



14th CIRP Conference on Modeling of Machining Operations, Turin-Italy, 13-14 June 2013

3D Simulation and Process Optimization of Laser Assisted Milling of Ti6Al4V



Prof. C. Sommitsch
Dr. B. Sonderegger
DI J. P. Hermani
DI H. Zamani

Overview

- Laser Assisted Milling
- Experimental Procedure
- Resulting Force Reduction
- 3D FEM of Laser Assisted Machining
- Model Validation
- Summary

Technology Supplier



- Process design and development
- System development and interface design
- Control system
- Machining center



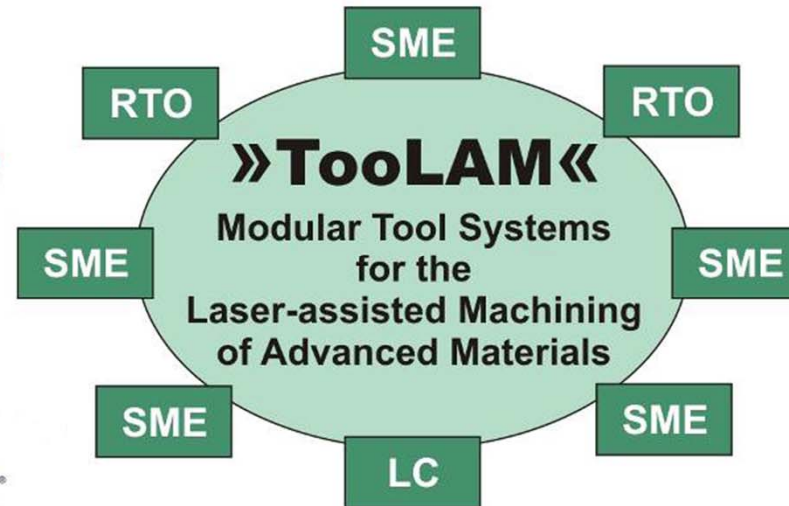
- Demonstrator geometries
- Process and system requirements profile
- System testing, manufacturing of demonstrators



- Thermo-mechanical material modelling
- Simulation of material heating, plastification, material removal



- Design of spindle shaft, housing, machine interface
- Spindle drive and control
- Mechanical interface and clamping system



- CAM-planning
- CAD/CAM-system
- Machining strategies
- Software module for NC-interfacing



- Modularity and scalability concept
- Tool system design
- Mechanical spindle interface
- Clamping system



- Provision of laser source with optical fiber and fiber coupling interface

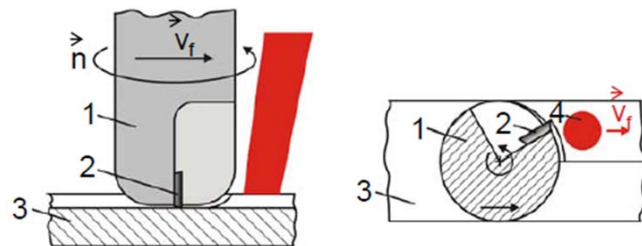


- Ray tracing simulations
- Active beam forming system
- Focusing system

Laser Assisted Milling

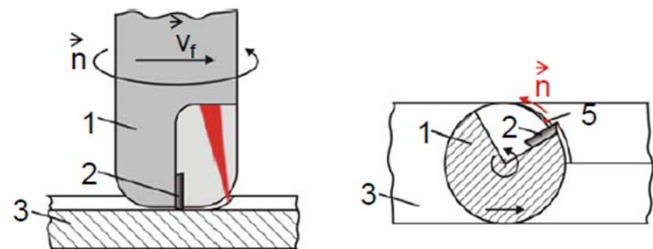
Objective	Reduction of tool wear and increasing material removal rate
Approach	Reduction of process forces
Implementation	Reduction of material strength using laser heating of chip volume

Previous Approach



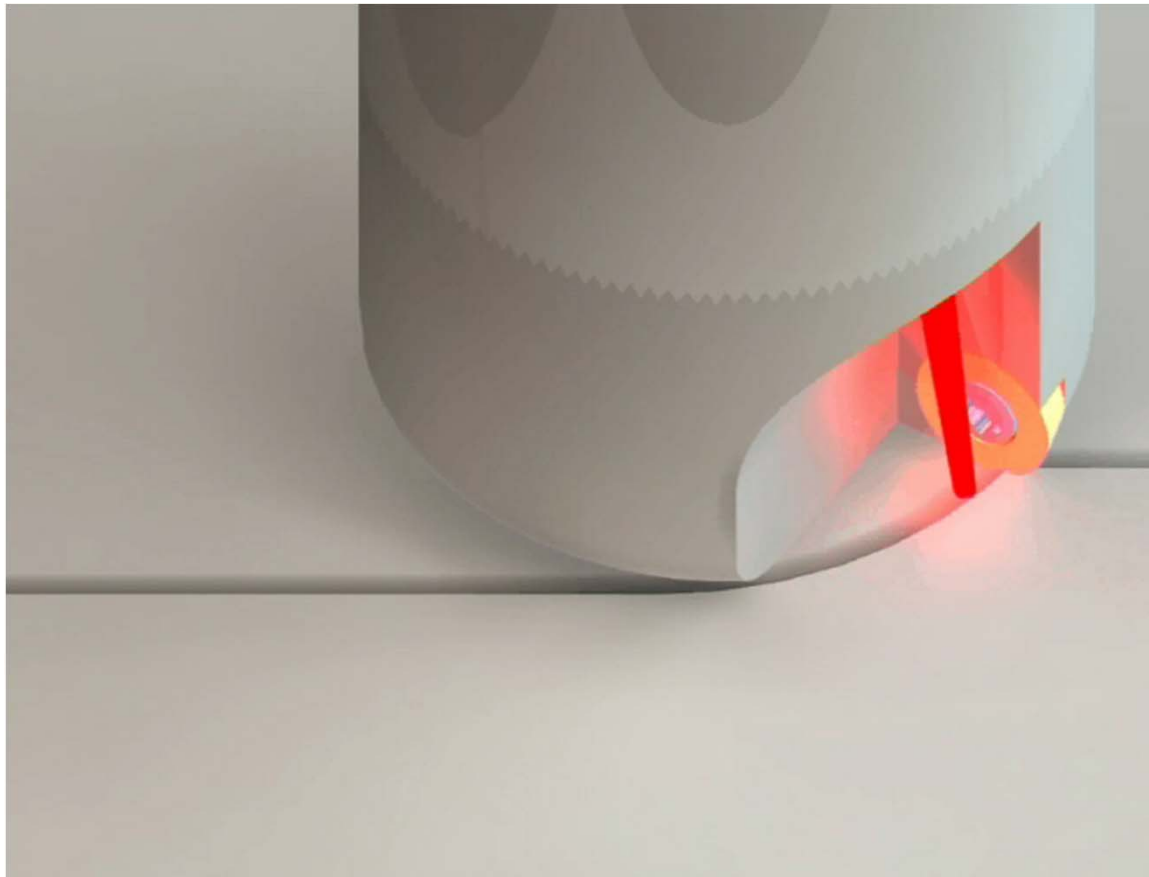
- Irradiation in front of tool
- Movement of laser spot in feed direction
- Laser spot diameter \approx width of cutting
- ➔ Extensive irradiation and thermal damage of workpiece

Novel Approach

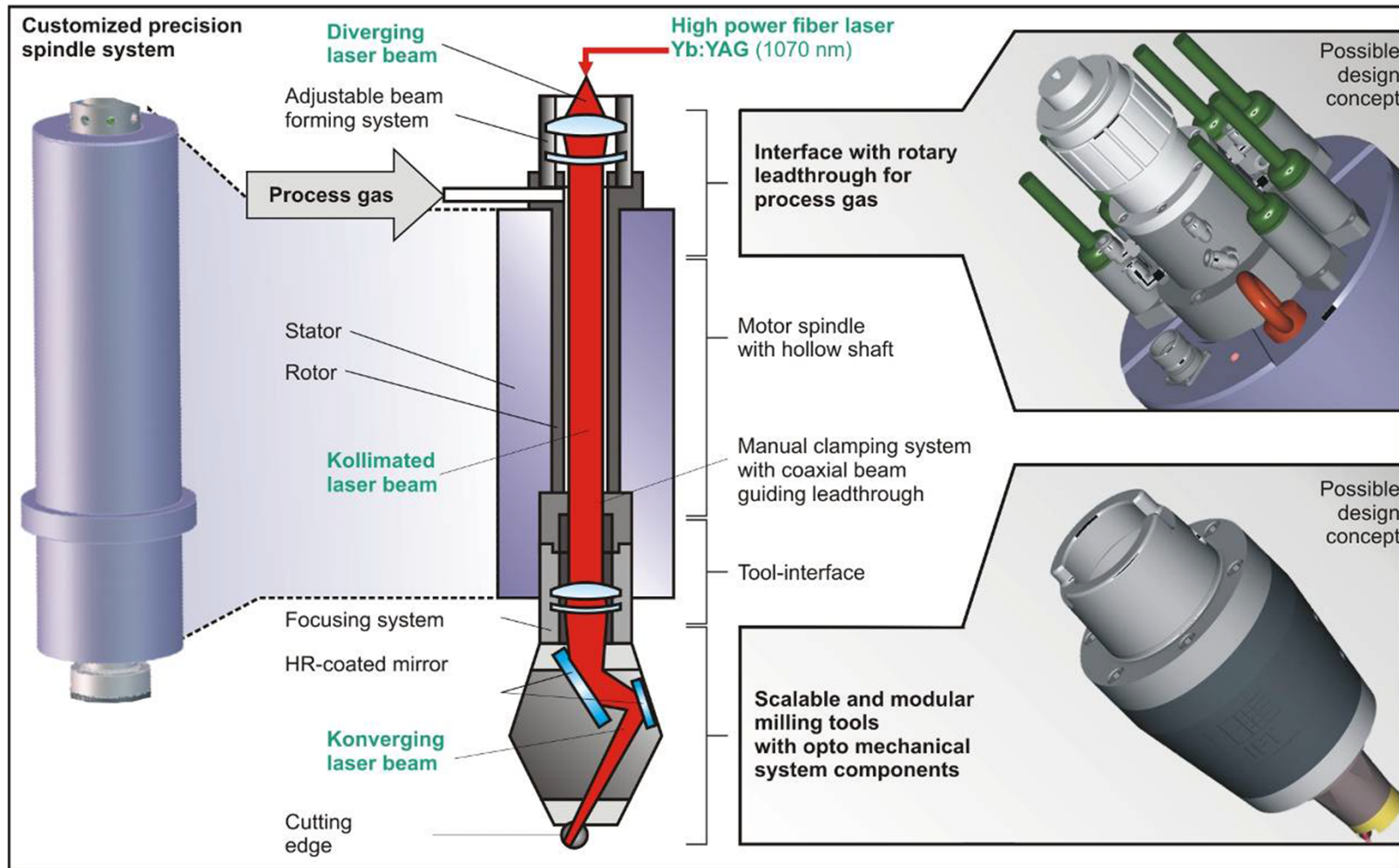


- Irradiation in front of tool tip
- Movement of laser spot with the cutter
- Laser spot diameter \approx feed per tooth
- ➔ Exact irradiation and low thermal damage of workpiece

Working principle of the Novel Laser Assisted Milling



Tool principle of the Novel Laser Assisted Milling



Process Control Parameters

Laser Power is proportional to chip volume:

$$P_L(t) \sim V_{SP}(t)$$

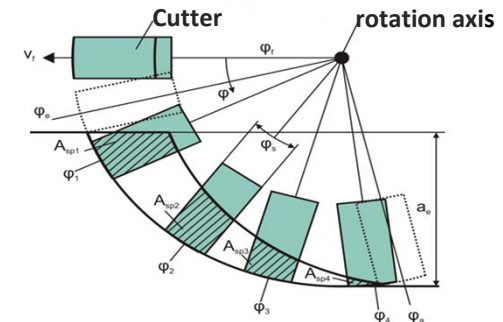
$$V_{SP} = A_{SP} a_p$$

$$A_{SP} = r_F \int_{\varphi_e}^{\varphi_a} h_{SP}(\varphi) d\varphi$$

Chip thickness :

$$h_{SP, Martellotti}(\varphi) = r_F + f_z \sin \varphi - \sqrt{r_F^2 - (f_z \cos \varphi)^2}$$

- Provision of data
 - Cutter entrance angle (φ_e)
 - Cutter exit angle (φ_a)
 - Entrance chip surface ($A_{SP,e}$)
 - Exit chip surface ($A_{SP,e}$)
- Programming of 4 data in NC-Code as linearly interpolated value
- Generation of high frequency analog laser signal



```
G00 X150.000 Y30.000 Z10.000
G00 X150.000 Y30.000 Z-1.000
F100 S00 M03
(Laser Ein)
G01 X105.000 Y30.000 WE250.000 WA250.000 AE0.000 AA0.000
G01 X100.000 Y30.000 WE270.000 WA250.000 AE2.000 AA1.000
G01 X5.000 Y30.000 WE270.000 WA250.000 AE2.000 AA1.000
G01 X0.000 Y30.000 WE250.000 WA250.000 AE0.000 AA0.000
(Laser Aus)
G01 X-50.000 Y30.000 Z-1.000
G00 X-50.000 Y30.000 Z10.000
```



Laser Heat Source Modeling

Absorbed power (P) per unit area (A)

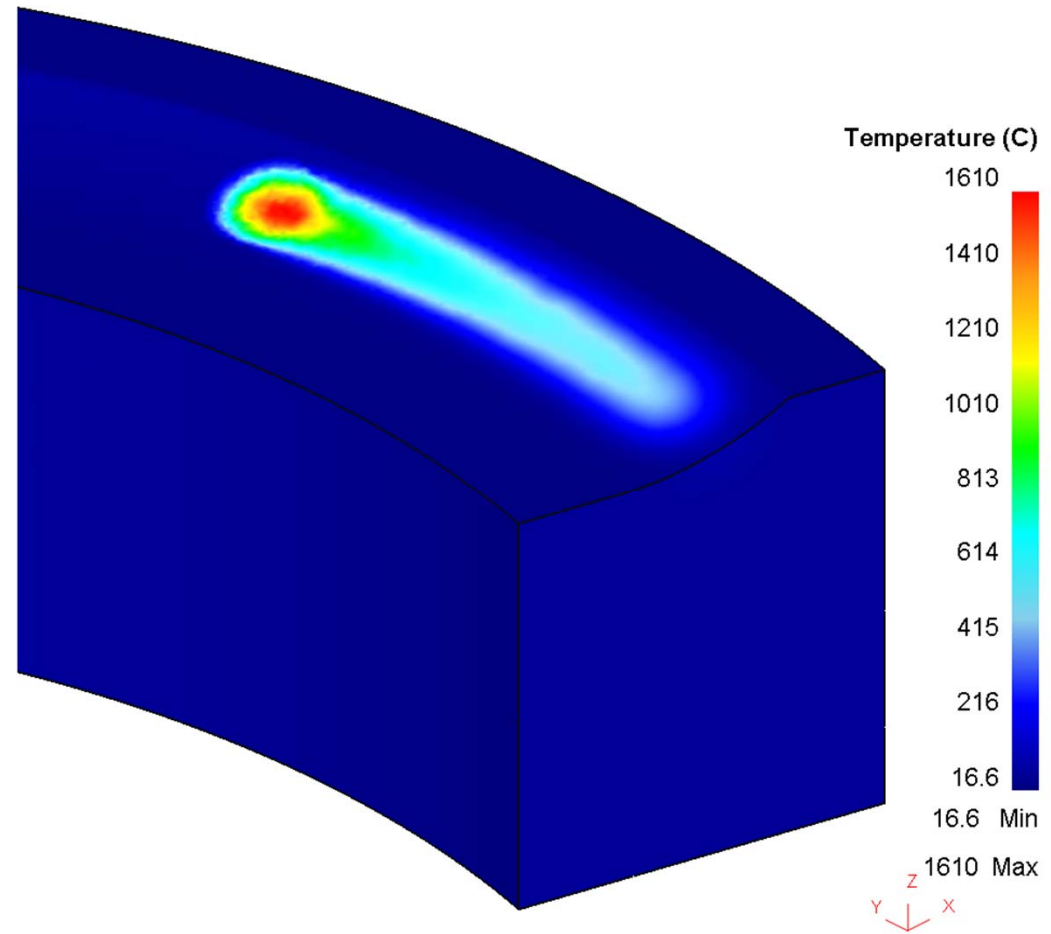
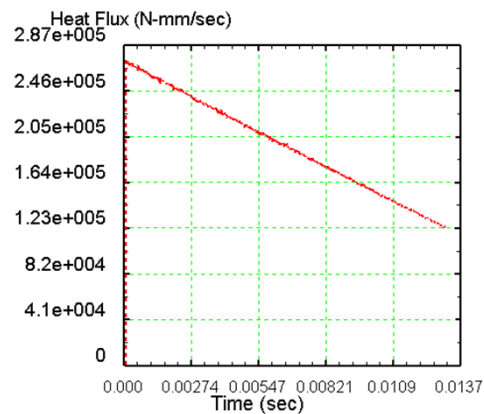
$$P = Ah(T_e - T_s)$$

If the local convection coefficient (h) approaches near zero, the laser power density ($I = P/A$):

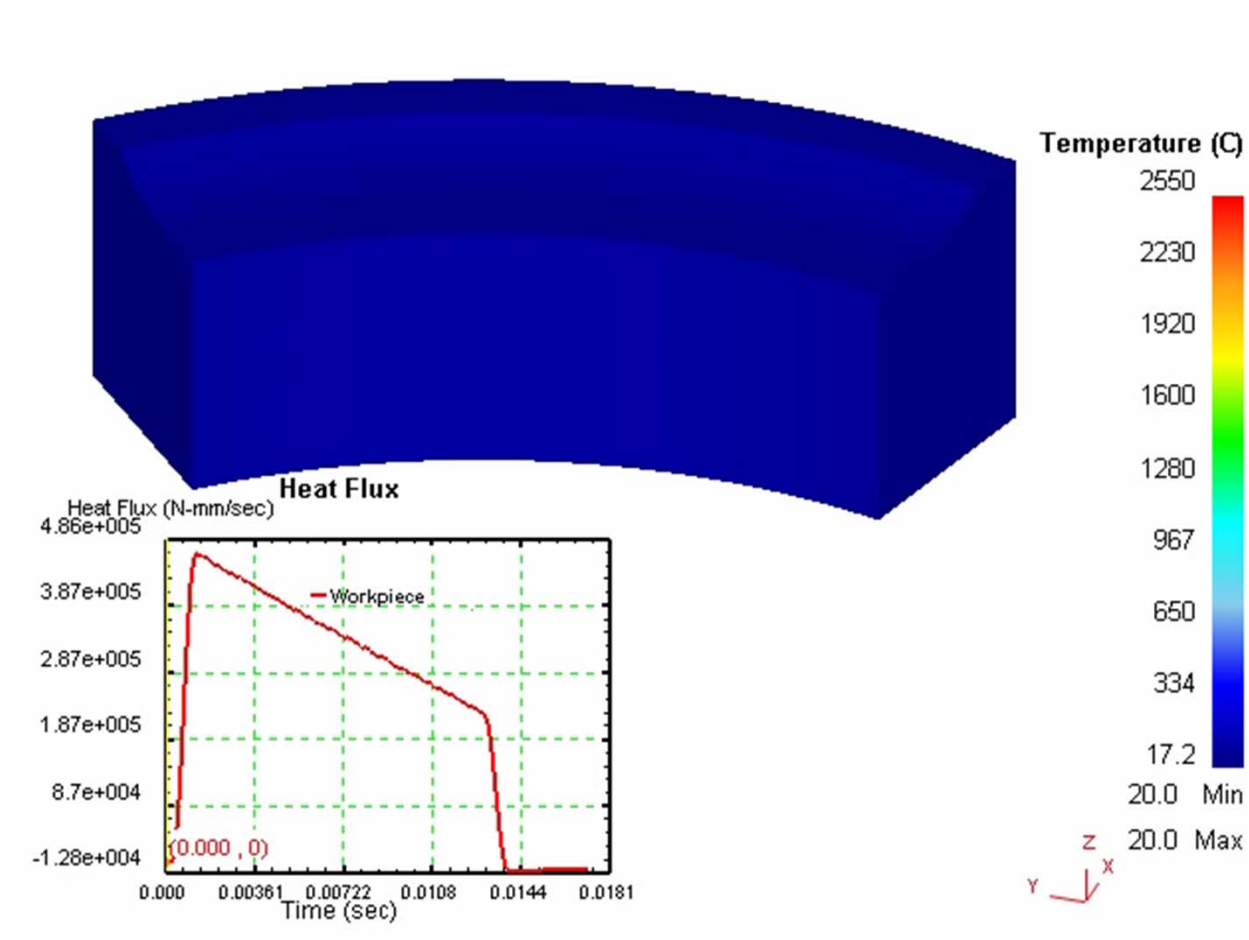
$$I \cong hT_e$$

T_e : environmental temperature

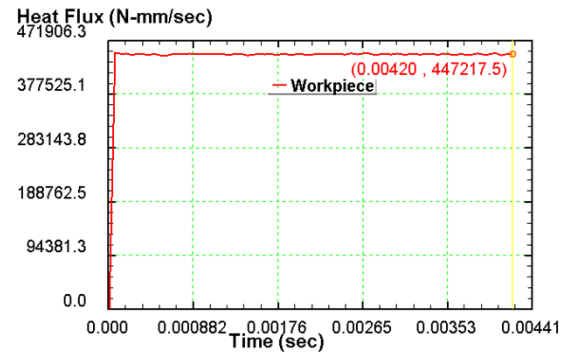
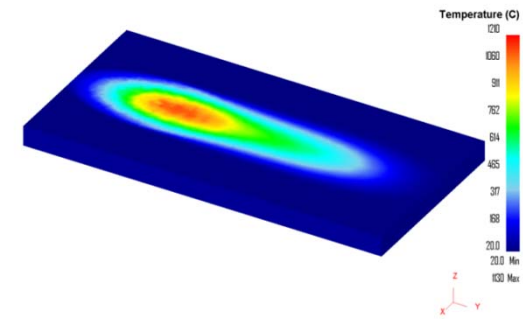
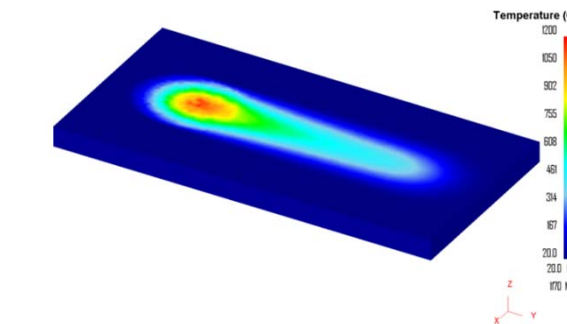
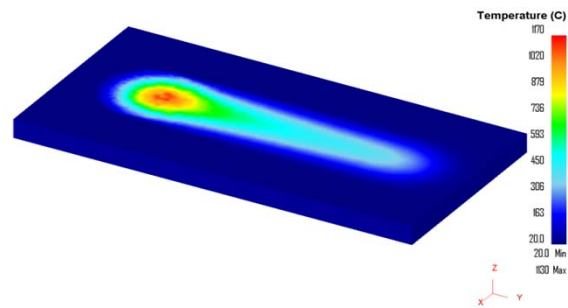
T_s : surface temperature



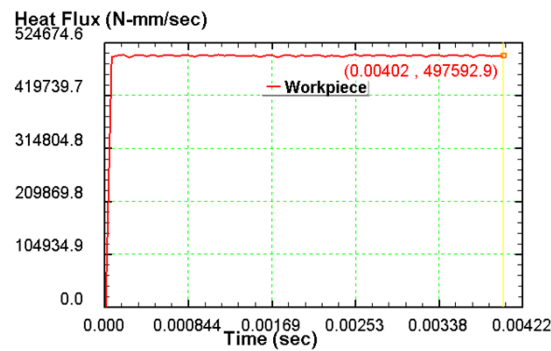
Time Depending Laser Power (Video)



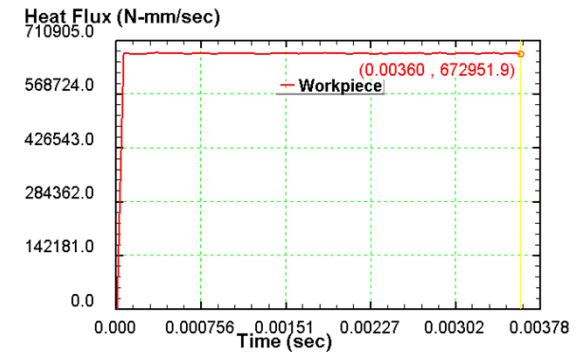
The Modeling of Incident Angle



V=100 m/min
Incident angle= 0 °
Power = 1000 W
 $A_p=0.44$

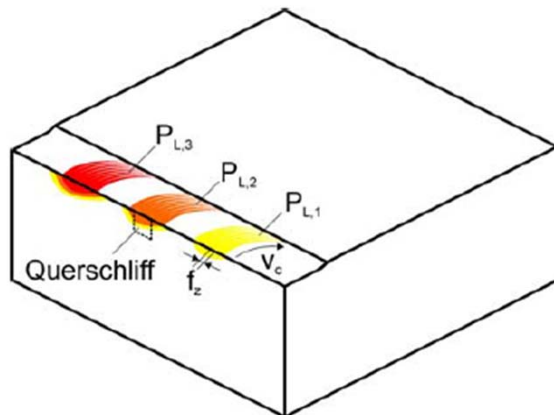
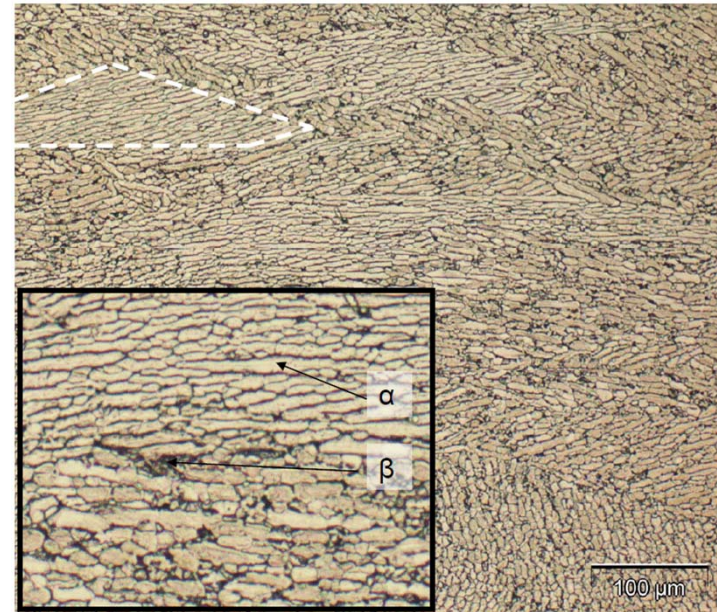
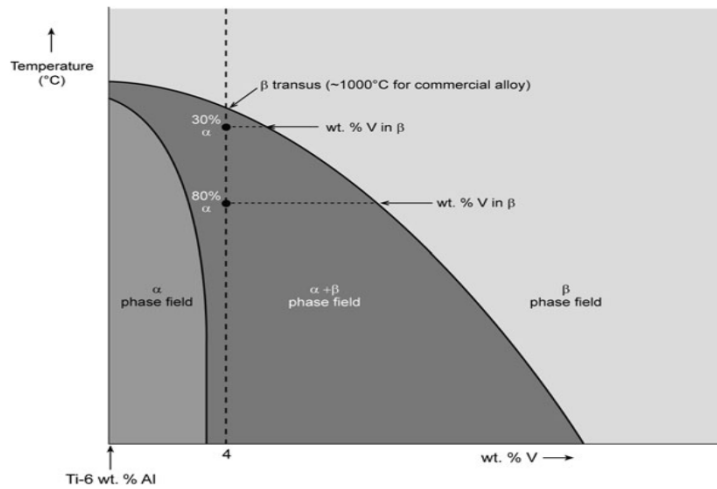


V=100 m/min
Incident angle= 30 °
Power = 1000 W
 $A_p=0.49$



V=100 m/min
Incident angle= 60 °
Power = 1000 W
 $A_p=0.67$

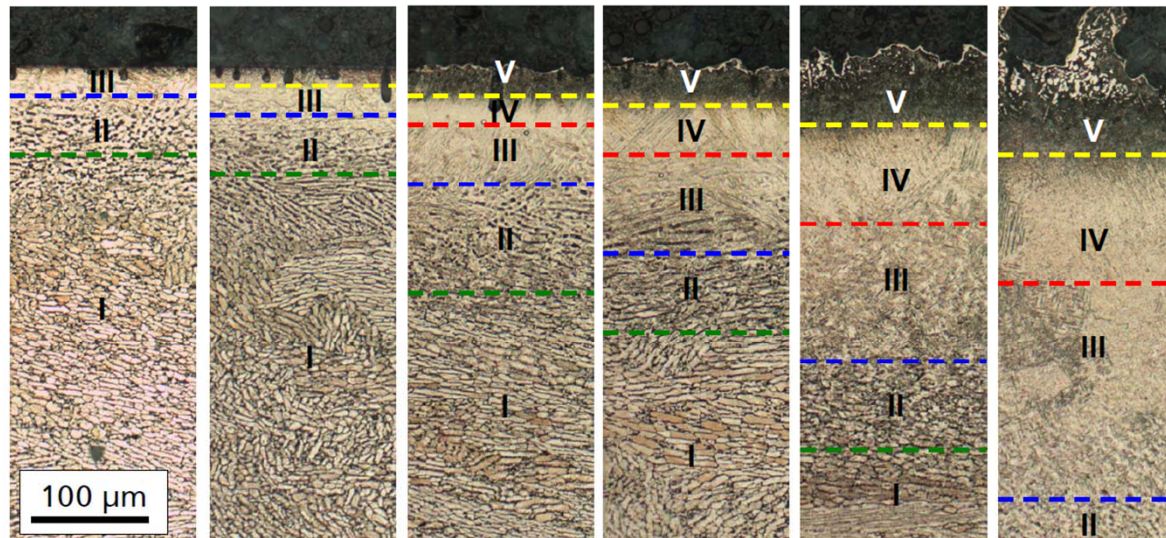
Absorption Coefficient



Approach:

- Irradiation of **Ti-6Al-4V** workpiece without tool engagement at different laser powers
- Cutting velocity: 25 m/min (331 rpm)
- Feed=50 μm/rev
- Determination of max. temperature by means of depth and kind of microstructure

Absorption Coefficient



$P_{L,eff} = 893 \text{ W}$ $P_{L,eff} = 1071 \text{ W}$ $P_{L,eff} = 1250 \text{ W}$ $P_{L,eff} = 1428 \text{ W}$ $P_{L,eff} = 1607 \text{ W}$ $P_{L,eff} = 1785 \text{ W}$

T_{β}	0 μm	0 μm	51 μm	76 μm	136 μm	186 μm
T_{MS}	17 μm	42 μm	102 μm	161 μm	254 μm	373 μm

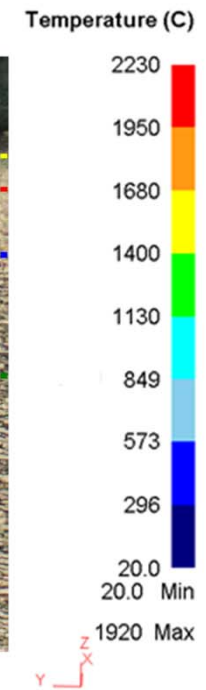
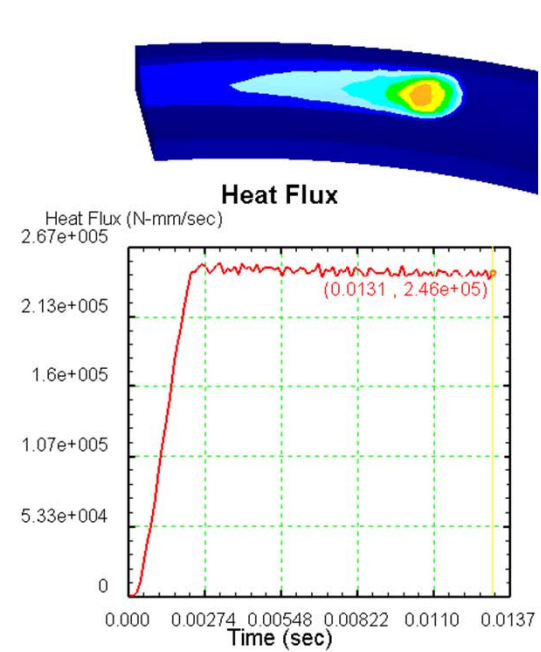
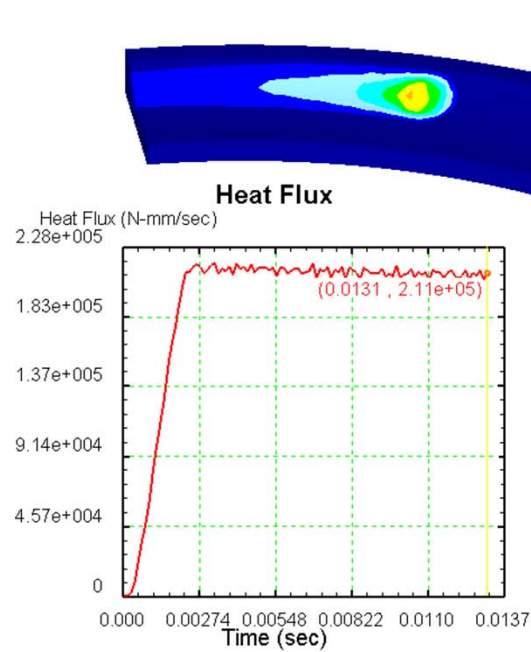
Estimated absorption coefficient (α):
 0.27 ± 0.03

- I. initial microstructure ($\alpha+\beta$)
- II. no martensitic transformation but β transformation from α
- III. partial martensitic transformation
- IV. complete martensitic transformation
- V. oxide layer and white surface layer

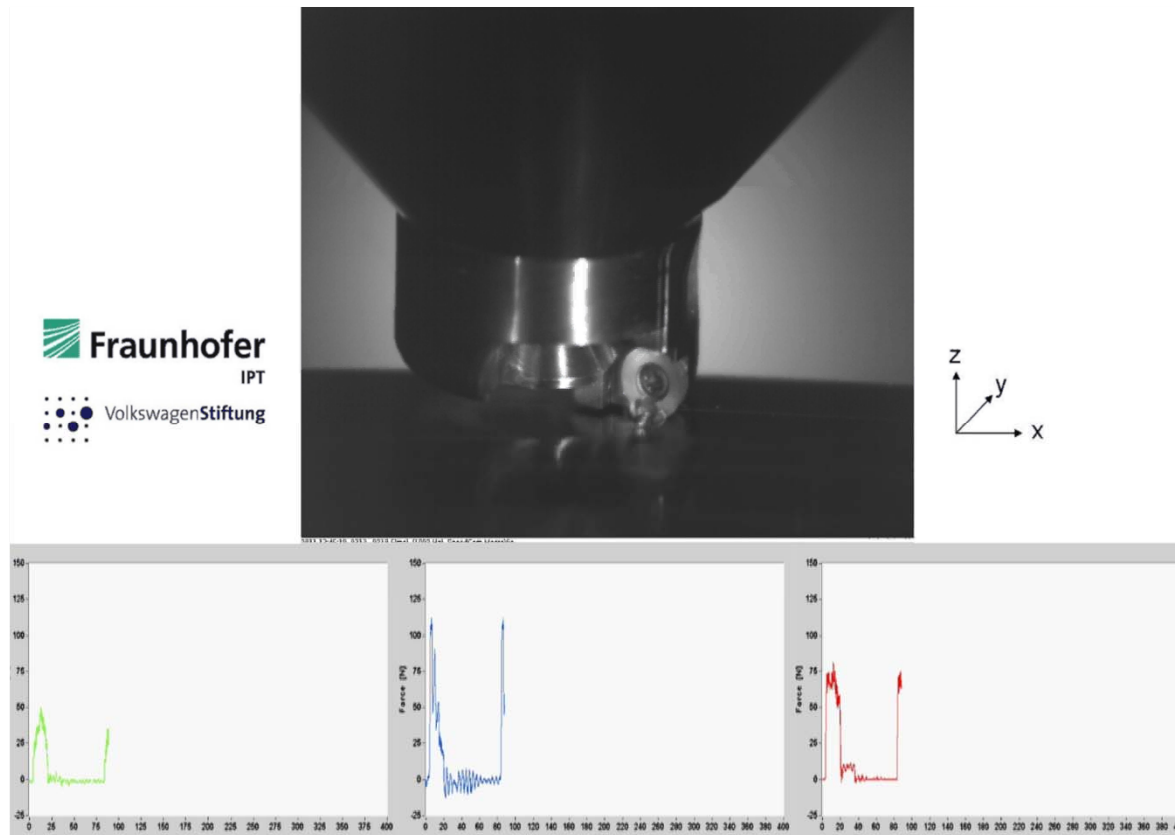
Thermal Model Validation

V=25 m/min
 Feed=50 $\mu\text{m}/\text{rev}$
 Power = 1071 W
 $\alpha = 0.23$

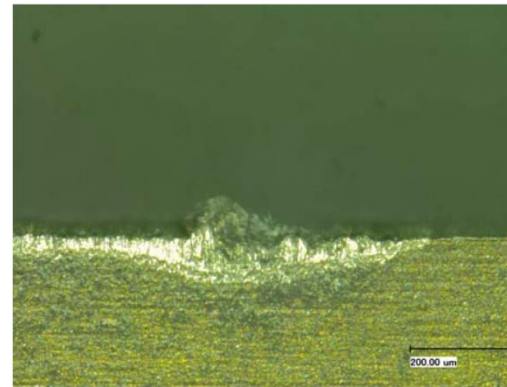
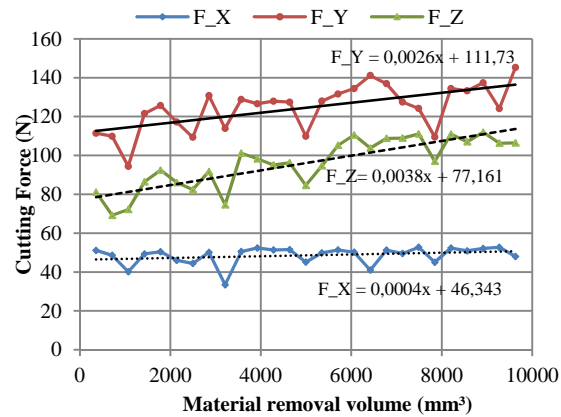
V=25 m/min
 Feed=50 $\mu\text{m}/\text{rev}$
 Power = 1250 W
 $\alpha = 0.23$



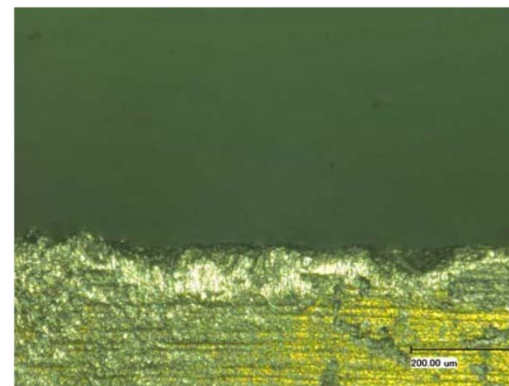
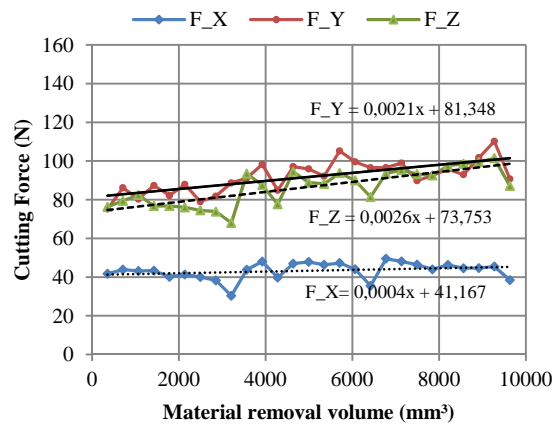
Laser Assisted Milling (Video)



Process Forces and Tool Wear



V=50 m/min
Feed=70 µm/rev
Power = 0 W
Laser advance= 6 mm

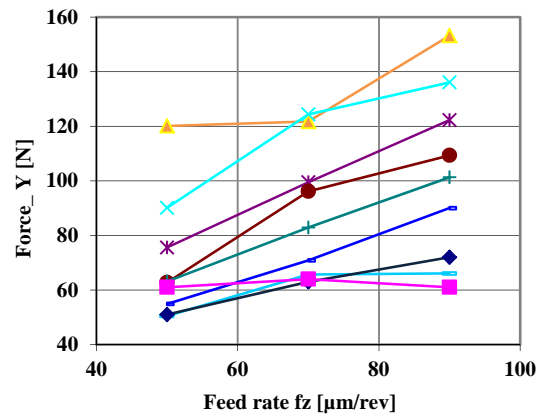


V=50 m/min
Feed=70 µm/rev
Power = 1428 W
Laser advance= 6 mm

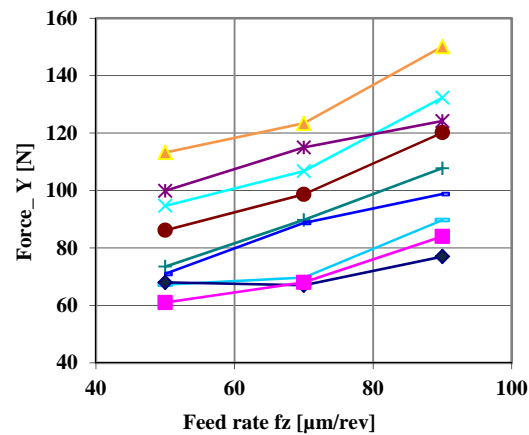
The effect of milling time on the process forces and flank wear

Process Forces

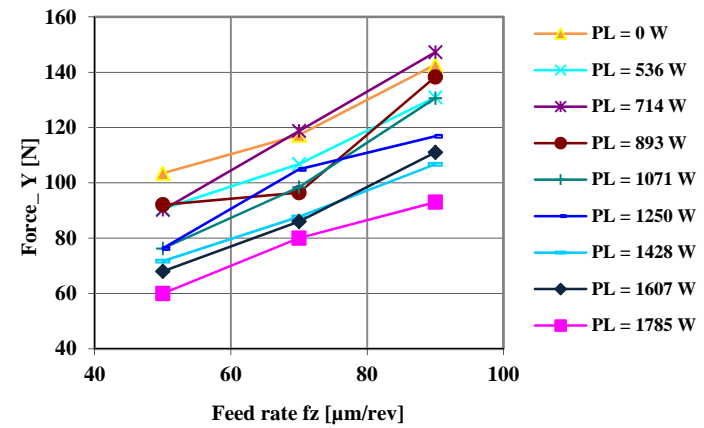
The effect of cutting velocity on the main cutting force at different laser powers



cutting velocity
25 m/min



cutting velocity
50 m/min

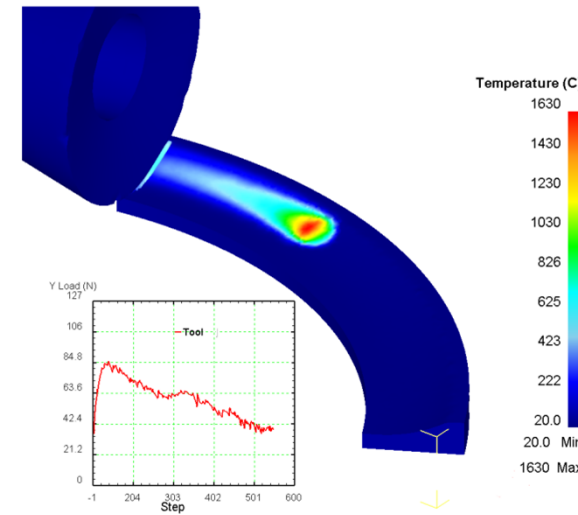


cutting velocity
100 m/min

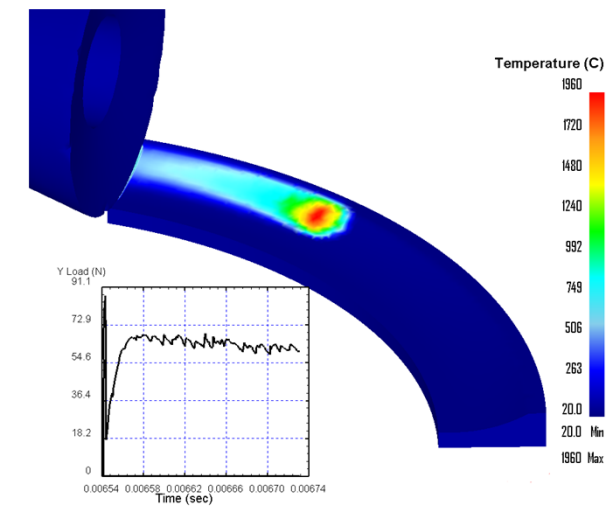
Absolute value of force reduction decreases with cutting velocity

3D FEM of Laser Assisted Milling

Material	Conductivity (W/mK)	Part (Ti6Al4V)	25 °C	7
			500 °C	12.6
			900 °C	20.2
			995 °C	19.3
	1100 °C	21		
	1650 °C	28.4		
heat capacity (J/Kg °C)	Part (Ti6Al4V)	25 °C	546	
		500 °C	651	
		900 °C	734	
		995 °C	641	
1100 °C	660			
1650 °C	759			
Tool (TiAlN-coated cemented carbide)	25 °C	12		
	1000 °C	20		
heat transfer coefficient (kW/m²K)	50			
	Friction coefficient $m=0.7 \quad \mu=0.5$			
Forced convection (Air jet cooling, Overhead) (W/m²K)	2000			
	Cutter RDHX 0702 MOT			
Milling condition	Cutting width(mm) 8			
	Nose radius(mm) 0.02			
	Depth of cut (mm) 0.5			
	Cutting velocity(m/min) 25, 50, 75, 100			
	Feed (mm/rev) 0.05, 0.07, 0.09			
	Laser power (W) 536, 714, 893, 1071, 1250, 1428			
	Rake angle (°) 11			
	Y Load (N) 127			



Video



3D FEM of Laser Assisted Milling

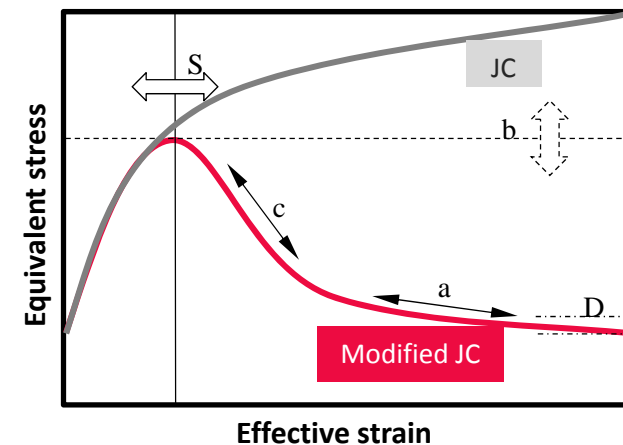
Modified (TANH) Johnson- Cook

$$\sigma_{eq} = \left(A + \frac{B\varepsilon^n}{\exp(\varepsilon^a)} \right) \left(1 + C \ln \left(\frac{\dot{\varepsilon}}{\dot{\varepsilon}_0} \right) \right) \left(1 - \left(\frac{T - T_r}{T_m - T_r} \right)^m \right) \left(D + (1 - D) \left[\tanh \left(\frac{1}{(\varepsilon + S)^c} \right) \right]^e \right)$$

$$D = 1 - \left(\frac{T}{T_m} \right)^d \quad p = \left(\frac{T}{T_m} \right)^b$$

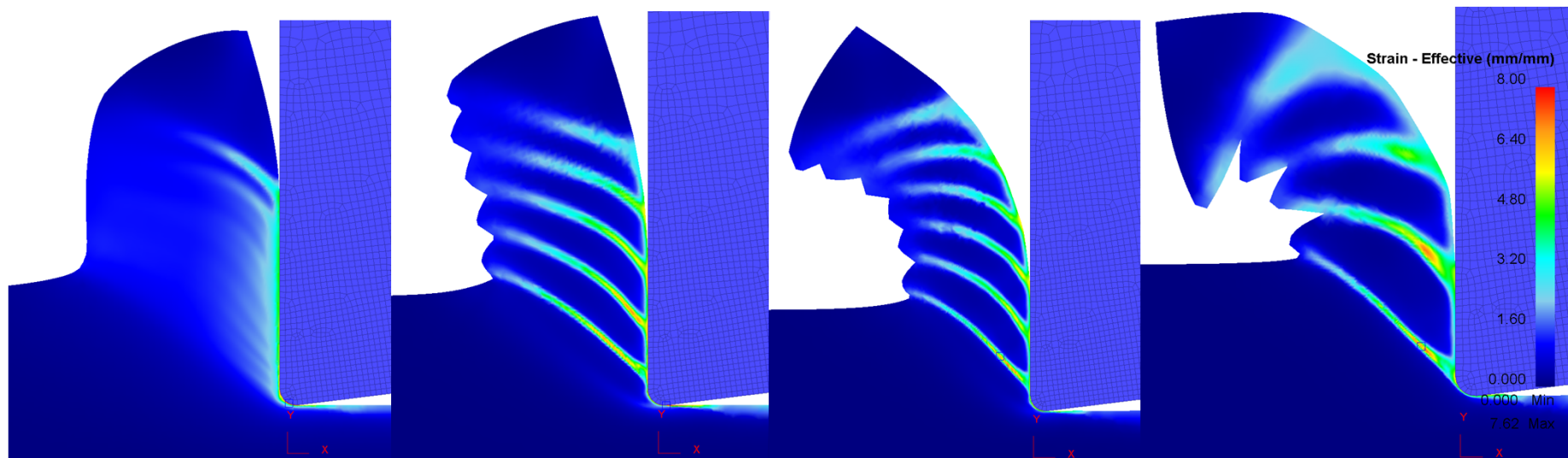
Johnson- Cook

$$\sigma_{eq} = (A + B\varepsilon^n) \left(1 + C \ln \left(\frac{\dot{\varepsilon}}{\dot{\varepsilon}_0} \right) \right) \left(1 - \left(\frac{T - T_r}{T_m - T_r} \right)^m \right)$$



	A (MPa)	B (MPa)	C	m	n	T _m (°C)	a	b	c	d	e
Modified JC-model [Sima et al, 2010]	724	683.2	0.035	1.0	0.47	1660	2	1	2	1	0.05

2D Chip Formation



V=0.005 m/s
 Feed=100 $\mu\text{m}/\text{rev}$
 Rake angle= 0 $^\circ$
 Power = 0 W

V=0.05 m/s
 Feed=100 $\mu\text{m}/\text{rev}$
 Rake angle= 0 $^\circ$
 Power = 0 W

V=0.5 m/s
 Feed=100 $\mu\text{m}/\text{rev}$
 Rake angle= 0 $^\circ$
 Power = 0 W

V=5 m/s
 Feed=100 $\mu\text{m}/\text{rev}$
 Rake angle= 0 $^\circ$
 Power = 0 W

Nonlinear Thermal Softening (NTS)

Johnson- Cook

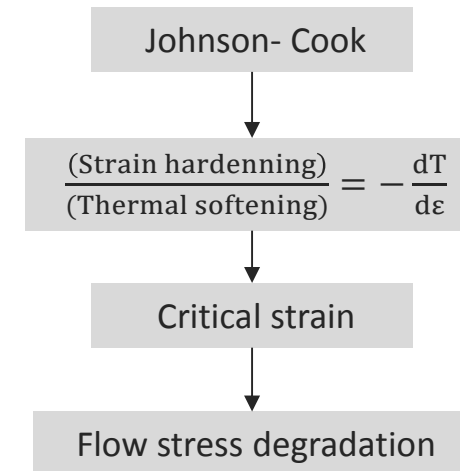
$$\sigma_{eq} = (A + B\varepsilon^n) \left(1 + C \ln \left(\frac{\dot{\varepsilon}}{\dot{\varepsilon}_0} \right) \right) \left(1 - \left(\frac{T - T_r}{T_m - T_r} \right)^m \right)$$

Minimum strain rate ($\dot{\varepsilon}_c$) for occurrence of adiabatic shear (a simplification for 3D modeling)

$$\dot{\varepsilon}_c = \frac{-\dot{\alpha}nk(T)}{R^2 \left(\frac{\partial \sigma}{\partial T} \right)_{\varepsilon, \dot{\varepsilon}}}$$

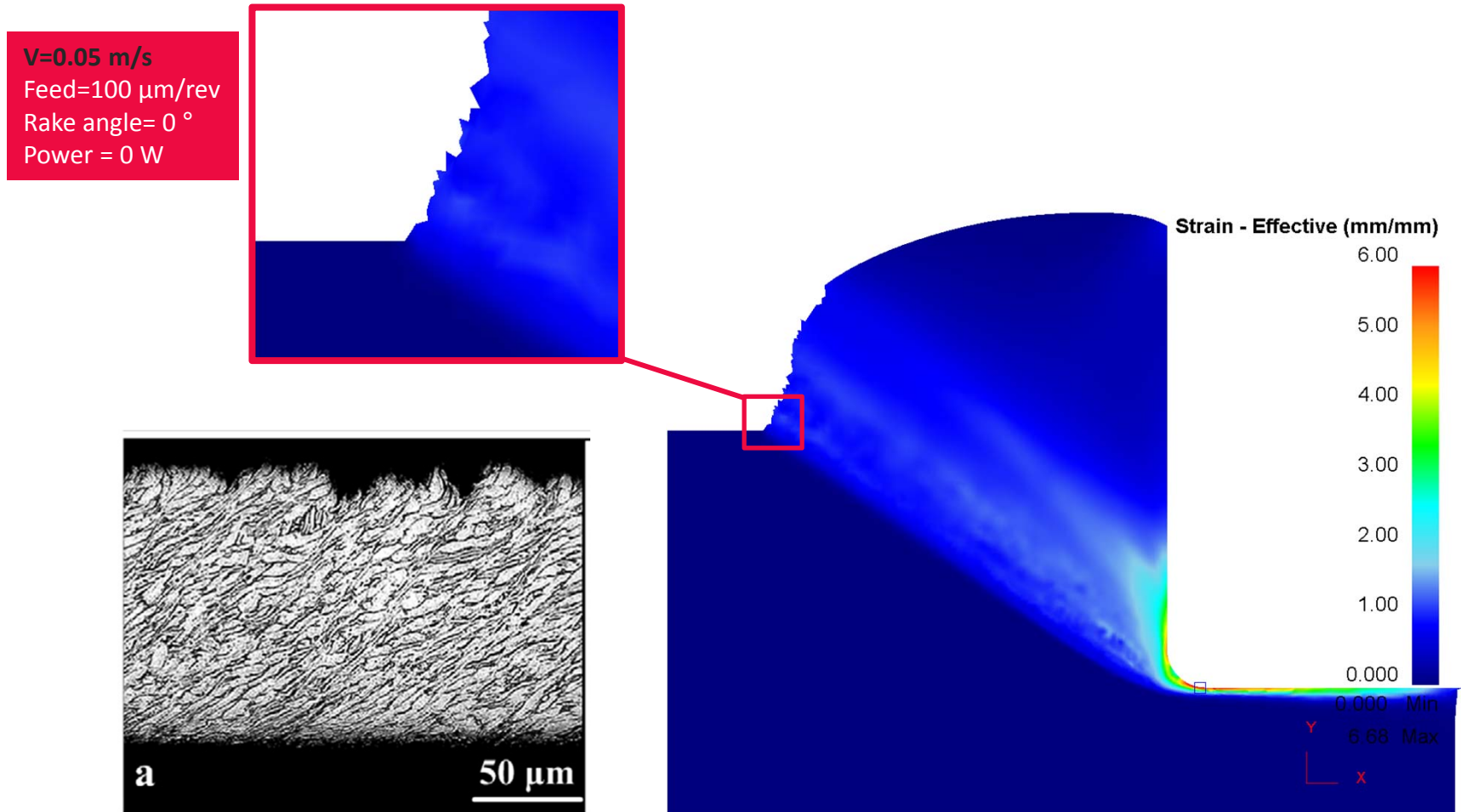
Nonlinear thermal softening at high strain rates

$$m = m_0 \exp(-aT^b)$$



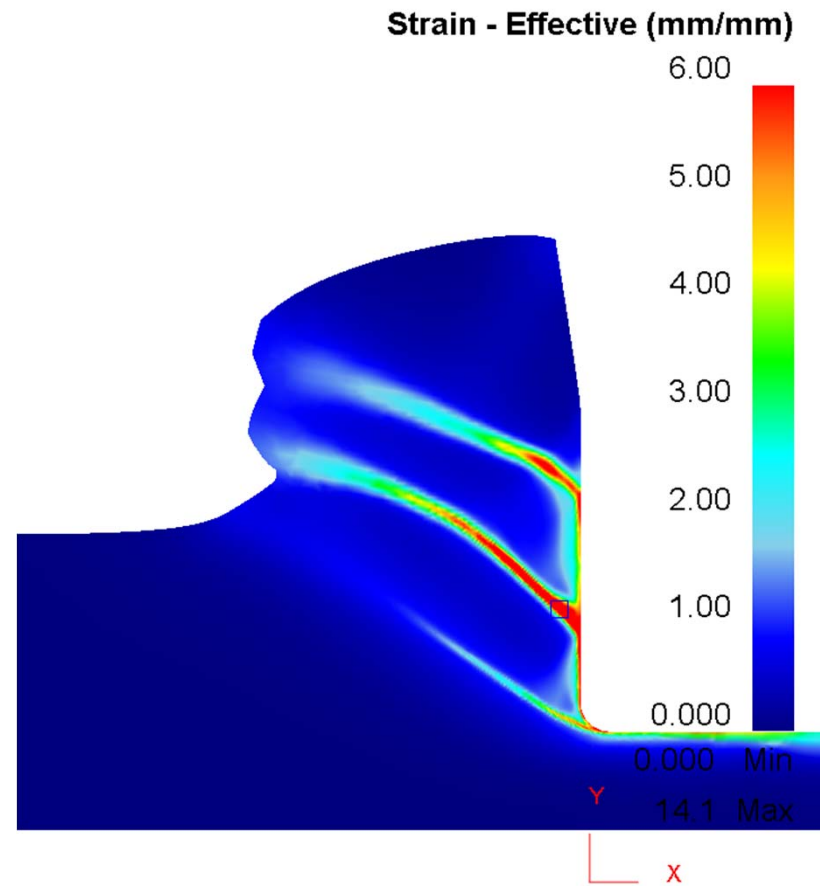
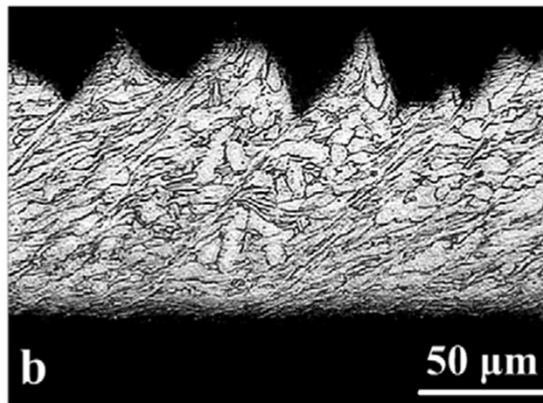
	A (MPa)	B (MPa)	C	m	n	T _m (°C)	a	b	m ₀	α
Modified JC-model	724	683.2	0.035	1.0	0.47	1660	10 ⁻⁷	2.9	1	10 ⁻⁴

2D Chip Formation (NTS)



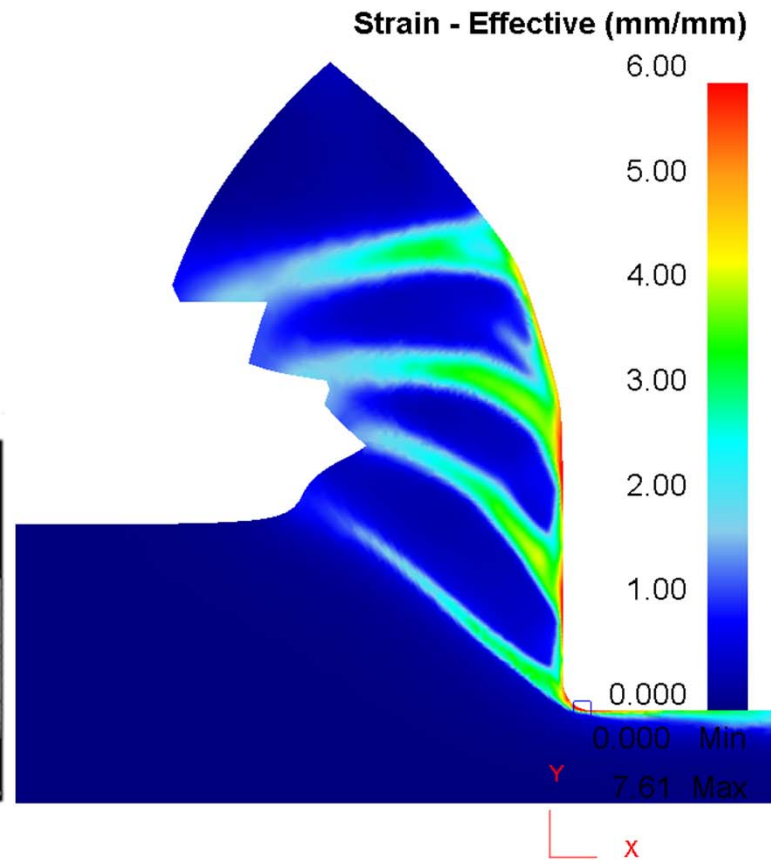
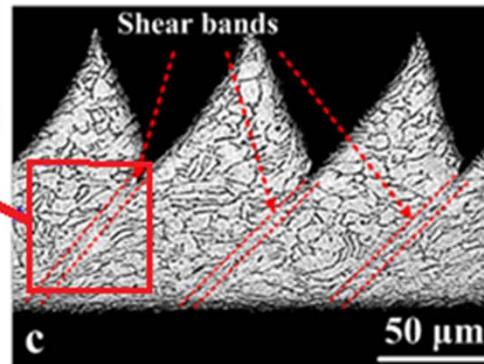
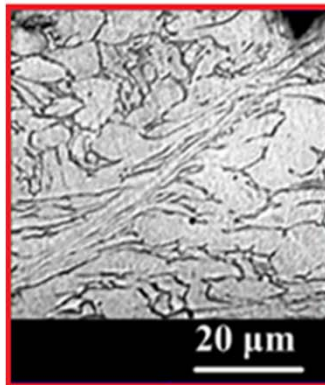
2D Chip Formation (NTS)

V=0.5 m/s
 Feed=100 $\mu\text{m}/\text{rev}$
 Rake angle= 0°
 Power = 0 W



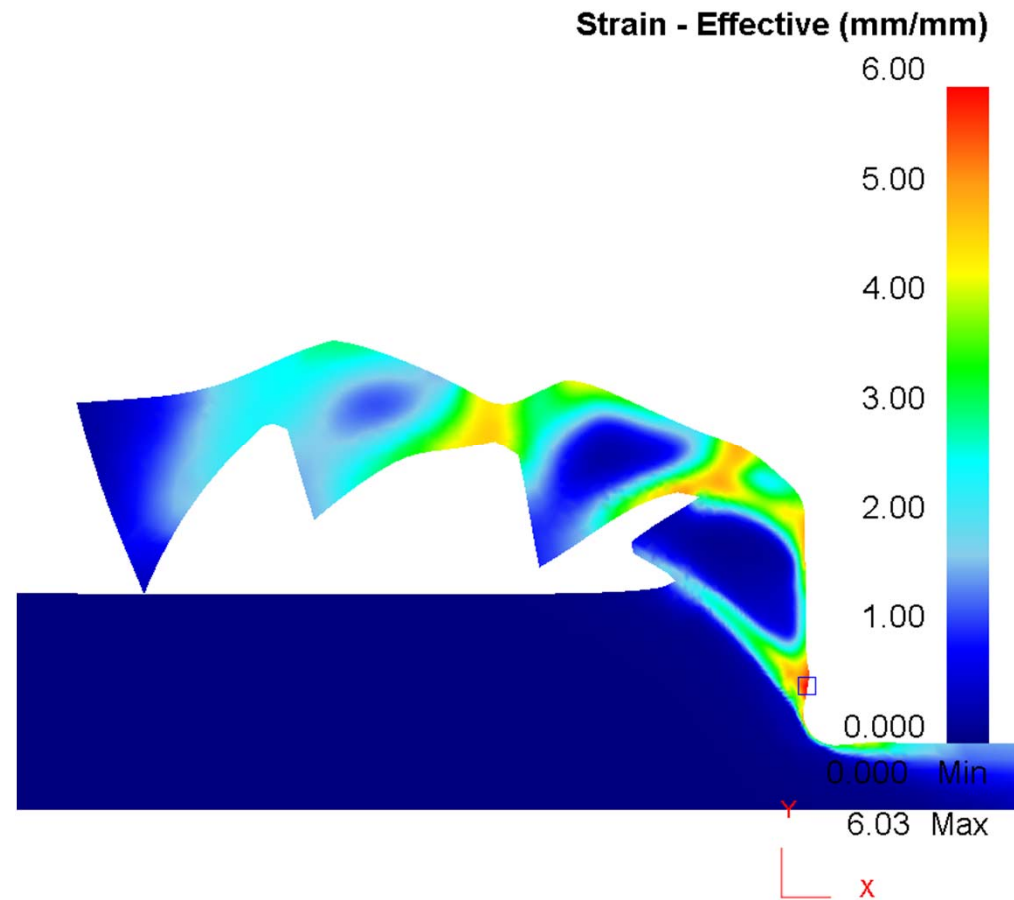
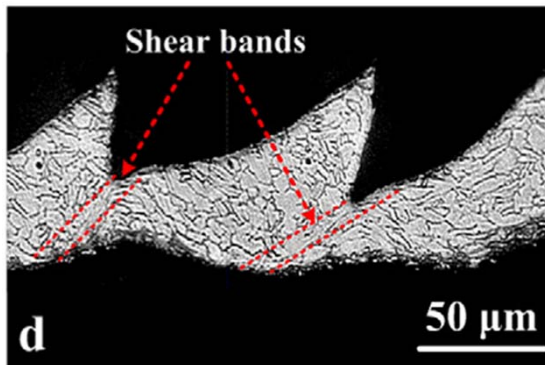
2D Chip Formation (NTS)

$V=5\text{ m/s}$
 Feed=100 $\mu\text{m/rev}$
 Rake angle= 0°
 Power = 0 W

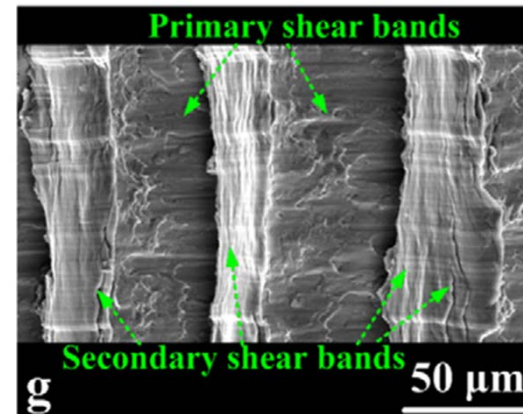
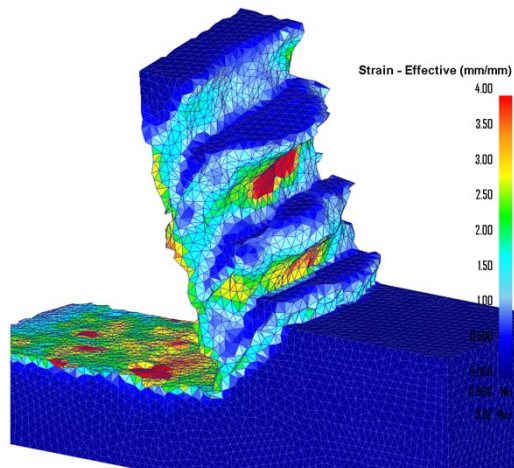
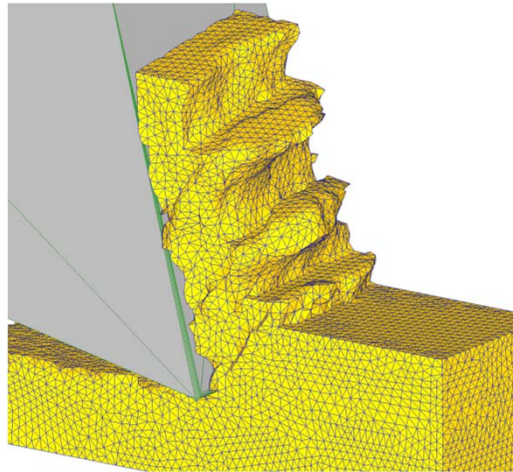


2D Chip Formation (NTS)

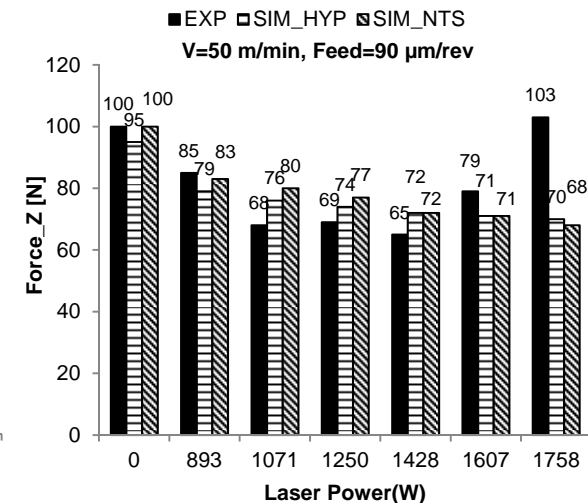
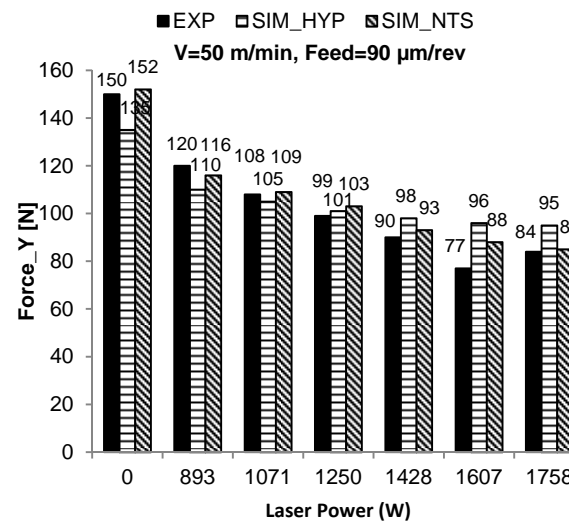
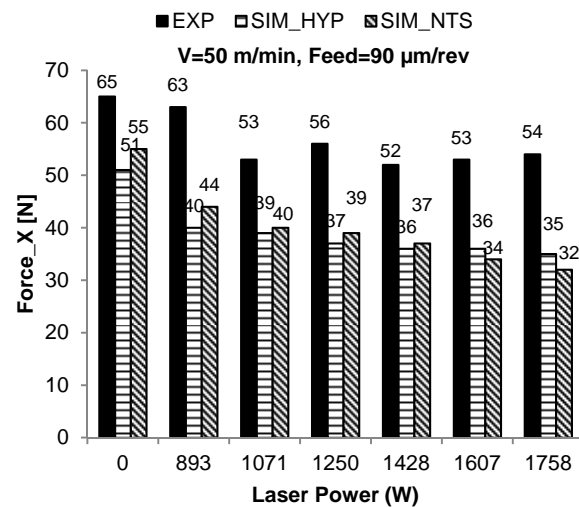
$V=312\text{ m/s}$
 Feed=100 $\mu\text{m/rev}$
 Rake angle= 0°
 Power = 0 W



3D Chip Formation (NTS)



3D Model validation



- The amount of predicted force reduction with increasing the laser power in X direction is higher than the experimental results
- An excellent agreement for cutting forces in Y-direction was found for the used model
- The forces in Z-direction showed a very good agreement for laser powers up to 1428W

Summary

Review:

- Presentation of novel laser assisted milling
- Results of laser-assisted milling of Ti-6Al-4V using TiAlN-coated cemented carbide cutting insert in different cutting conditions
- Reduction of force in X-direction up to 25%, Y-direction up to 60% and Z-direction up to 65%
- Low level of tool wear according to the milling time
- 3D-FEM simulation
- Integration of time depending laser power in machining simulation
- Model validation for machining of Ti6Al4V at different cutting conditions (TANH and NTS)

Outlook:

- Expand the milling material spectrum
- Increasing the machining productivity

Acknowledgements

The research work is part of the **TooLAM** project,
funded by the European Union and the

Austrian Research Promotion Agency (FFG)

within the EraSME program.

Thanks for your attention