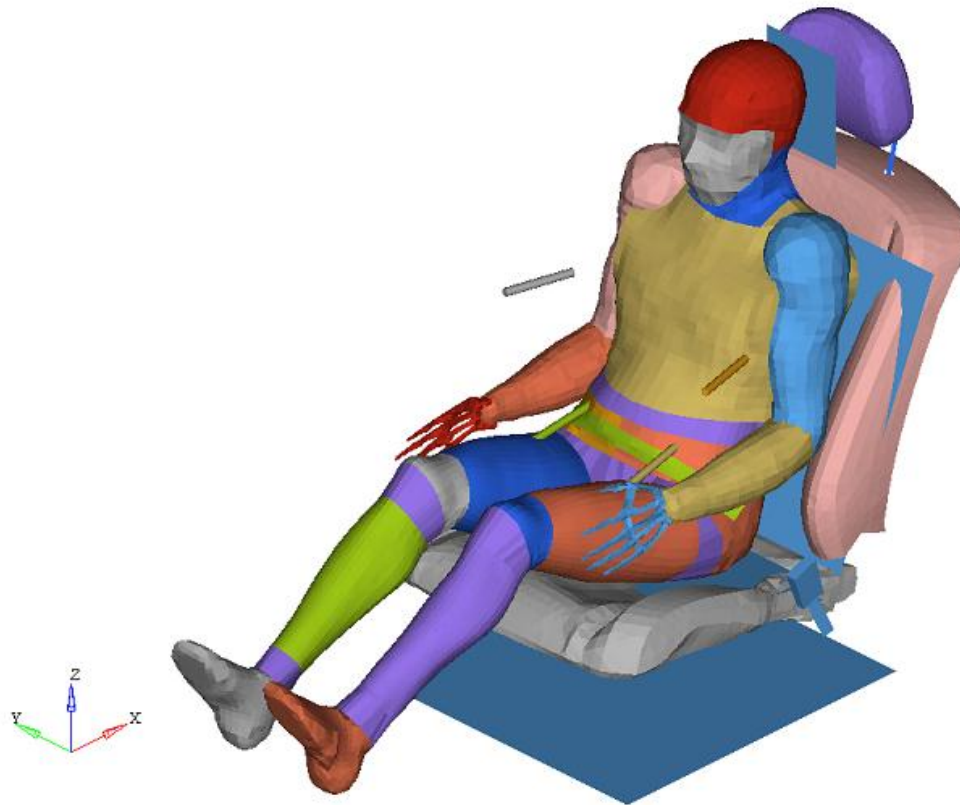




## Comparison Front Braking Maneuver





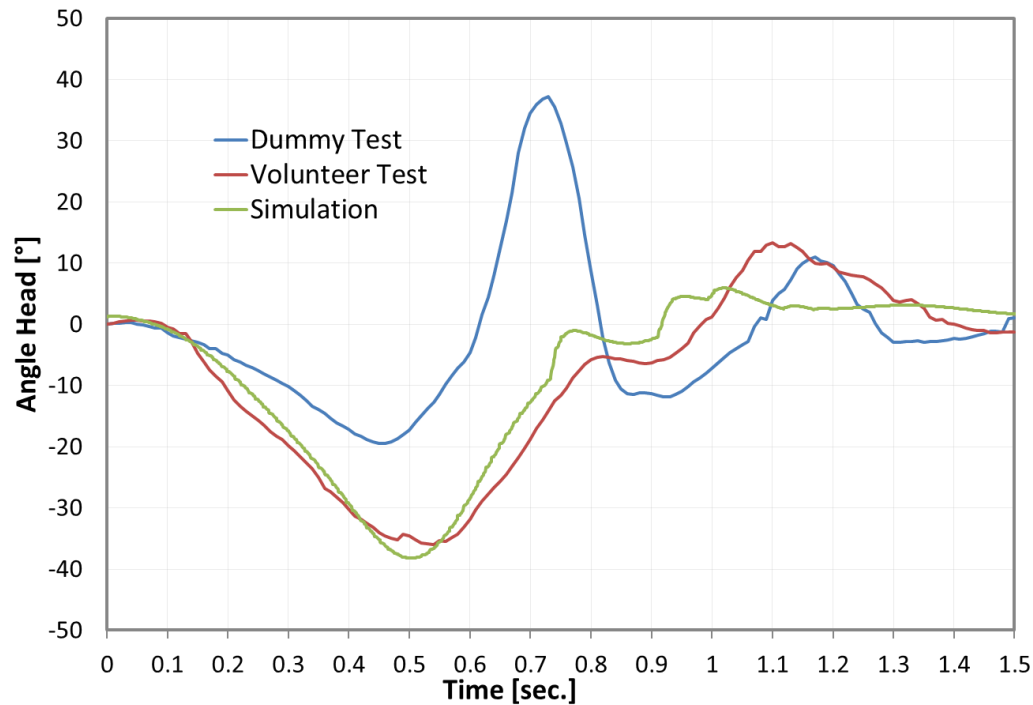


THUMS and belt  
Result : X:\scratch\MFE\_VD\_V027\_FA\_human\_lap\_belt\_rigidcon2\_201\_120112\vd3plot  
Loadcase 1 : Time = 0.000000  
Frame 1

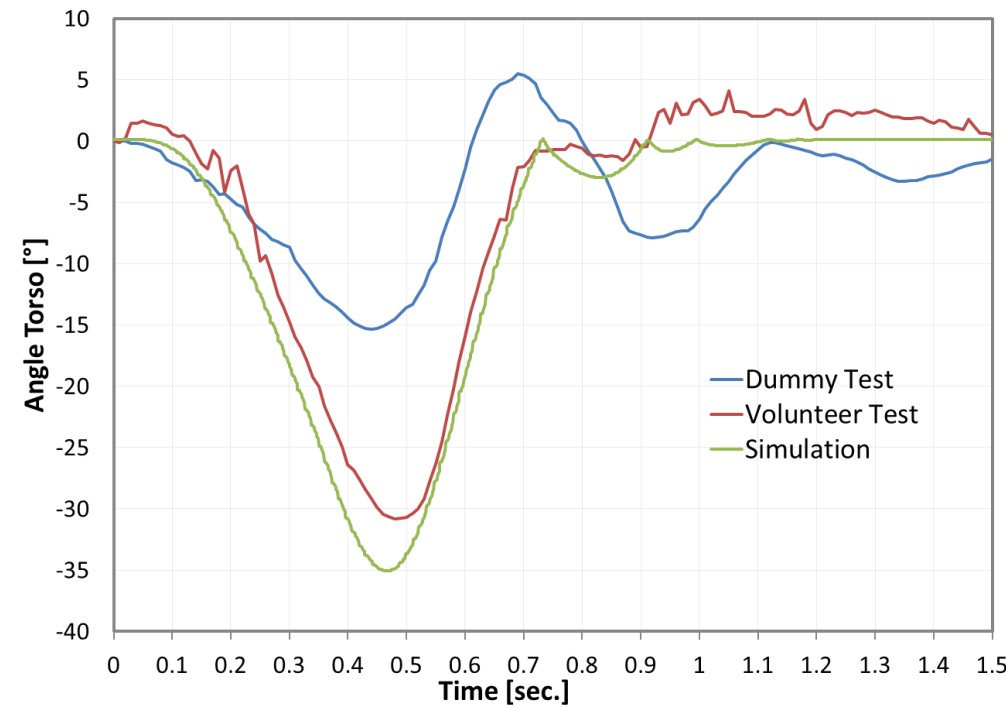
- Code-independent controller
- Simulation method independent controller (suitable for MBS and FE)
- Model is able to cover full range of subject movement

## Comparison Dummy Test - Volunteer Test - Simulation

Head



Torso

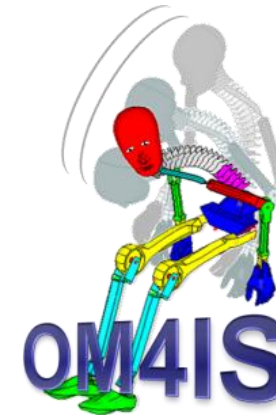


## Conclusions:

- Differences in kinematic behavior between volunteer and Dummy
- Large inter-subject variability
- Good agreement between simulation and volunteer kinematics

## Outlook:

- EMG analyses
- Movement patterns
- Movement controller optimization



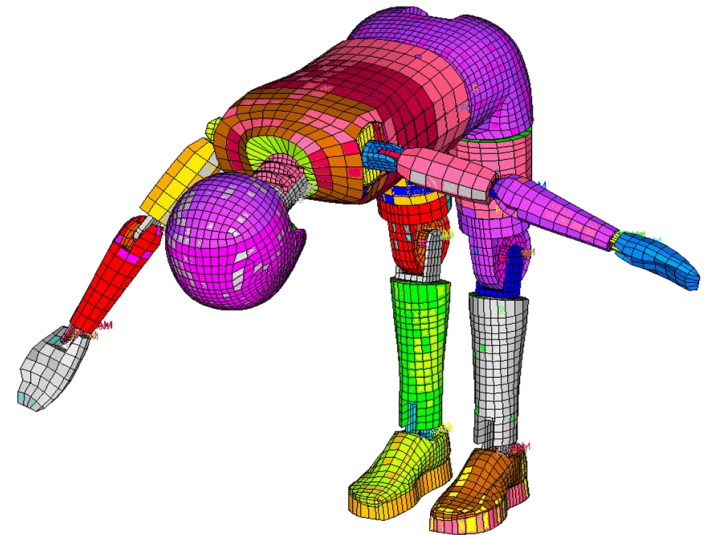


# Thank you for your attention

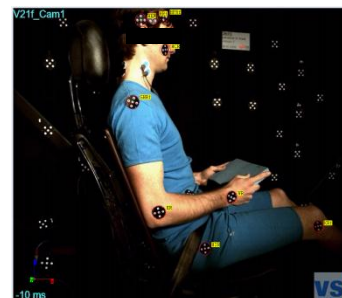
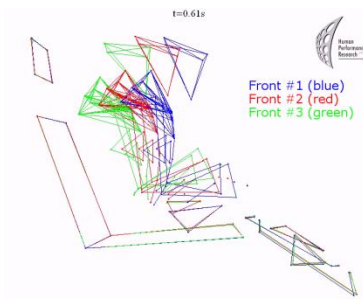
[www.om4is.com](http://www.om4is.com)

[www.vsi.at](http://www.vsi.at)

[www.v2c2.at](http://www.v2c2.at)



- 11 volunteers analogue 50% male dummy (average weight 78 kg, average height 175 cm)
- 3 frontal tests per volunteer (0,8 g acceleration / 10 km/h velocity)
- 3 lateral tests per volunteer (0,4 g acceleration / 8 km/h velocity)
- 2 different camera systems (Vicon infrared / Weinberger highspeed)
- Measurement of 8 different muscles (left and right bodypart → 16 muscles)



For detailed information refer to

**Detailed Analysis of 3D Occupant Kinematics and Muscle Activity during the Pre-crash Phase as Basis for Human Modeling Based on sled tests**

13.06.2011 ESV Washington DC

- Volunteer 1-30
  - **1.) frontal passive/unaware**
  - **2.) lane change passive/unaware**
  - **3.) frontal passive/anticipated**
  - **4.) lane change passive/anticipated**
  - **5.) frontal active/informed**
  - **6.) lane change active/informed**
  
- Summary
  - **30 volunteers**
  - **90 frontal tests**
  - **90 lane change maneuver**