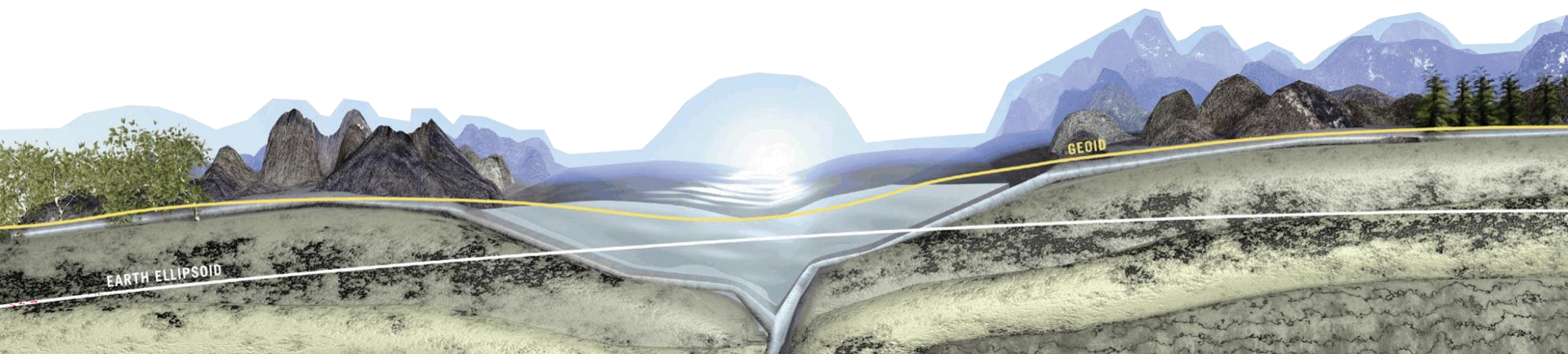


Do we need a new definition of gravity anomalies?

Torsten Mayer-Gürr and Christian Pock

WG Theoretical Geodesy and Satellite Geodesy
Institute of Geodesy, NAWI Graz
Graz University of Technology

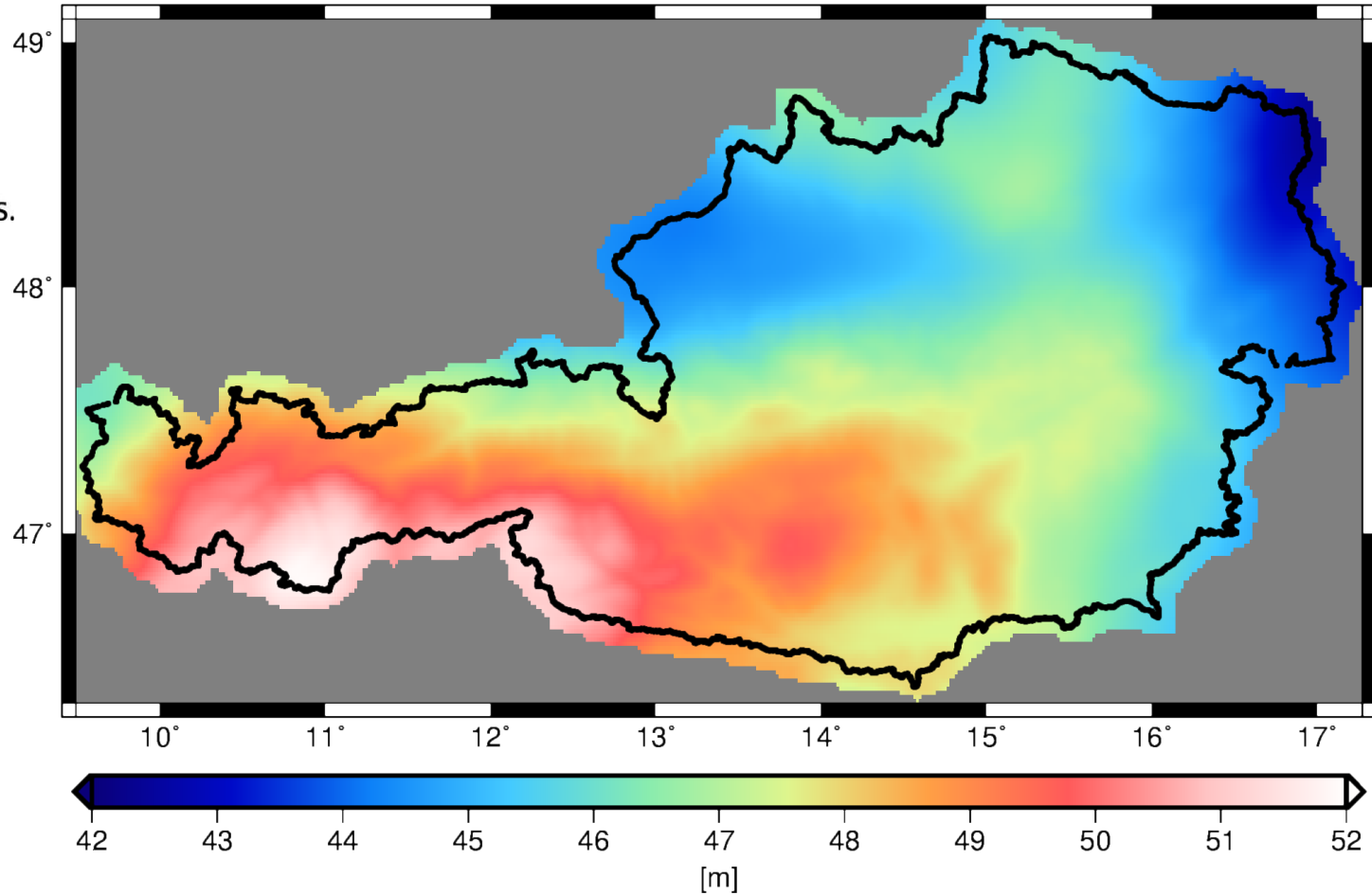


Goal: Geoid determination in Austria with cm accuracy

GARFIELD

FWF

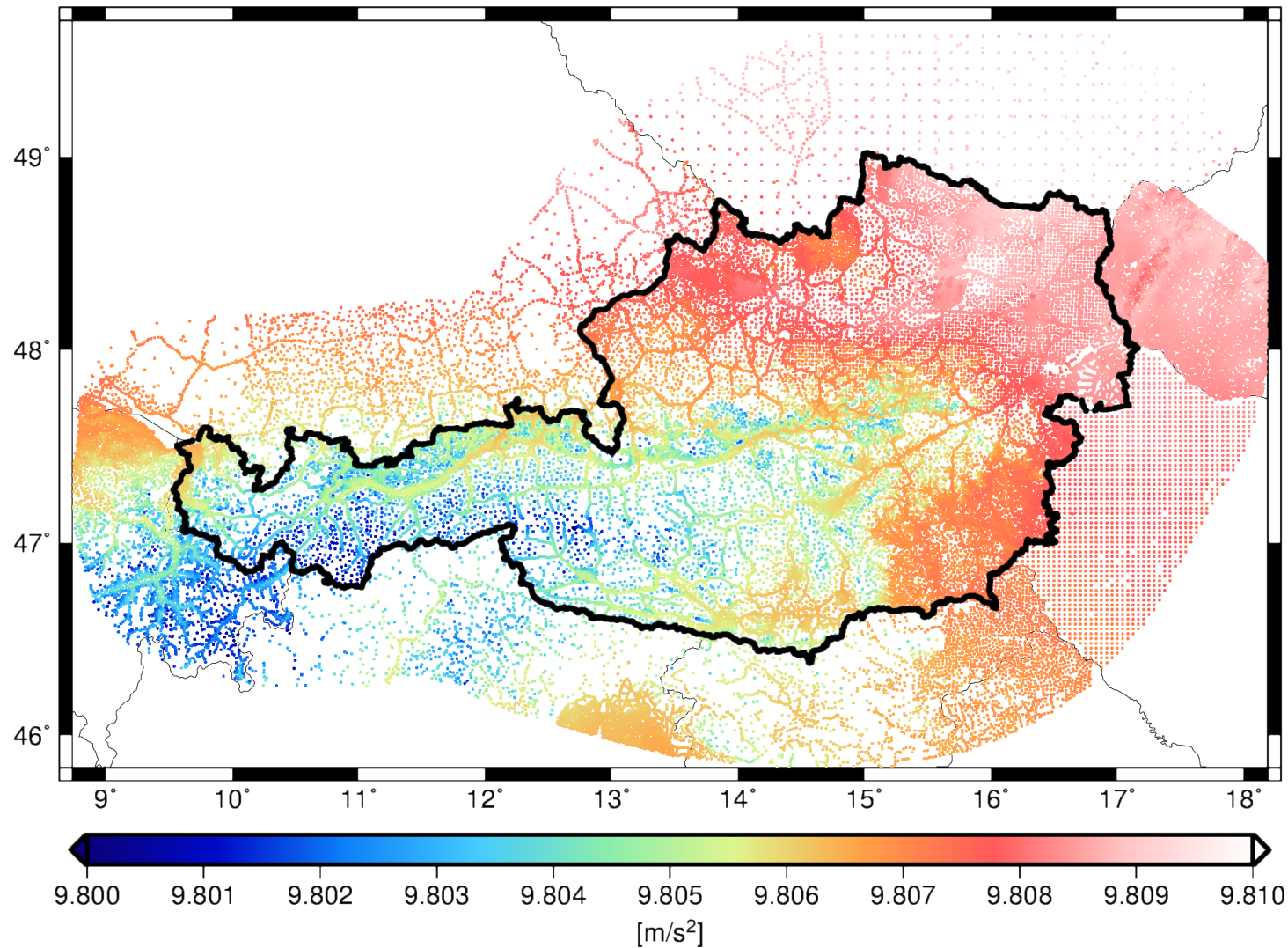
Der Wissenschaftsfonds.



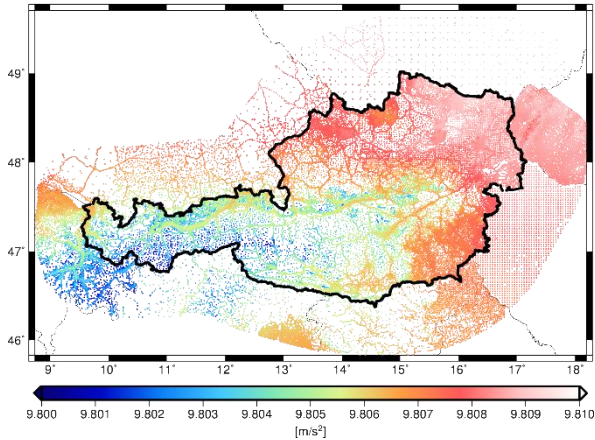
Input data: Gravimetric observations

72.723 observations
in and around Austria

Accuracy for most
data: $\ll 0.1$ mGal



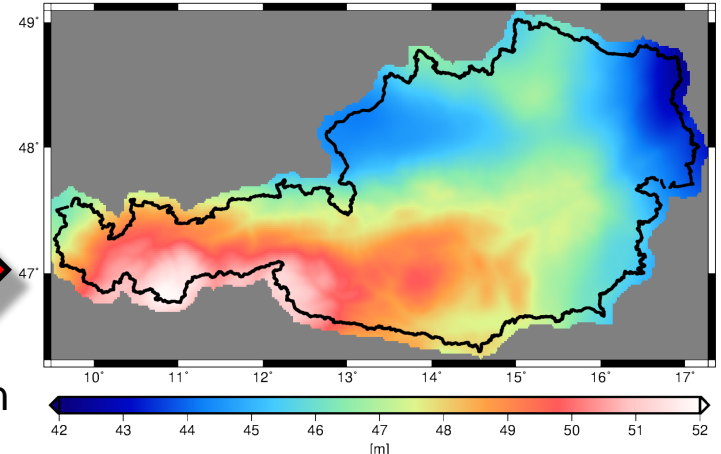
Fundamental equation of physical geodesy



Connection

$$\Delta g = -\frac{\partial T}{\partial r} - 2\frac{T}{r}$$

Linearized with spherical approximation



Is the **fundamental equation of physical geodesy** in linearized form (with spherical approximation) **accurate enough** to model the observations?

Helmut Moritz (1980), Advanced physical geodesy:

“This spherical approximation causes an error which is negligible in most practical applications.”

“This error is [on a global average] on the order of ± 20 cm in the geoidal height. This is one order of magnitude smaller than the accuracy implied by the present gravimetric and satellite data.”

Observation equations

Linearization of non-linear observation equations

$$f(x) = f(x_0) + \left. \frac{\partial f}{\partial x} \right|_{x_0} (x - x_0) + \dots$$

Unknown parameter $x = W(L, B, h)$

Gravity potential

Taylor point $x_0 = U(L, B, h)$

Normal potential with $N_0 = 0$

Difference $x - x_0 = T(L, B, h)$


Disturbance potential

Observed $f(x) = g(L, B, h)$

Observed absolute gravity

Computed $f(x_0) = \gamma(L, B, h)$

Normal gravity



ellipsoidal height =
orthometric height + geoid height

$$h = H + N(W)$$

Observation equations

Linearization of non-linear observation equations

$$f(x) = f(x_0) + \left. \frac{\partial f}{\partial x} \right|_{x_0} (x - x_0) + \dots \quad \rightarrow \quad \Delta g = -\frac{\partial T}{\partial r} - 2\frac{T}{r}$$

Unknown parameter $x = W(L, B, h)$

Gravity potential

Taylor point $x_0 = U(L, B, h)$

Normal potential with $N_0 = 0$

Difference $x - x_0 = T(L, B, h)$

Disturbance potential

Observed $f(x) = g(L, B, h)$

Observed absolute gravity

Computed $f(x_0) = \gamma(L, B, h_0)$

Normal gravity

Reduced observations $f(x) - f(x_0) = g(L, B, H + N) - \gamma(L, B, H + N_0) = \Delta g$ (Free air) gravity anomalies

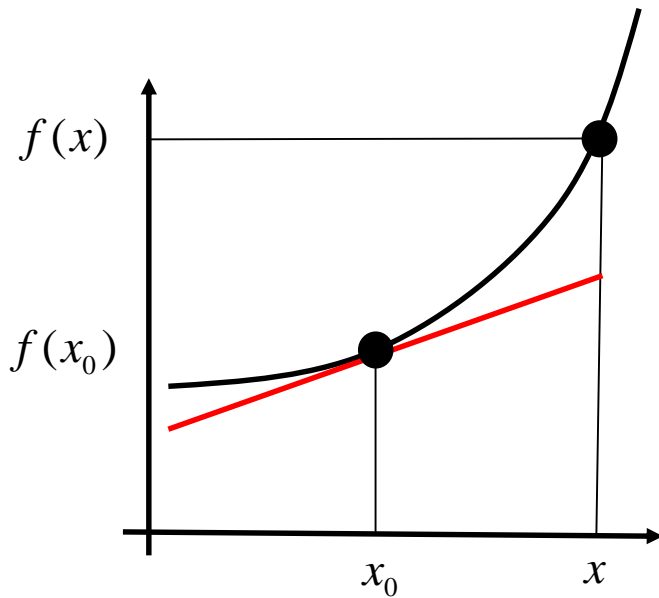
Linear model $\left. \frac{\partial f}{\partial x} \right|_{x_0} (x - x_0) = -\frac{\partial T}{\partial r} - 2\frac{T}{r}$

Fundamental equation in physical geodesy (In spherical approximation)

Observation equations

Linearization of non-linear observation equations

$$f(x) = f(x_0) + \left. \frac{\partial f}{\partial x} \right|_{x_0} (x - x_0) + \dots$$



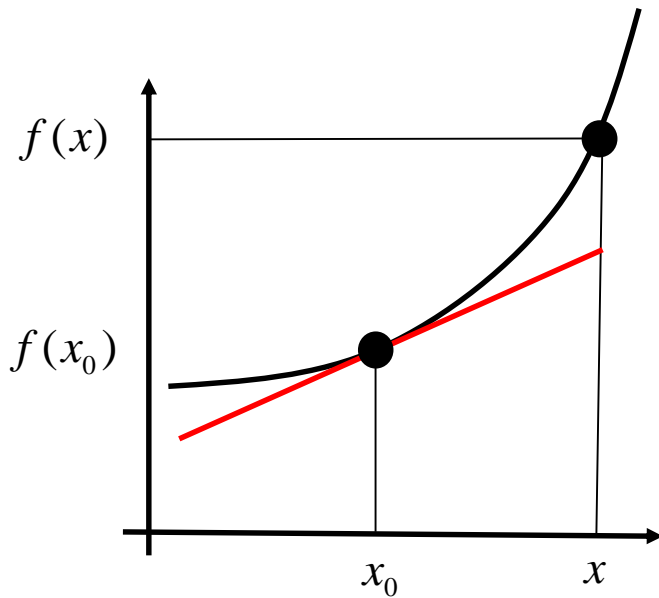
Possible improvements of accuracy:

1. Better linearization
(without spherical approximation)

Observation equations

Linearization of non-linear observation equations

$$f(x) = f(x_0) + \left. \frac{\partial f}{\partial x} \right|_{x_0} (x - x_0) + \dots$$



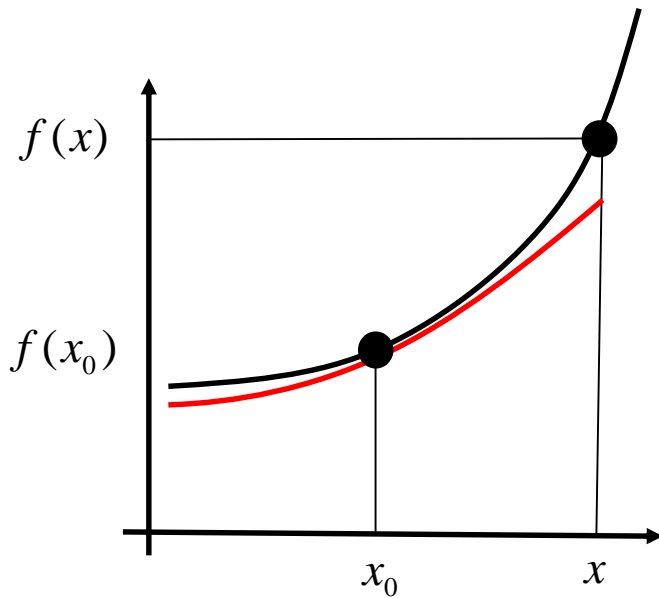
Possible improvements of accuracy:

1. Better linearization
(without spherical approximation)
2. Include quadratic terms

Observation equations

Linearization of non-linear observation equations

$$f(x) = f(x_0) + \left. \frac{\partial f}{\partial x} \right|_{x_0} (x - x_0) + \dots$$



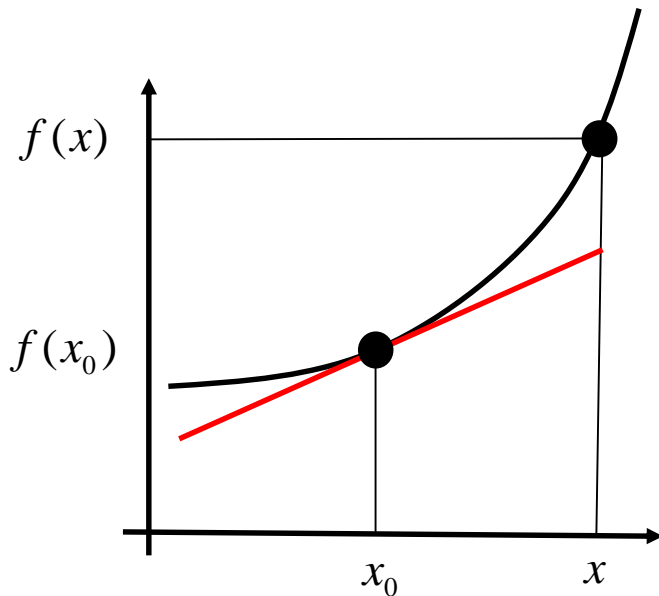
Possible improvements of accuracy:

1. Better linearization
(without spherical approximation)
2. Include quadratic terms

Observation equations

Linearization of non-linear observation equations

$$f(x) = f(x_0) + \left. \frac{\partial f}{\partial x} \right|_{x_0} (x - x_0) + \dots$$



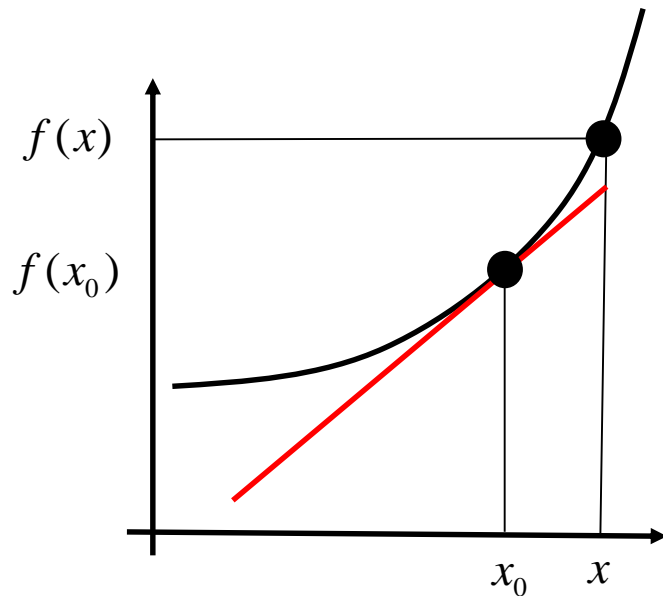
Possible improvements of accuracy:

1. Better linearization
(without spherical approximation)
2. Include quadratic terms
3. Better Taylor point

Observation equations

Linearization of non-linear observation equations

$$f(x) = f(x_0) + \left. \frac{\partial f}{\partial x} \right|_{x_0} (x - x_0) + \dots$$



Possible improvements of accuracy:

1. Better linearization
(without spherical approximation)
2. Include quadratic terms
3. Better Taylor point

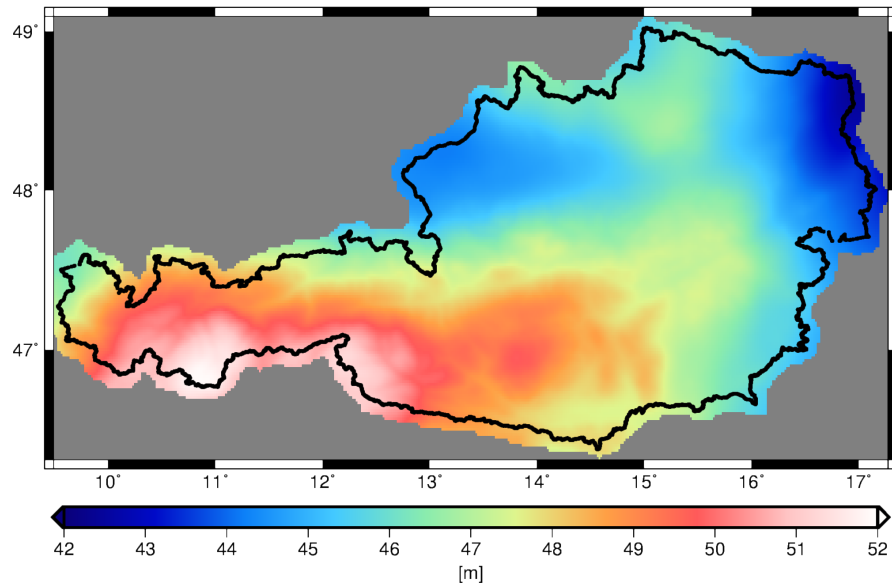
Taylor point

Approximate values (Taylor point)

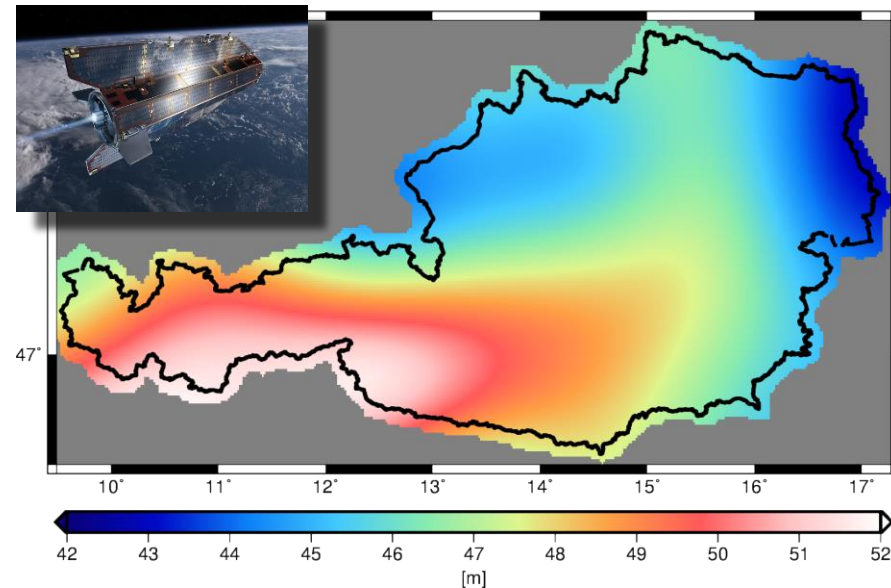
Classic $f(x_0) = \gamma(L, B, H + N_0)$ with $N_0 = 0$

New approach $f(x_0) = g_{sat}(L, B, H + N_{sat})$

Geoid



Satellite model GOCO05s

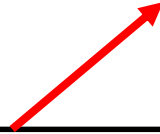


Taylor point

Approximate values (Taylor point)

Classic $f(x_0) = \gamma(L, B, H + N_0)$ with $N_0 = 0$

New approach $f(x_0) = g_{sat}(L, B, H + N_{sat}) = \|\mathbf{g}_{sat}\| = \|\nabla W_{sat}\|$

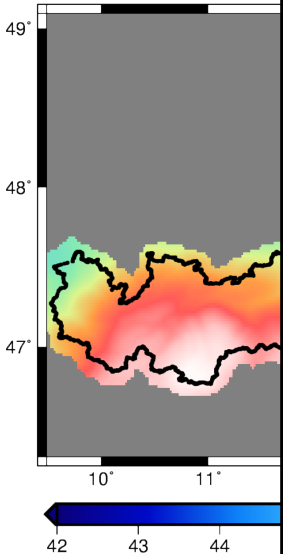


Gravity potential: $W(\lambda, \vartheta, r) = V(\lambda, \vartheta, r) + Z(\lambda, \vartheta, r)$

Gravitational potential: $V(\lambda, \vartheta, r) = \frac{GM}{R} \sum_{n=0}^{n_{max}} \left(\frac{R}{r}\right)^{n+1} \sum_{m=0}^{2n+1} c_{nm} C_{nm}(\lambda, \vartheta) + s_{nm} S_{nm}(\lambda, \vartheta)$

Centrifugal potential: $Z(\vartheta, r) = \frac{1}{2} \omega^2 r \sin^2 \vartheta$

Gravity: $g = \|\nabla W\| = \left\| \begin{pmatrix} \partial W / \partial \lambda \\ \partial W / \partial \vartheta \\ \partial W / \partial r \end{pmatrix} \right\| = \left\| \begin{pmatrix} \partial W / r \partial \lambda \\ \partial W / r \sin \vartheta \partial \vartheta \\ \partial W / \partial r \end{pmatrix} \right\|$



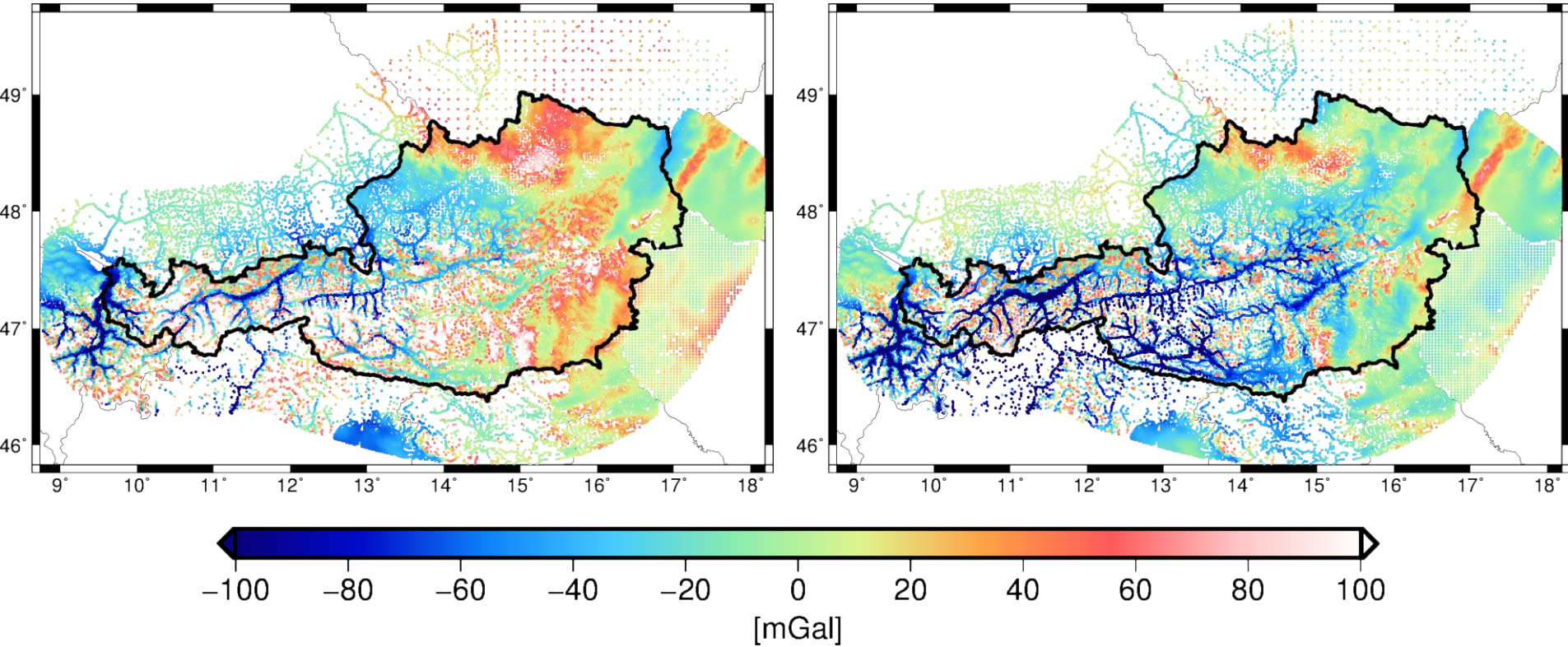
Reduced observations

Classic approach

$$\Delta g = g - \gamma$$

New approach

$$\Delta g = g - \|\mathbf{g}_{sat}\|$$



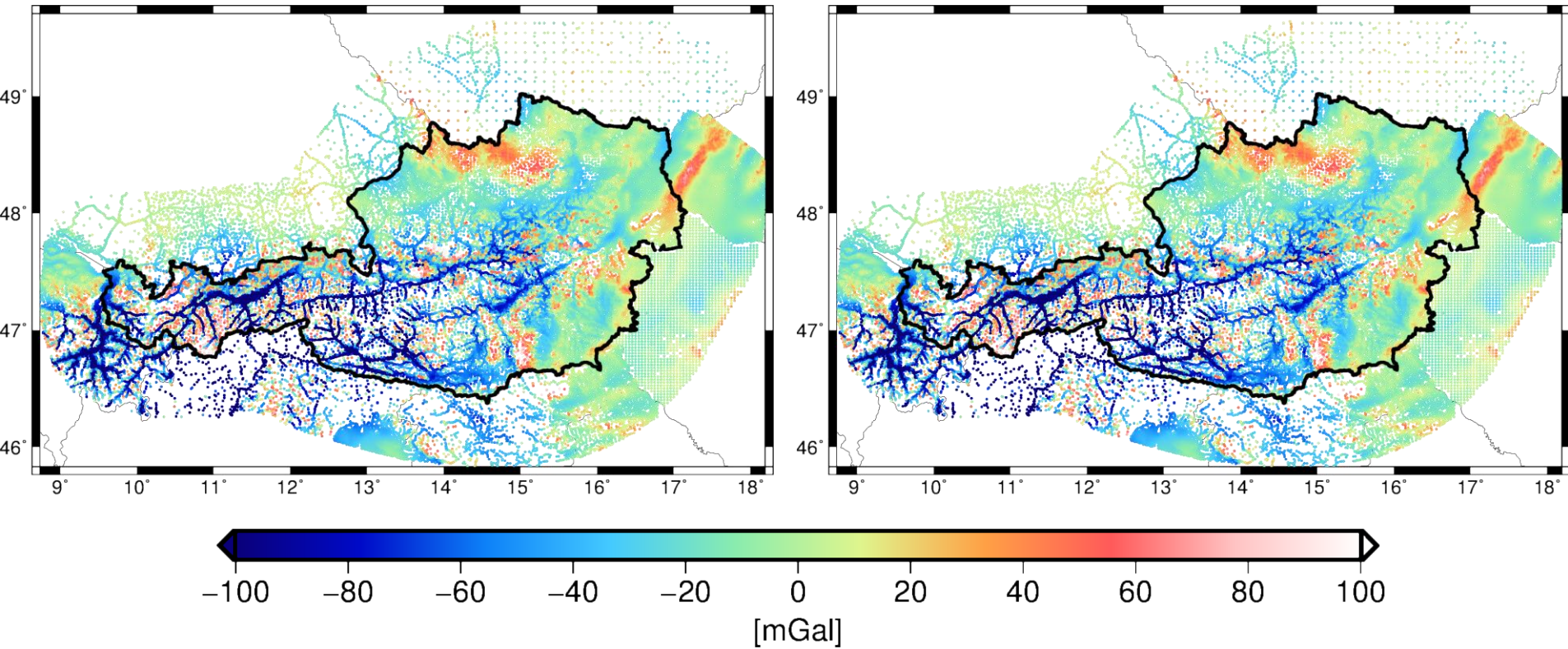
Reduced observations

Classic approach

$$\Delta g = g - \gamma - \Delta g_{sat}$$

New approach

$$\Delta g = g - \|\mathbf{g}_{sat}\|$$



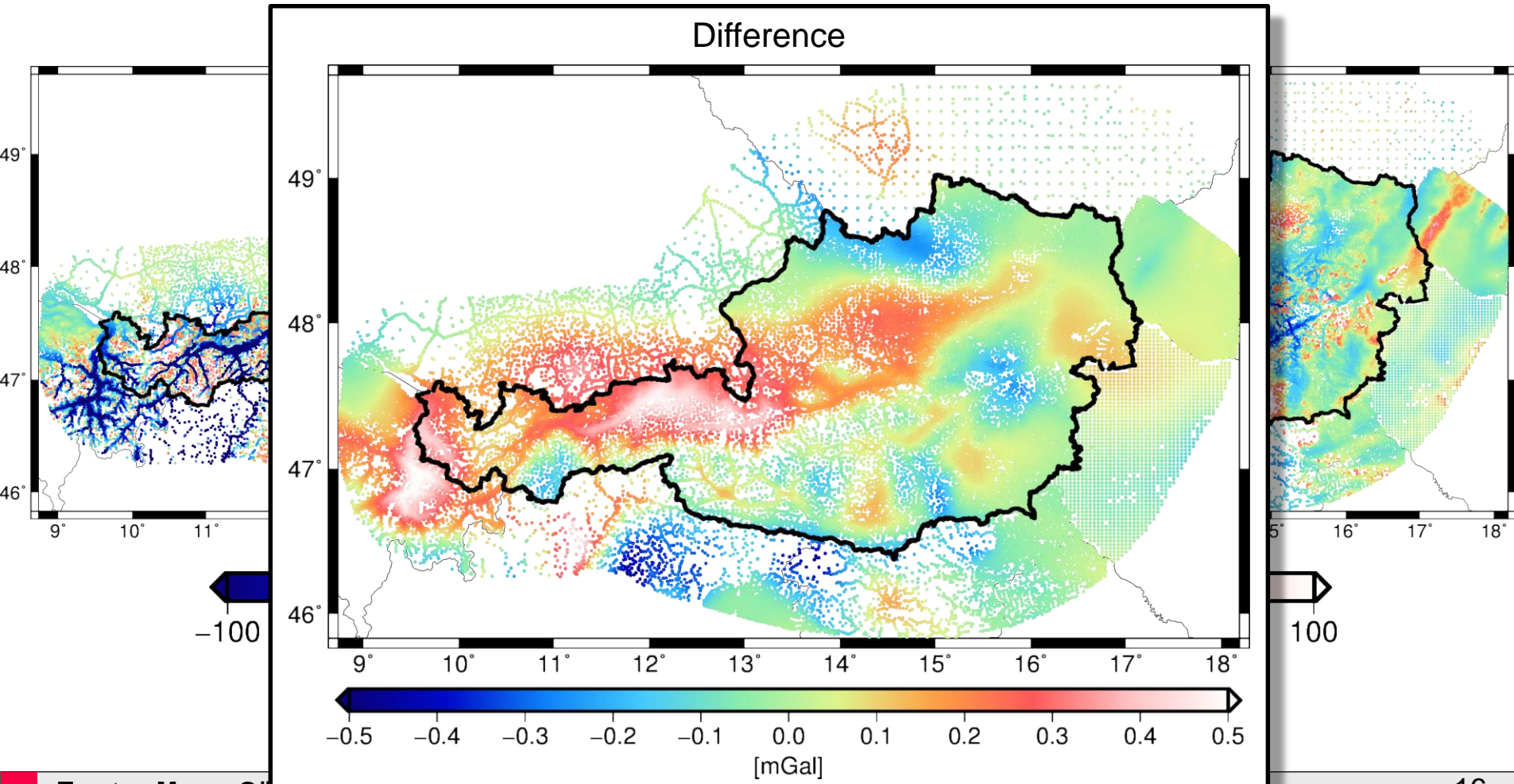
Reduced observations

Classic approach

$$\Delta g = g - \gamma - \Delta g_{sat}$$

New approach

$$\Delta g = g - \|\mathbf{g}_{sat}\|$$



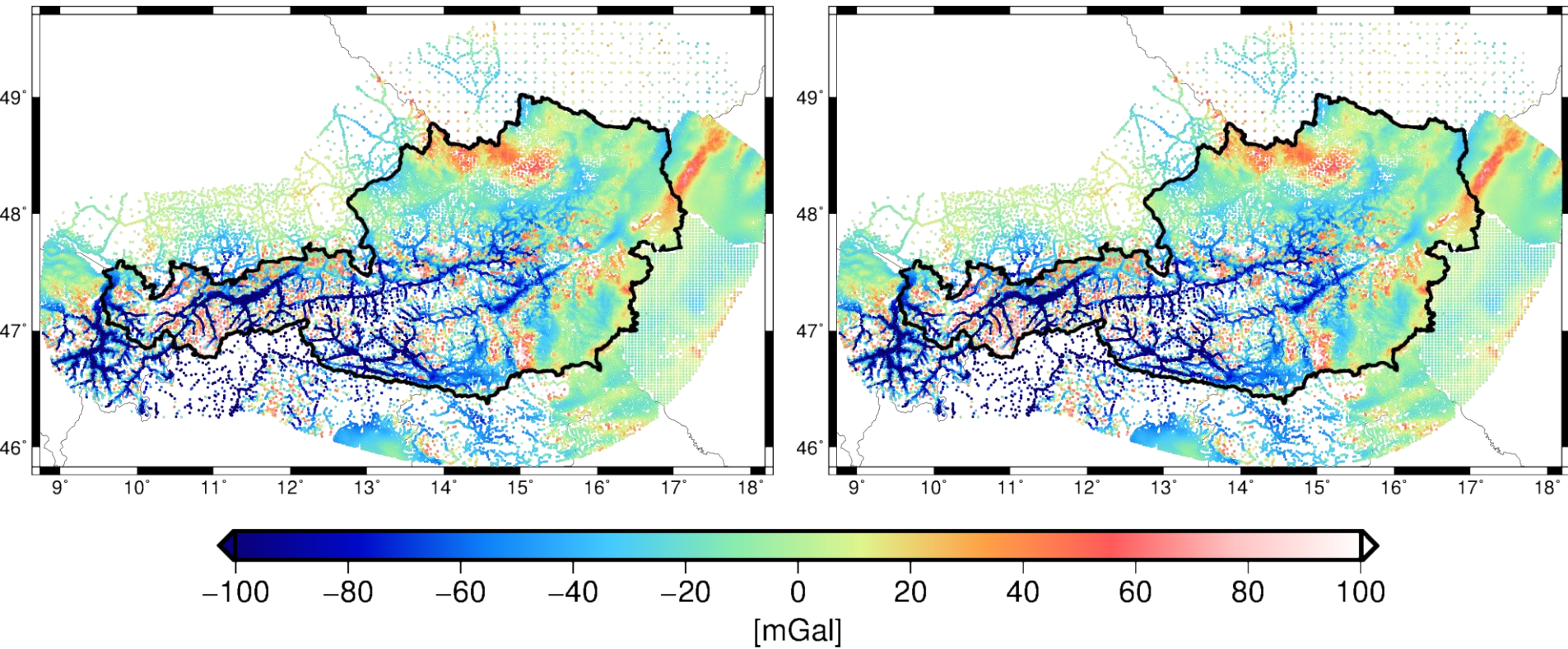
Reduced observations

Classic approach

$$\Delta g = g - \gamma - \Delta g_{sat}$$

New approach

$$\Delta g = g - \|\mathbf{g}_{sat}\|$$



Topography

Gravitational potential from topographic masses

$$T(\mathbf{r}_P) = G \iiint_{\Omega} \frac{1}{l(\mathbf{r}_P, \mathbf{r}_Q)} \rho(\mathbf{r}_Q) d\Omega(\mathbf{r}_Q)$$

Satellite model includes topographic effect

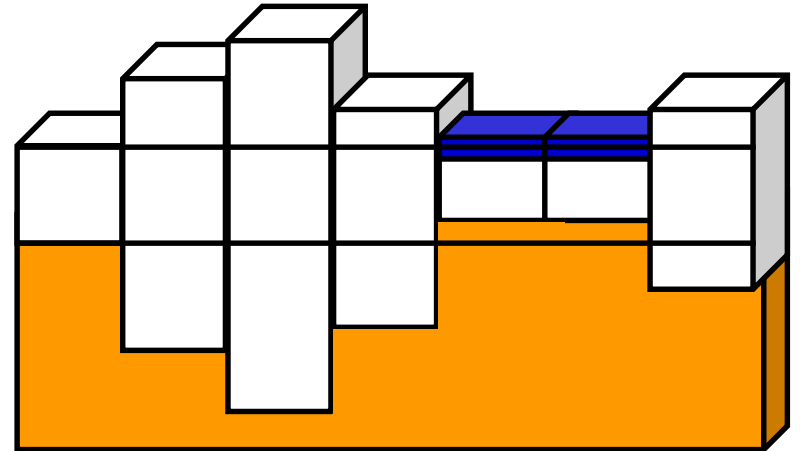
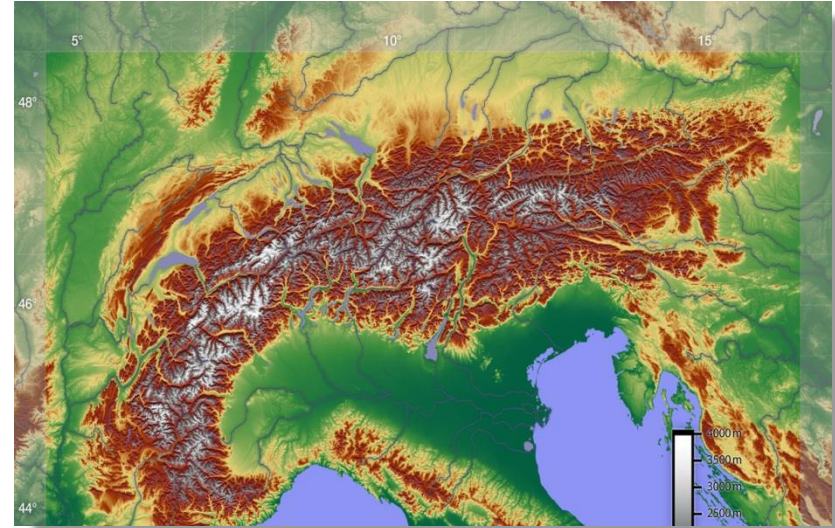
⇒ Spherical harmonic expansion of topography

$$T_{topo}(\mathbf{r}_P) = \frac{GM}{R} \sum_{n=0}^{\infty} \left(\frac{R}{r}\right)^{n+1} \sum_{m=-n}^n a_{nm}^{topo} Y_{nm}(\mathbf{r}_P)$$

$$a_{nm}^{topo} = \frac{1}{M(2n+1)} \iiint_{\Omega} \left(\frac{r'}{R}\right)^n \rho(\mathbf{r}_Q) Y_{nm}(\mathbf{r}_Q) d\Omega(\mathbf{r}_Q)$$

Topography without satellite model part

$$\delta T_{topo} = T_{topo} - \sum_{n=0}^N T_n^{topo}$$



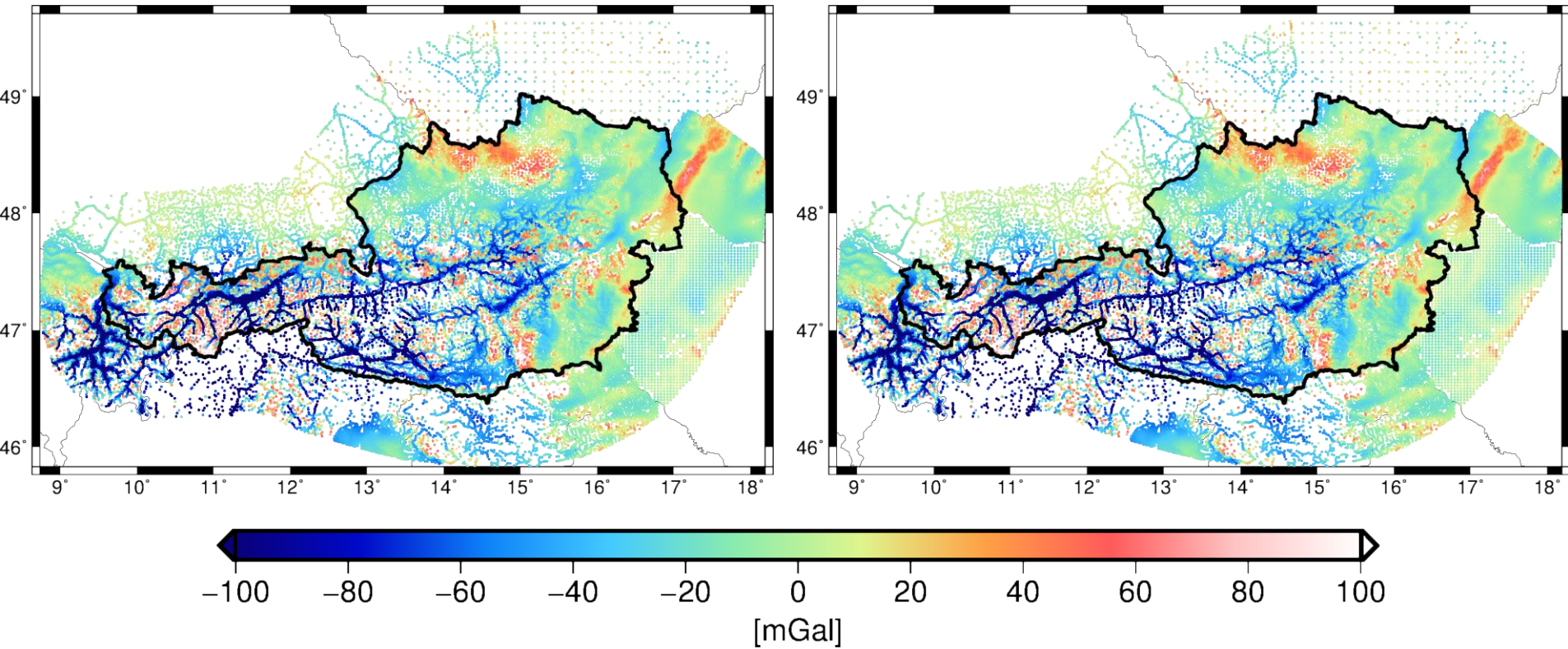
Reduced observations

Classic approach

$$\Delta g = g - \gamma - \Delta g_{sat}$$

New approach

$$\Delta g = g - \|\mathbf{g}_{sat}\|$$



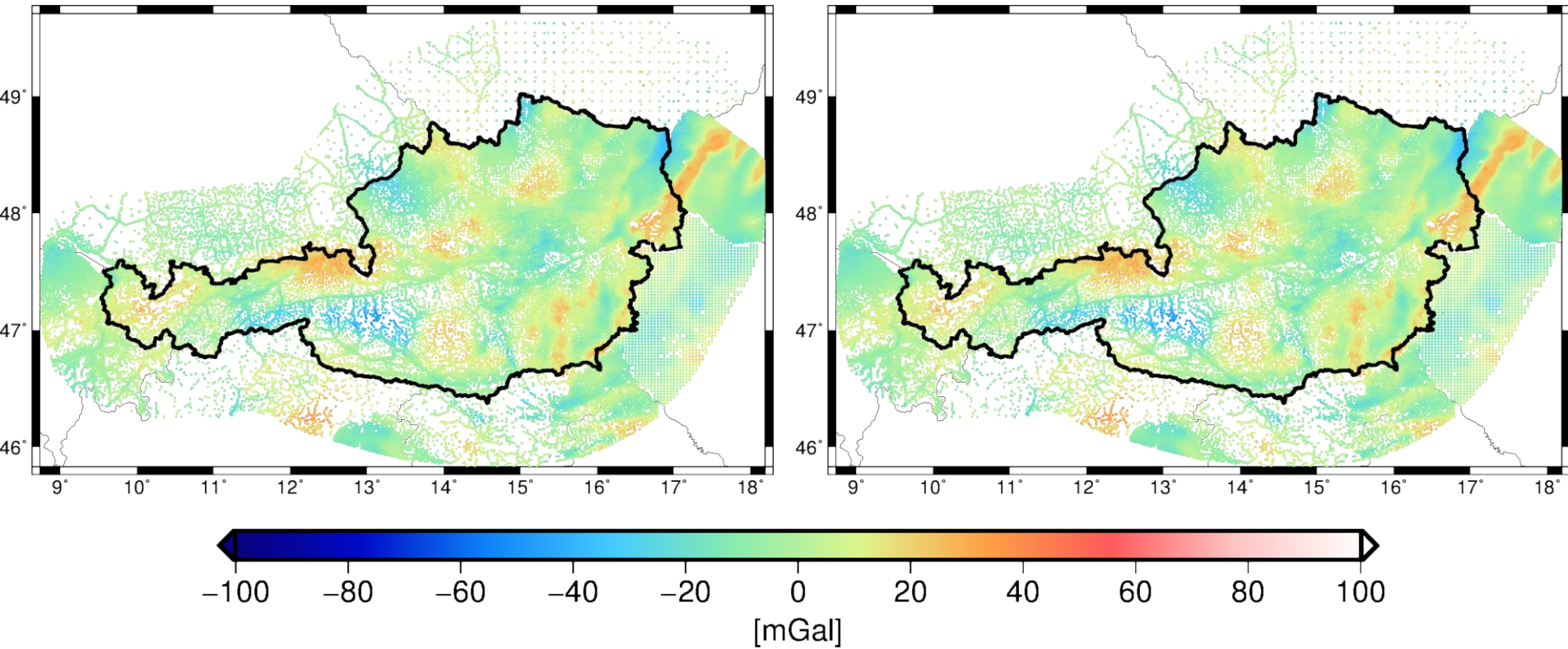
Reduced observations

Classic approach

$$\Delta g = g - \gamma - \Delta g_{sat} - \delta g_{topo}$$

New approach

$$\Delta g = g - \|\mathbf{g}_{sat} + \mathbf{g}_{topo}\|$$



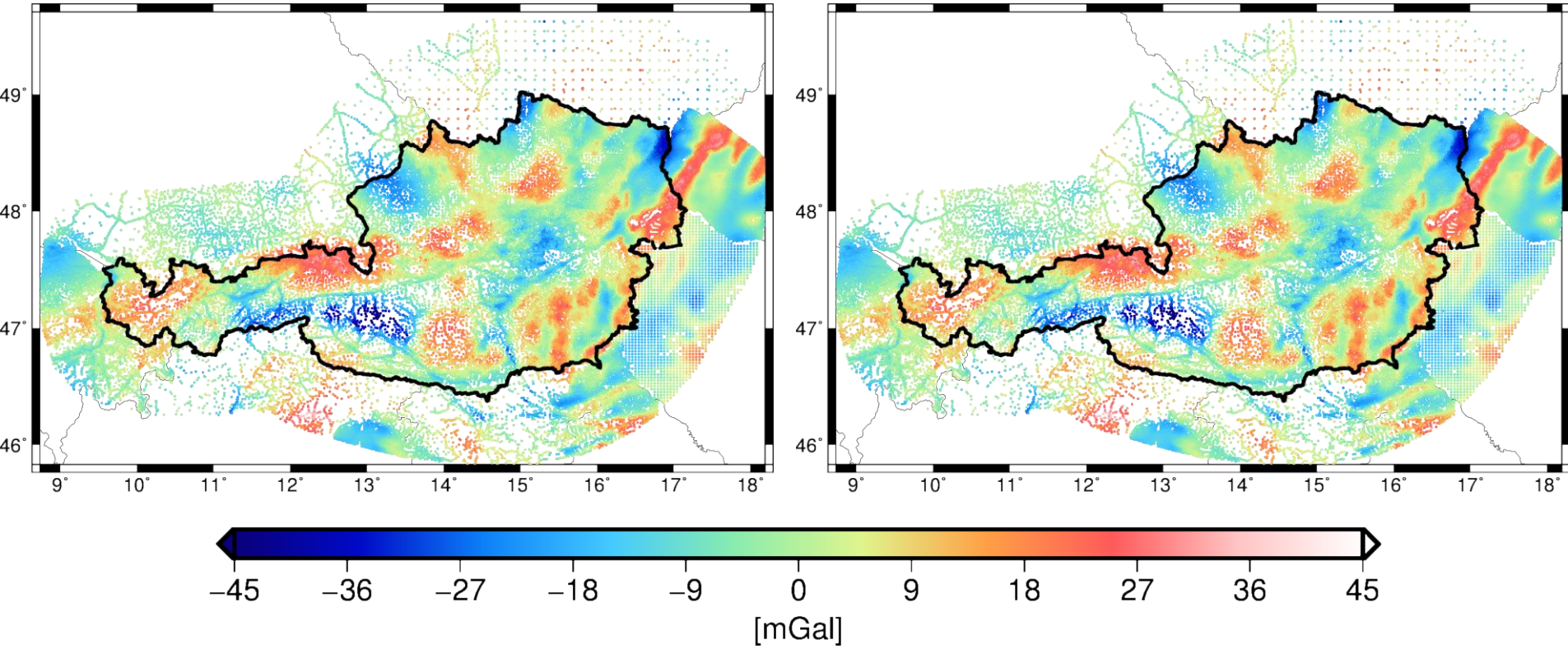
Reduced observations

Classic approach

$$\Delta g = g - \gamma - \Delta g_{sat} - \delta g_{topo}$$

New approach

$$\Delta g = g - \|\mathbf{g}_{sat} + \mathbf{g}_{topo}\|$$



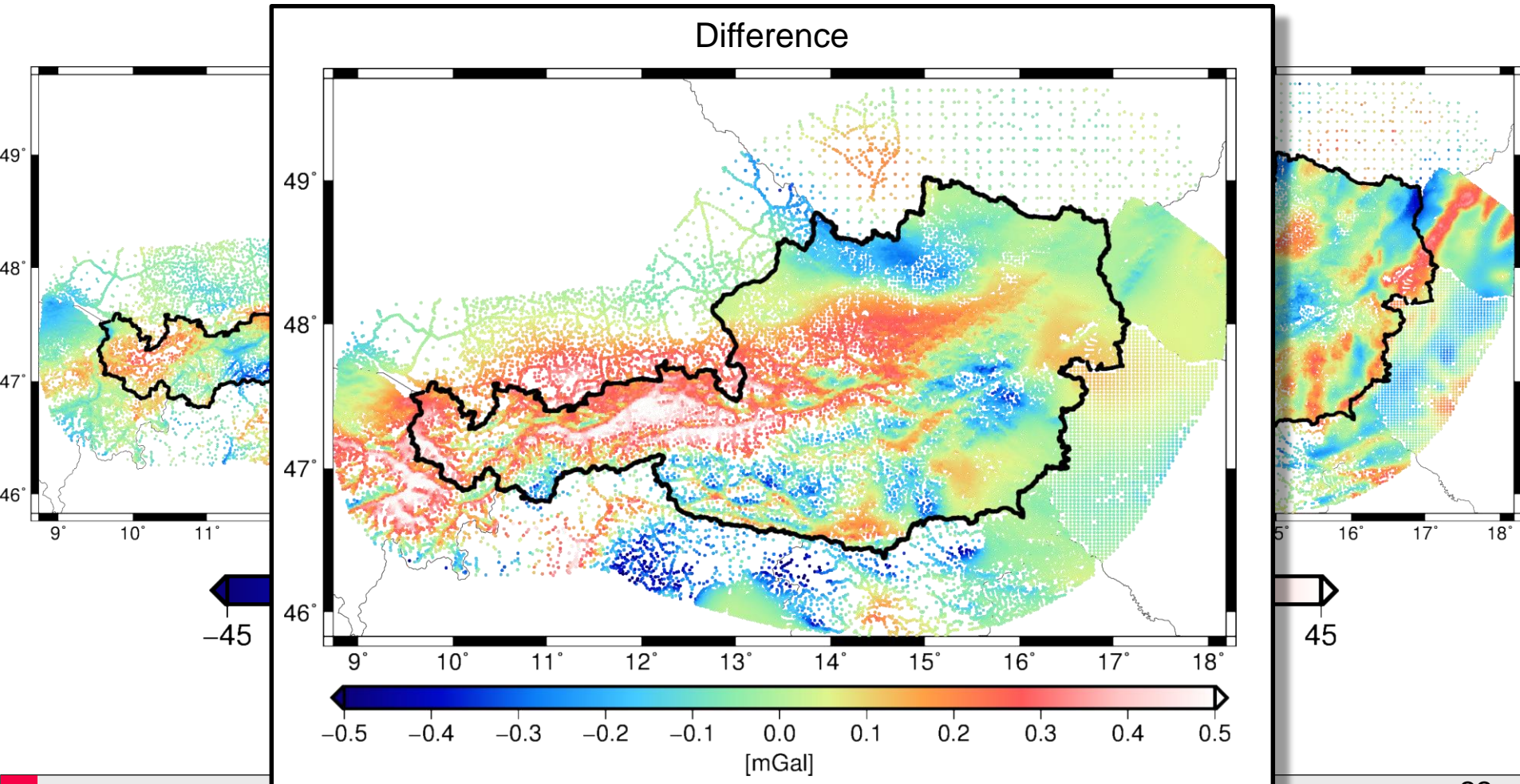
Reduced observations

Classic approach

$$\Delta g = g - \gamma - \Delta g_{sat} - \delta g_{topo}$$

New approach

$$\Delta g = g - \|\mathbf{g}_{sat} + \mathbf{g}_{topo}\|$$



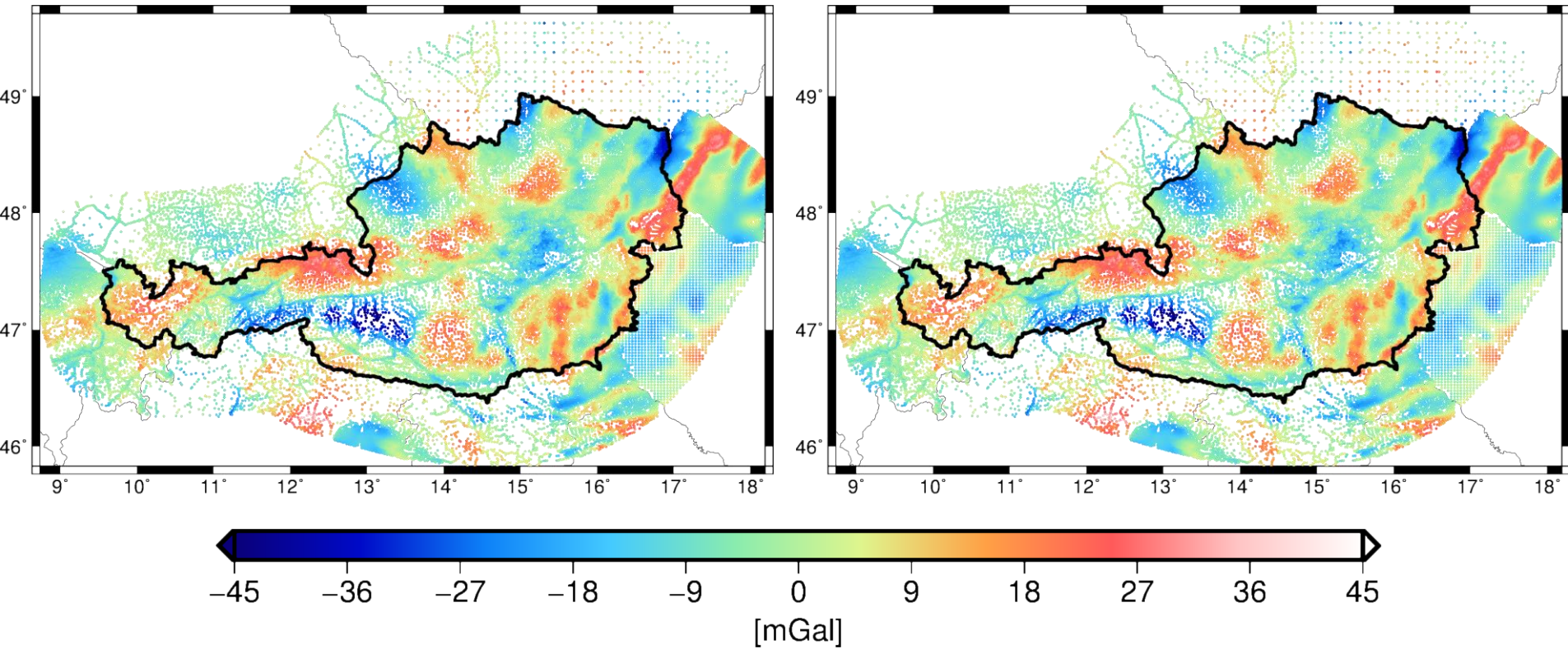
Reduced observations

Classic approach

$$\Delta g = g - \gamma - \Delta g_{sat} - \delta g_{topo}$$

New approach

$$\Delta g = g - \|\mathbf{g}_{sat} + \mathbf{g}_{topo}\|$$



Estimated Geoid

Classic approach

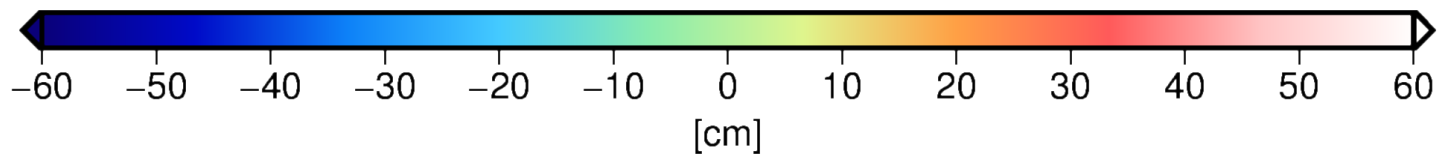
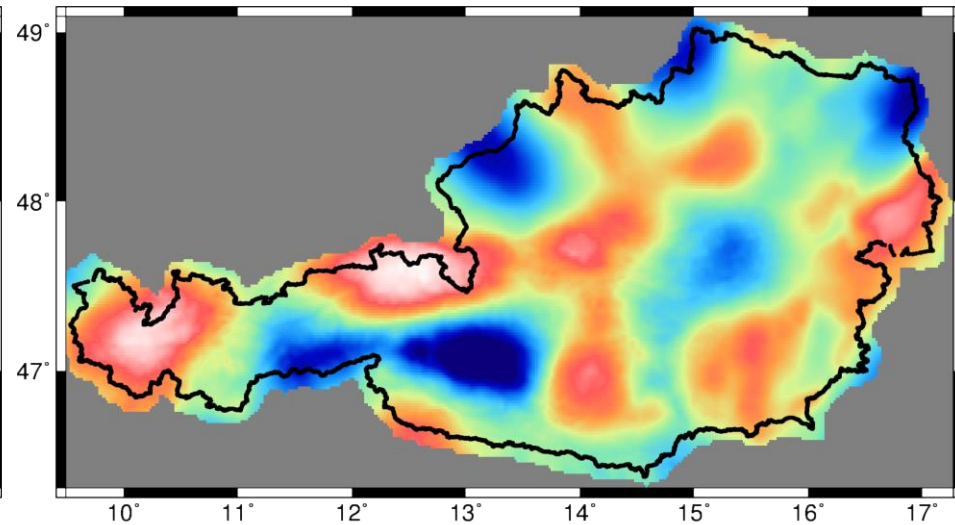
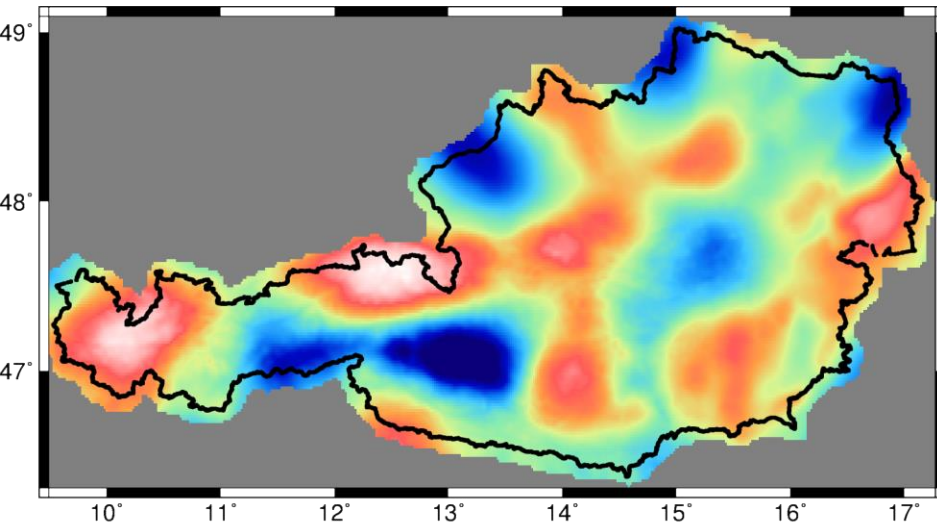
$$\Delta g = g - \gamma - \Delta g_{sat} - \delta g_{topo}$$

⇒ Residual geoid

New approach

$$\Delta g = g - \|\mathbf{g}_{sat} + \mathbf{g}_{topo}\|$$

⇒ Residual geoid



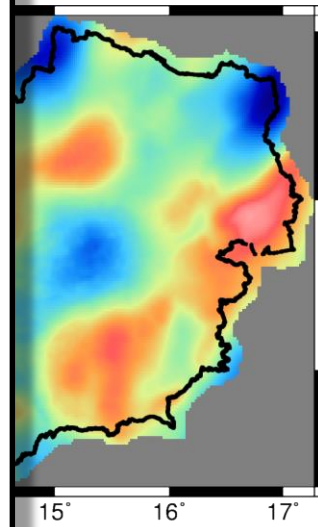
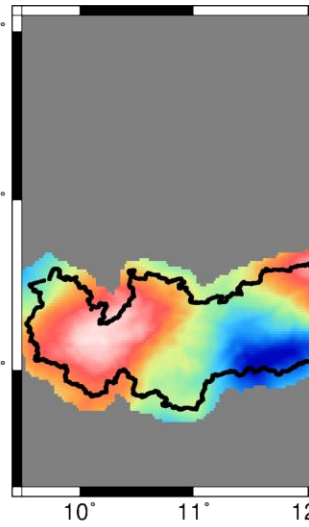
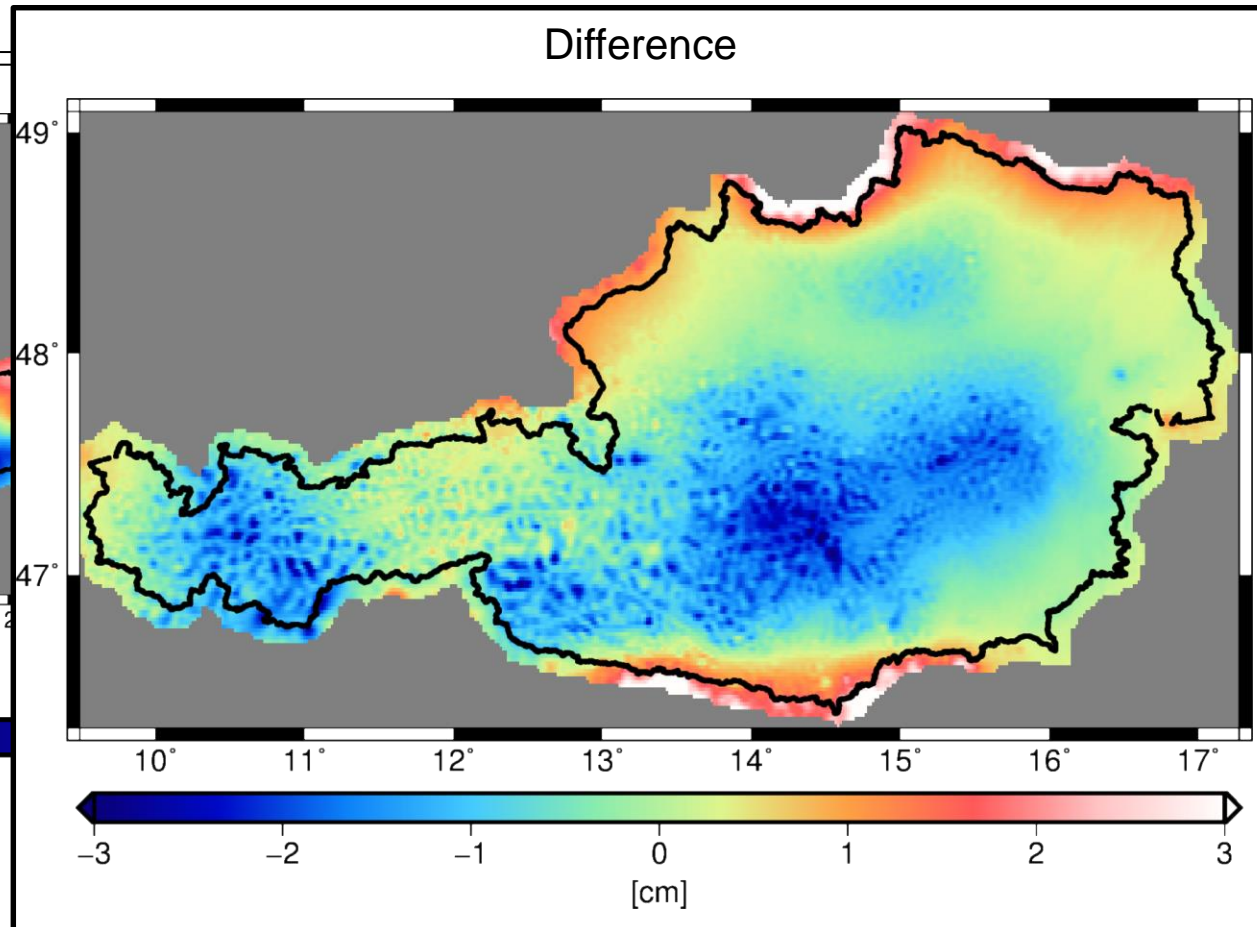
Estimated Geoid

Classic approach

$$\Delta g = g - \gamma - \Delta g_{sat} - \delta g_{topo}$$

New approach

$$\Delta g = g - \|\mathbf{g}_{sat} + \mathbf{g}_{topo}\|$$



-60

60

Summary

Classical definition:

Gravity anomalies = Observed absolute gravity
- Normal gravity

$$\Delta g = g - \gamma$$

⇒ Not accurate enough for geoid computation

Generalized definition:

Gravity anomalies = Observed absolute gravity
- Computed gravity from an approximate model

$$\Delta g = g - \|\mathbf{g}_{sat}\|$$