

# Empirical stochastic modeling of observation noise in global GNSS network processing

**Patrick Dumitraschkewitz, Torsten Mayer-Gürr and Sebastian Strasser**

Institute of Geodesy  
Graz University of Technology

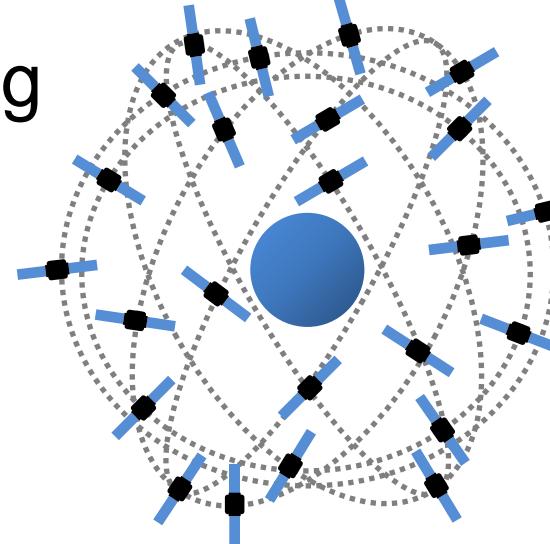
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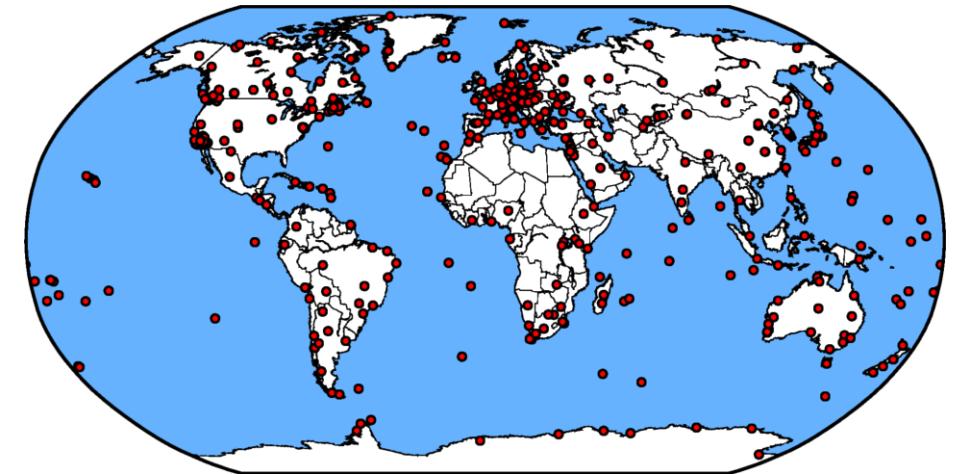


# Global GNSS processing and stochastic modeling

- Combined processing in a least squares adjustment. of
  - GNSS constellation
  - Ground station network
- Currently very simple variance weighting scheme at TUG
  - TUG repro3
    - $\sigma_{phase} = 1mm / \cos(\zeta)$
    - $\sigma_{code} = 220mm / \cos(\zeta)$
  - Neglection of covariances



GNSS constellation



IGS

INTERNATIONAL  
GNSS SERVICE

IGS station network

# Estimating temporal covariance model using post-fit residuals

- Based on the approach of Luo et al. (2012)
  - Adapted for multi-GNSS with multipath-hemispheric-maps (MHM)

- Basic 4 steps:

1. Create accuracy patterns and normalize
  - Accuracy patterns generated by

$$\hat{\sigma}(A, E) = \sqrt{\frac{\sum_i e_i^2(A, E)}{\sum_i r_i(A, E)}}$$

- Removes heteroskedasticity

2. Vondrak filter

- Removes daily trend components

3. MHM stack the residuals and filter

- Eliminates elevation and azimuth dependent systematic station biases

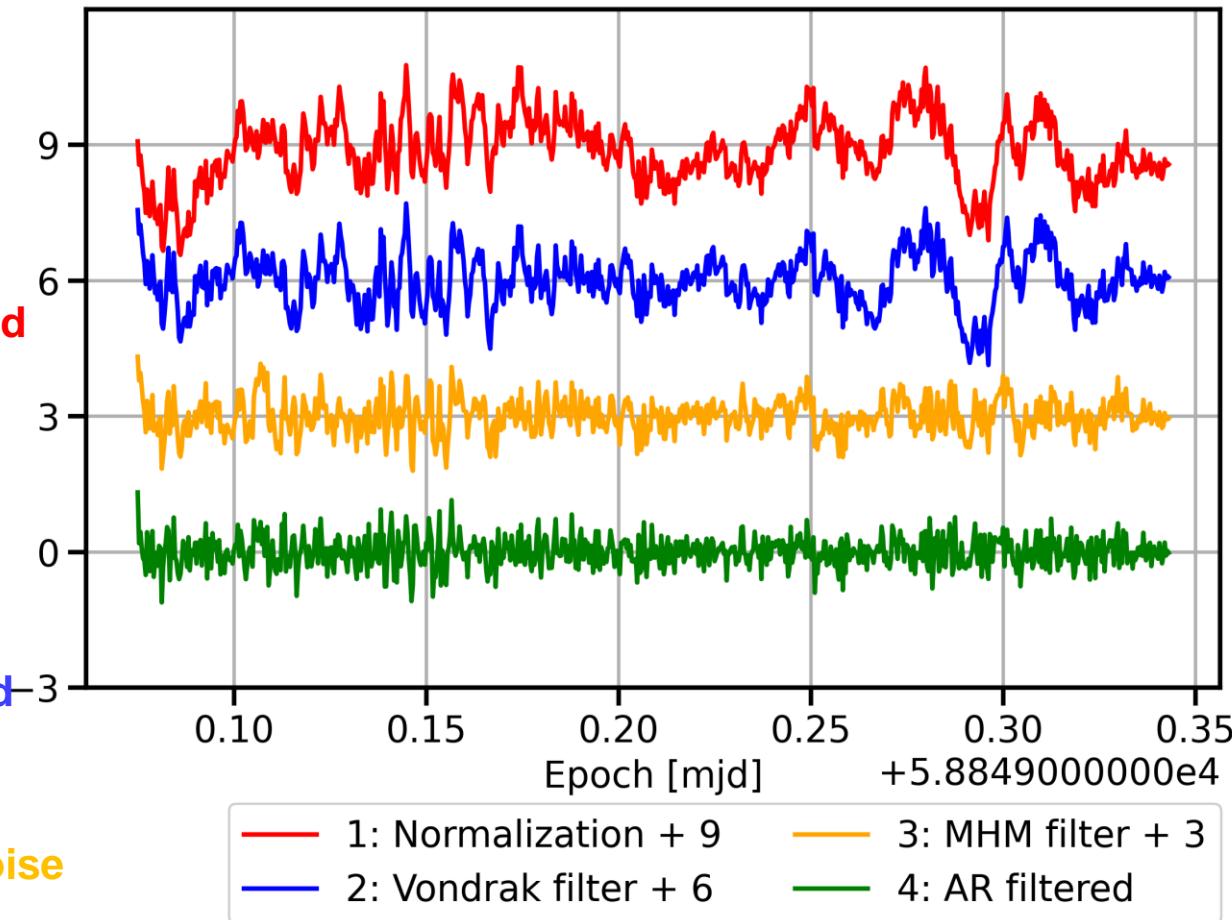
4. Estimate Autoregressive Moving average (ARMA) process into colored noise

→ Normalized residuals

→ Detrended residuals

→ Colored noise residuals

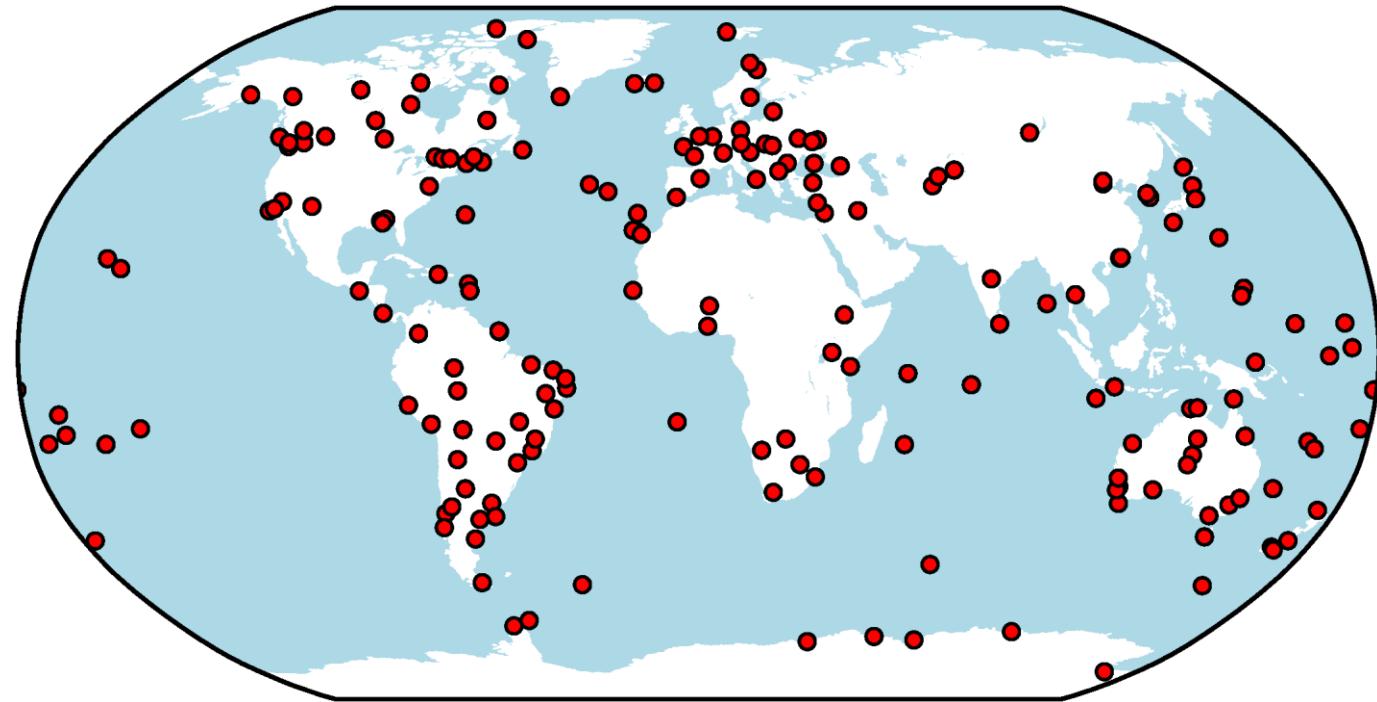
→ Gaussian noise



Residuals after each processing step for station Graz  
From 60 days of residuals

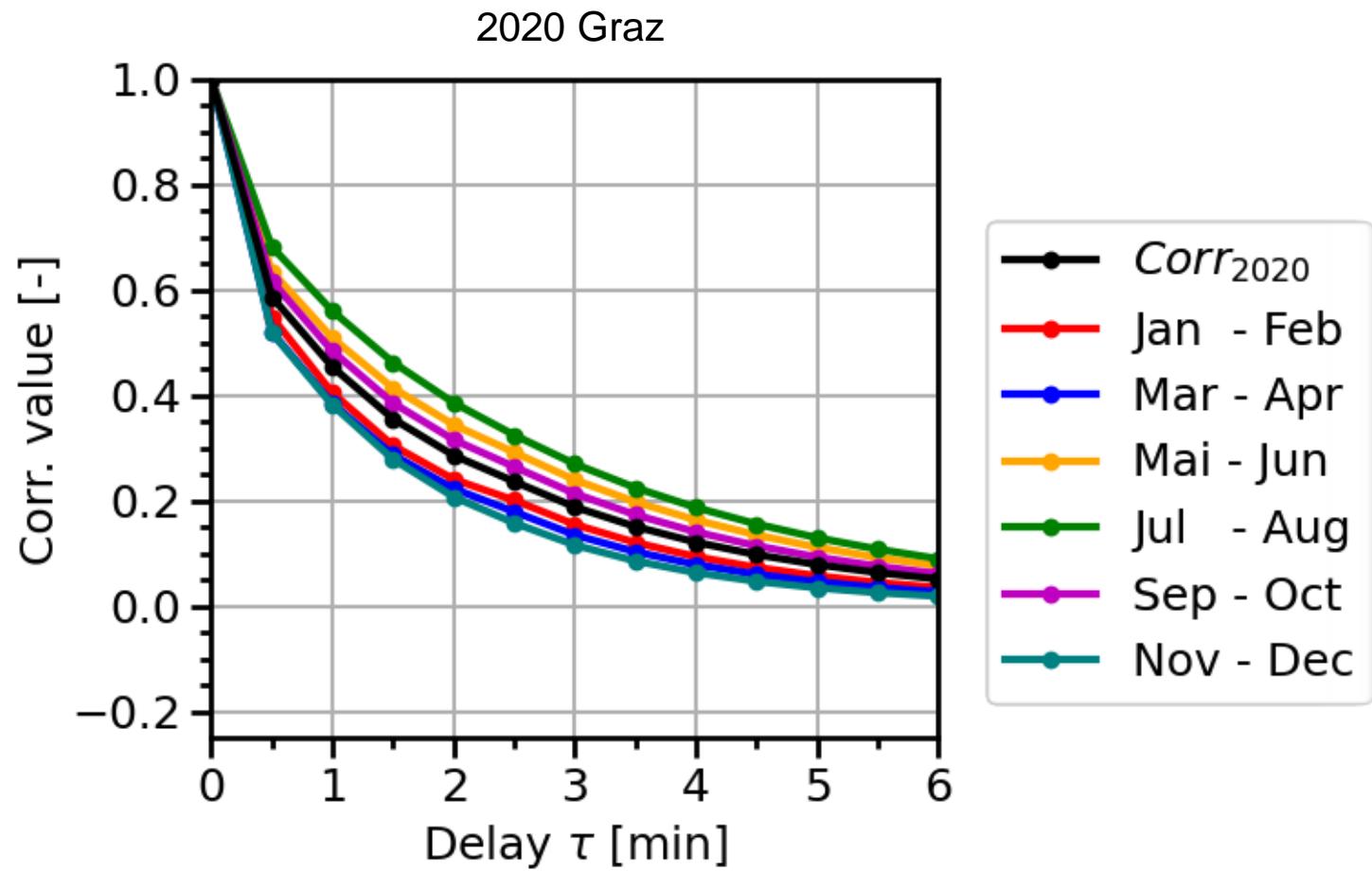
# Analysis setup

- Generated residuals by a global network estimation with ~200 stations
- Same models, procedures as was used in the repro3
- Year 2011, 2016 and 2020 are computed
- Each year is separated into **60 days intervals** for the stochastic model estimation and compared to the **full year** estimation
- Only AR processes are estimated

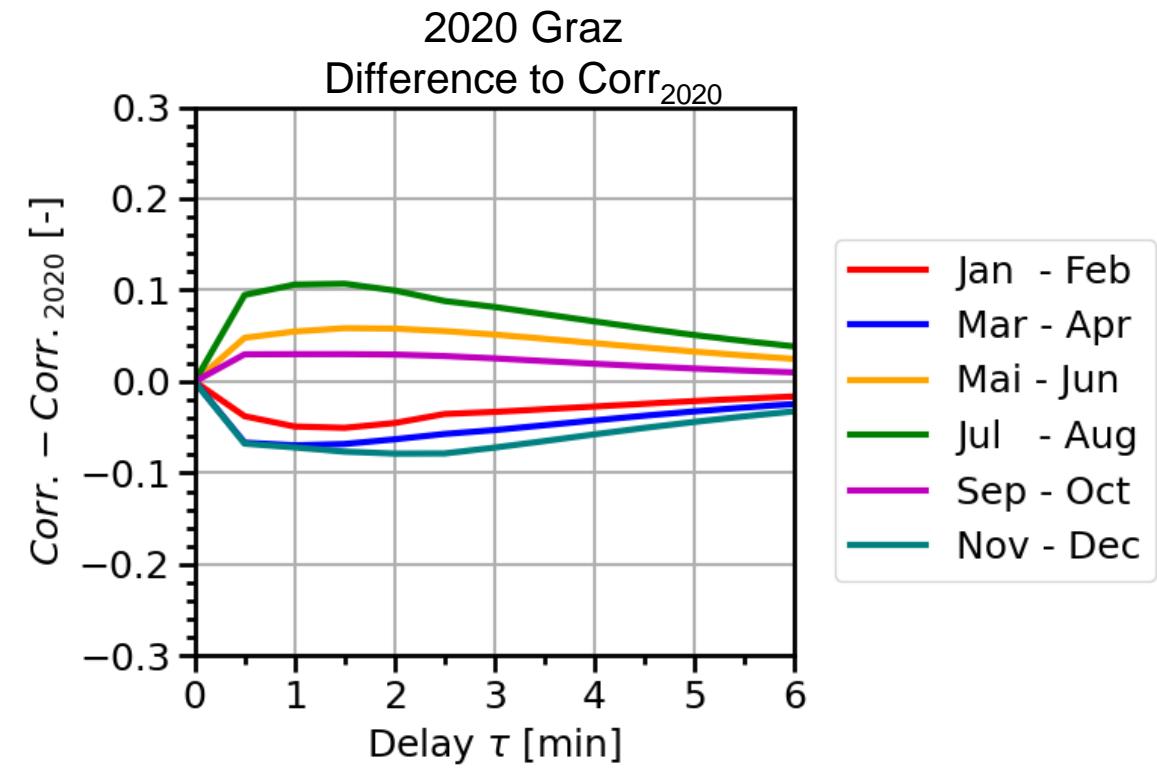
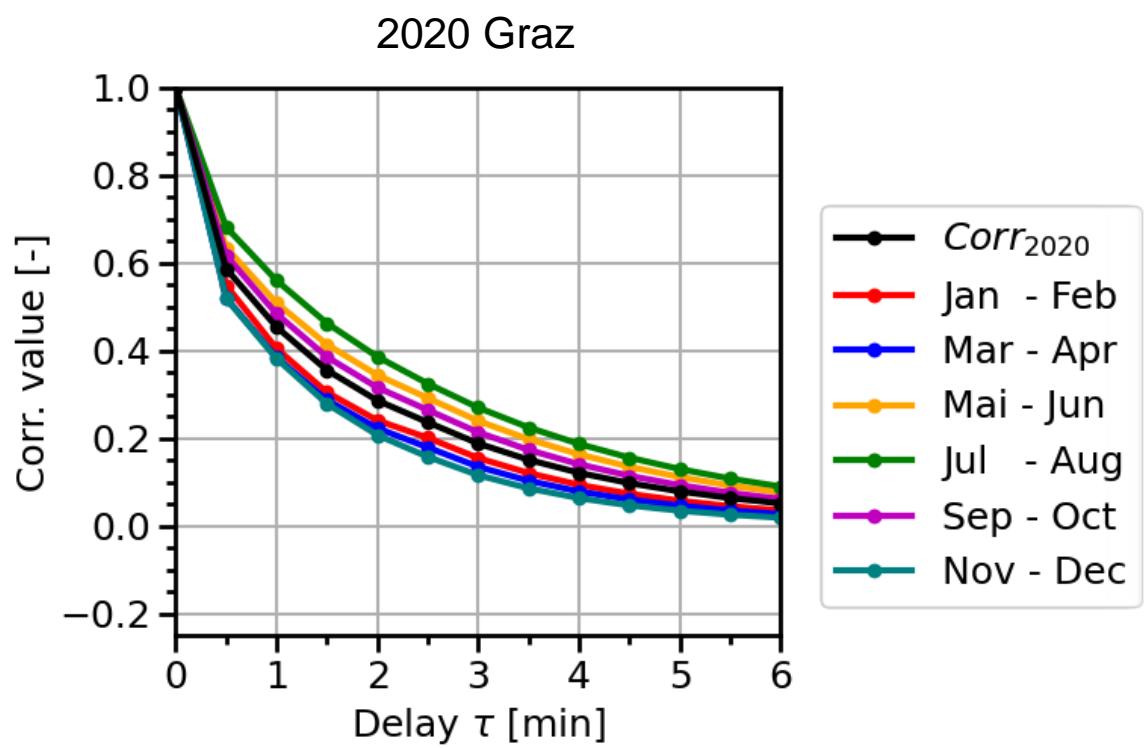


Selected stations for the analysis setup

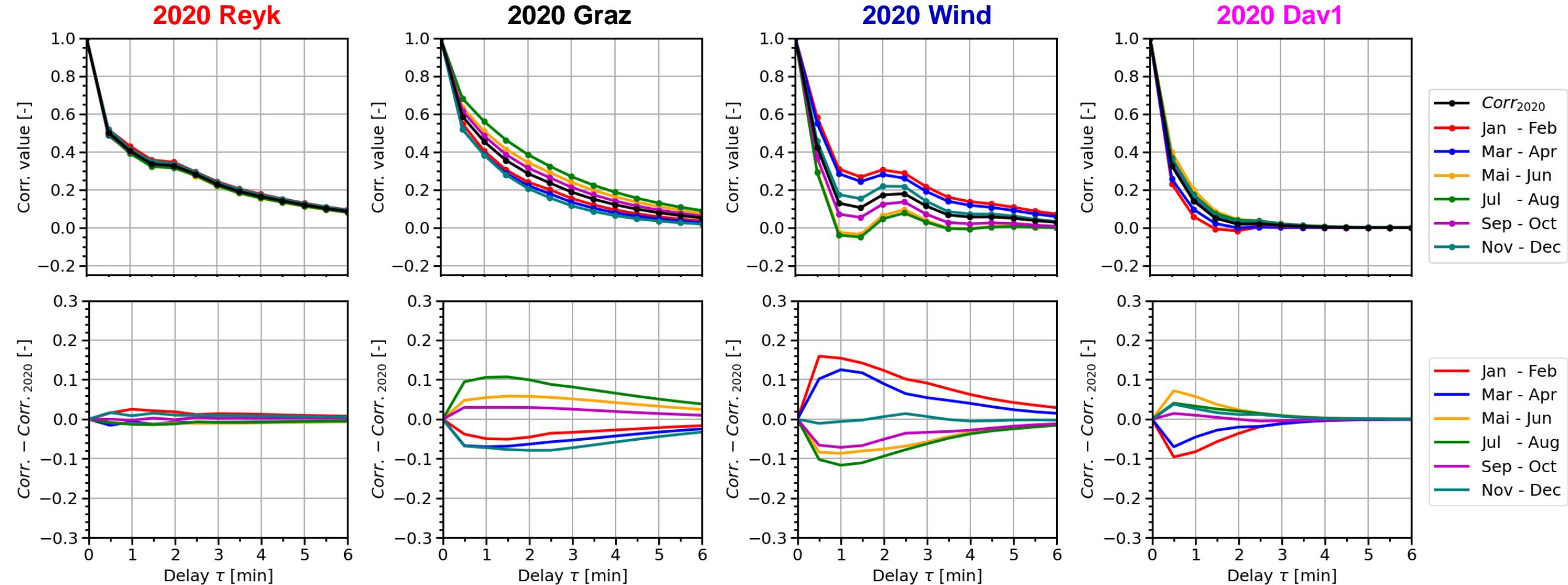
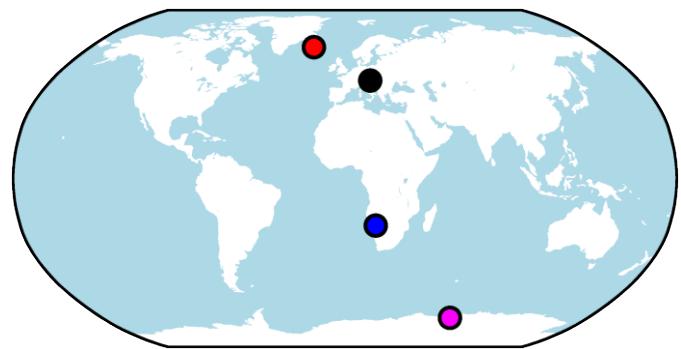
# Estimated L1 temporal correlations Graz



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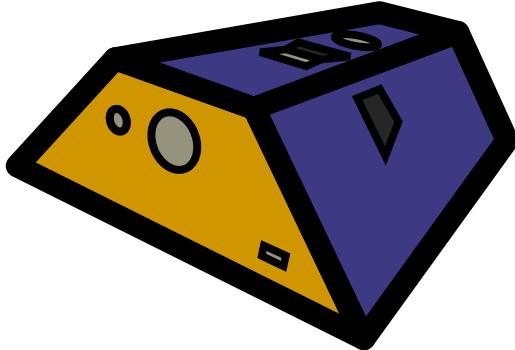


# Estimated L1 Temporal correlations global



# Summary

- Current stochastic model inadequate
- Estimated Co/Variances show annual seasonality

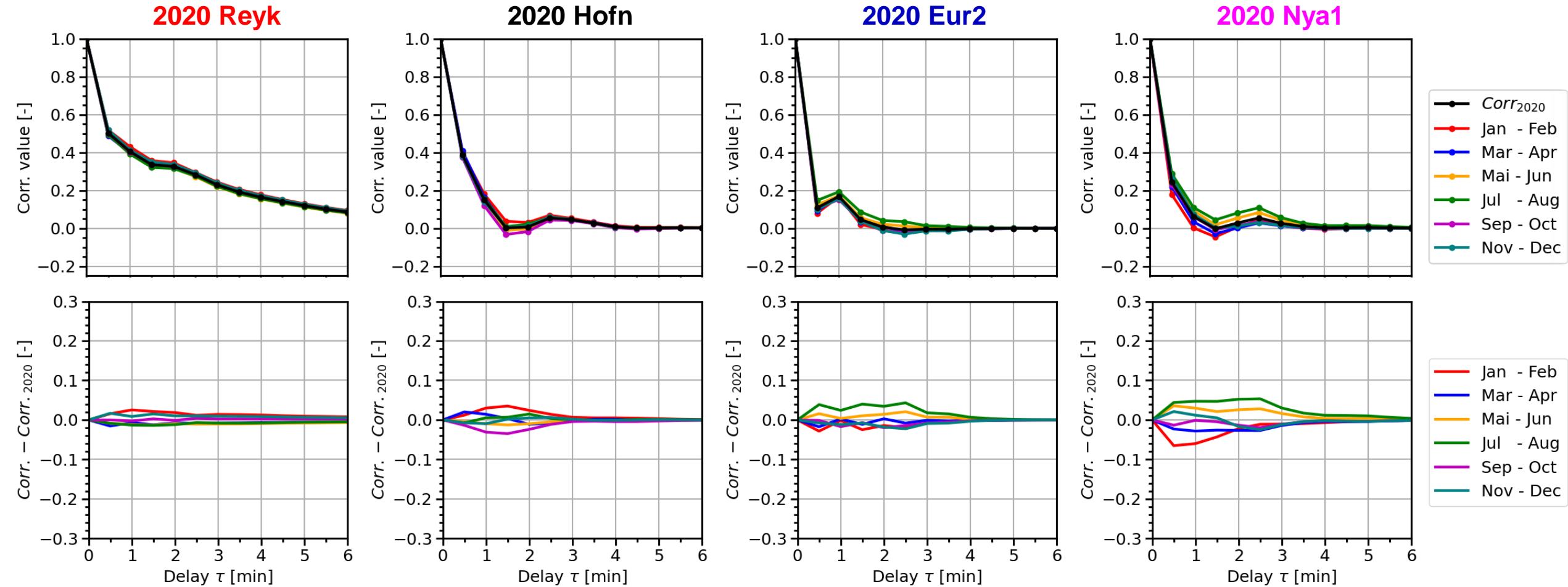
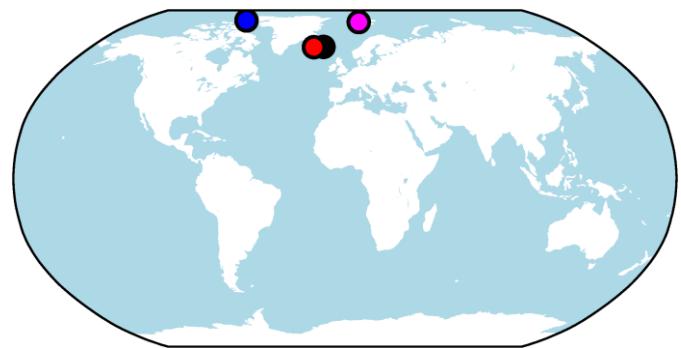


- Far north and far south show little variations
- Stations located in the northern and southern hemisphere have opposite seasonal behavior due to winter/summer environmental changes
  - In winter months the phase observations are more precise and correlate less than in the summer months
- Seasonality observable throughout all frequency (L1, L2, L5 ...) and in all analyzed years (2011, 2016, 2020)

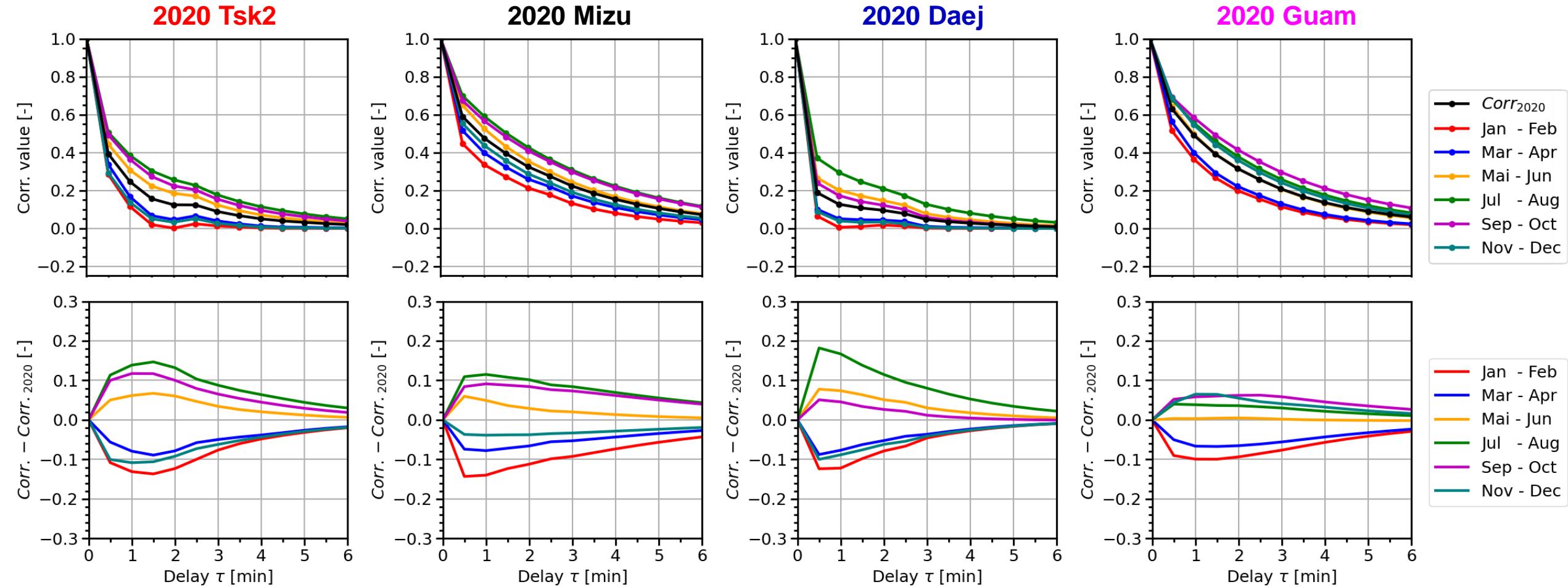
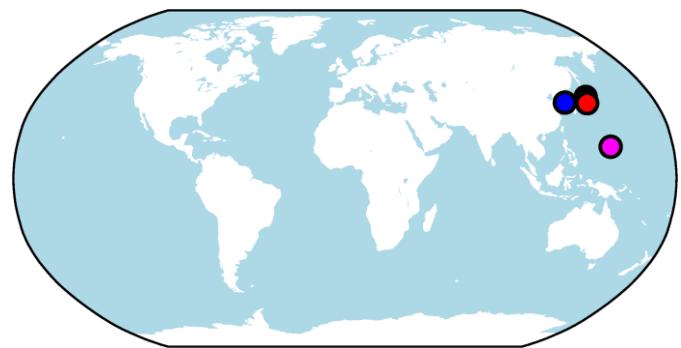
<https://github.com/groops-devs/groops/>

# Estimated L1 covariance models global comparison

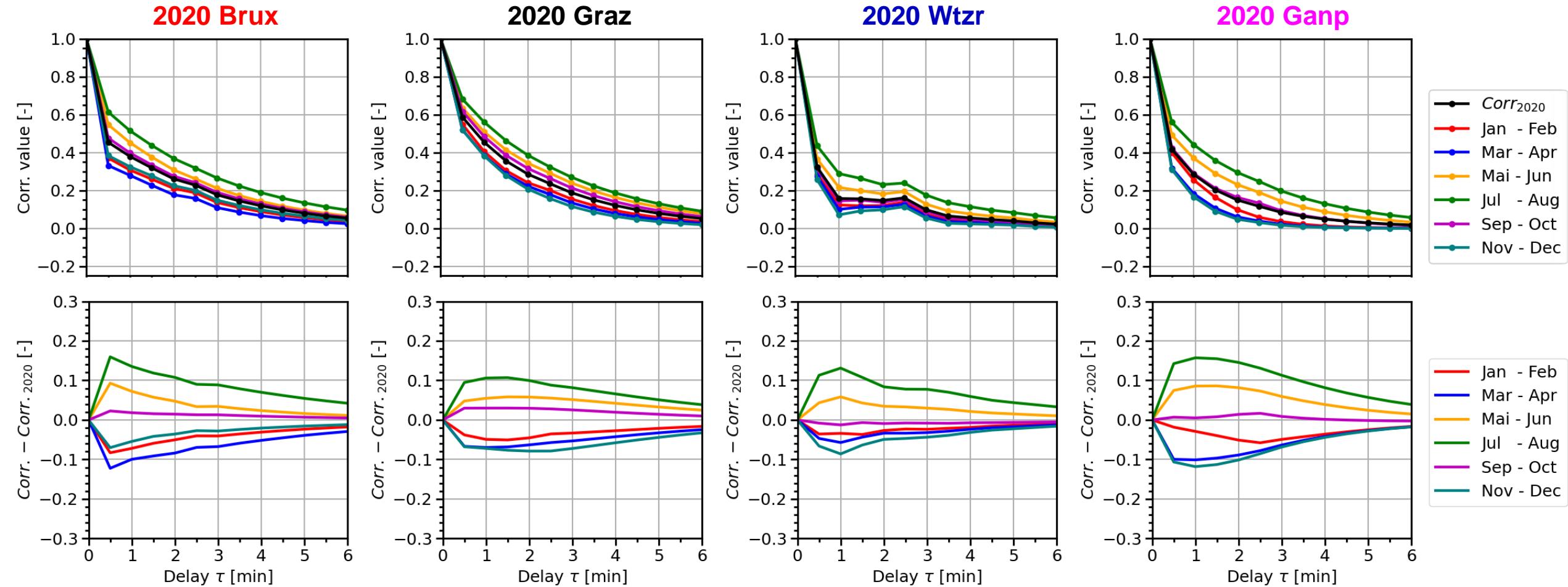
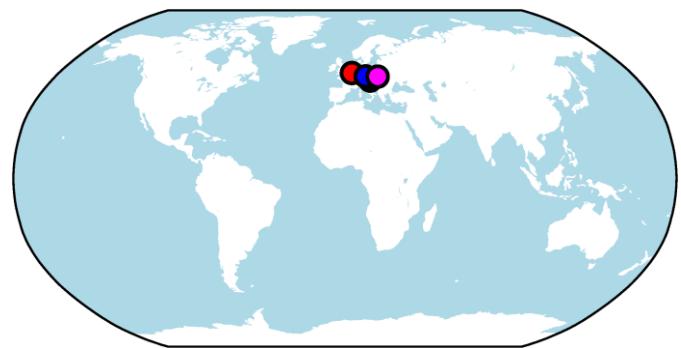
# Estimated L1 Temporal correlations Far North 2020



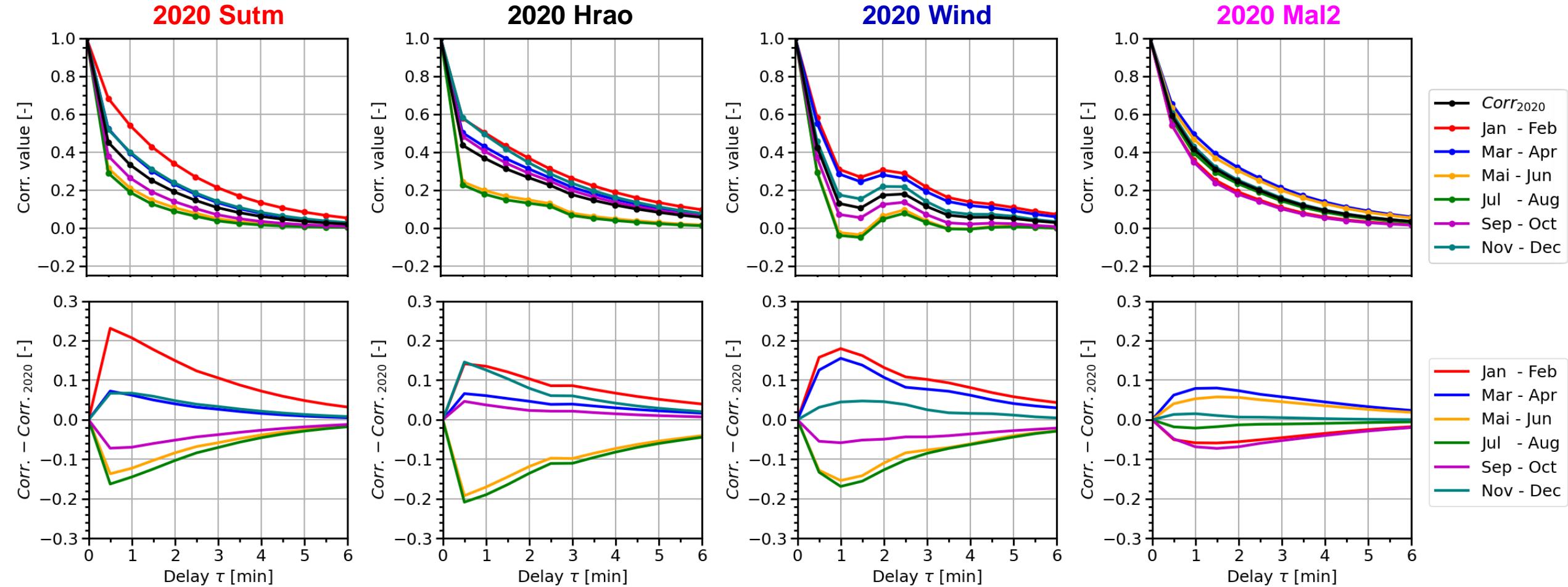
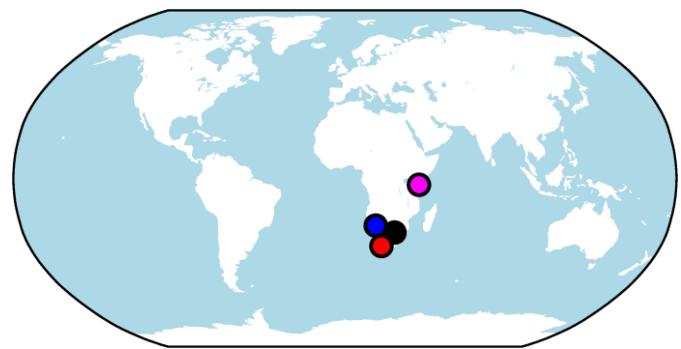
# Estimated L1 Temporal correlations East Asia 2020



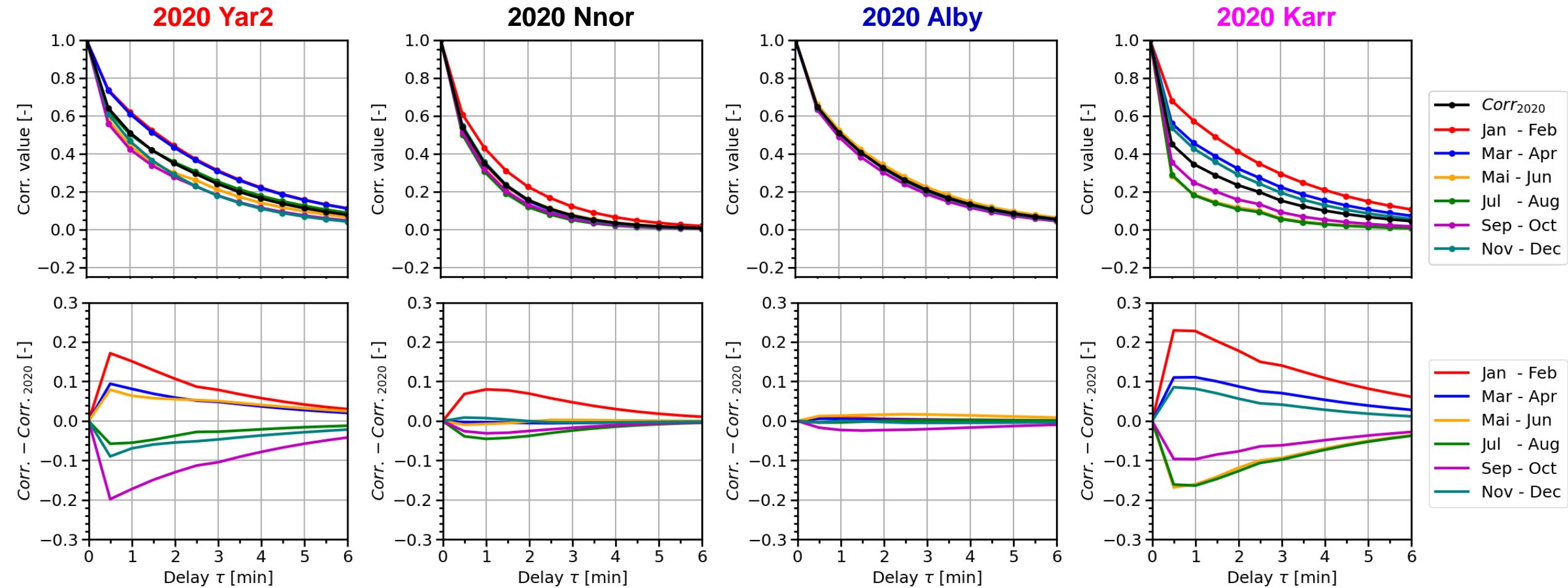
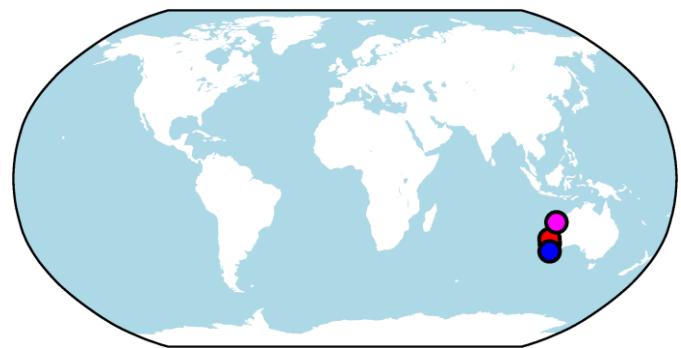
# Estimated L1 Temporal correlations Europe 2020



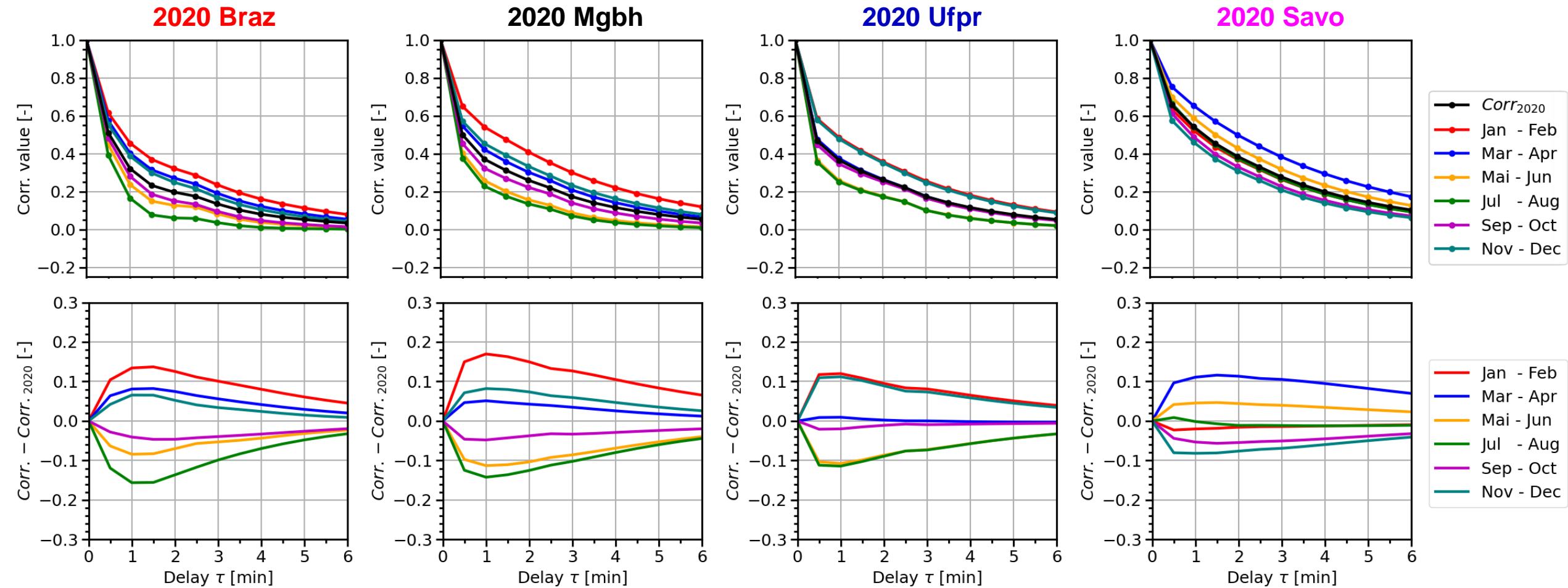
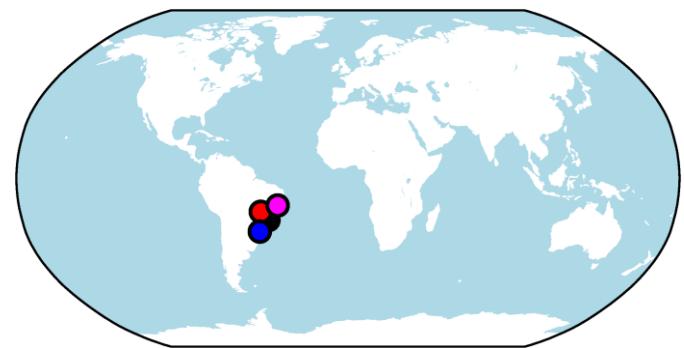
# Estimated L1 Temporal correlations South Africa 2020



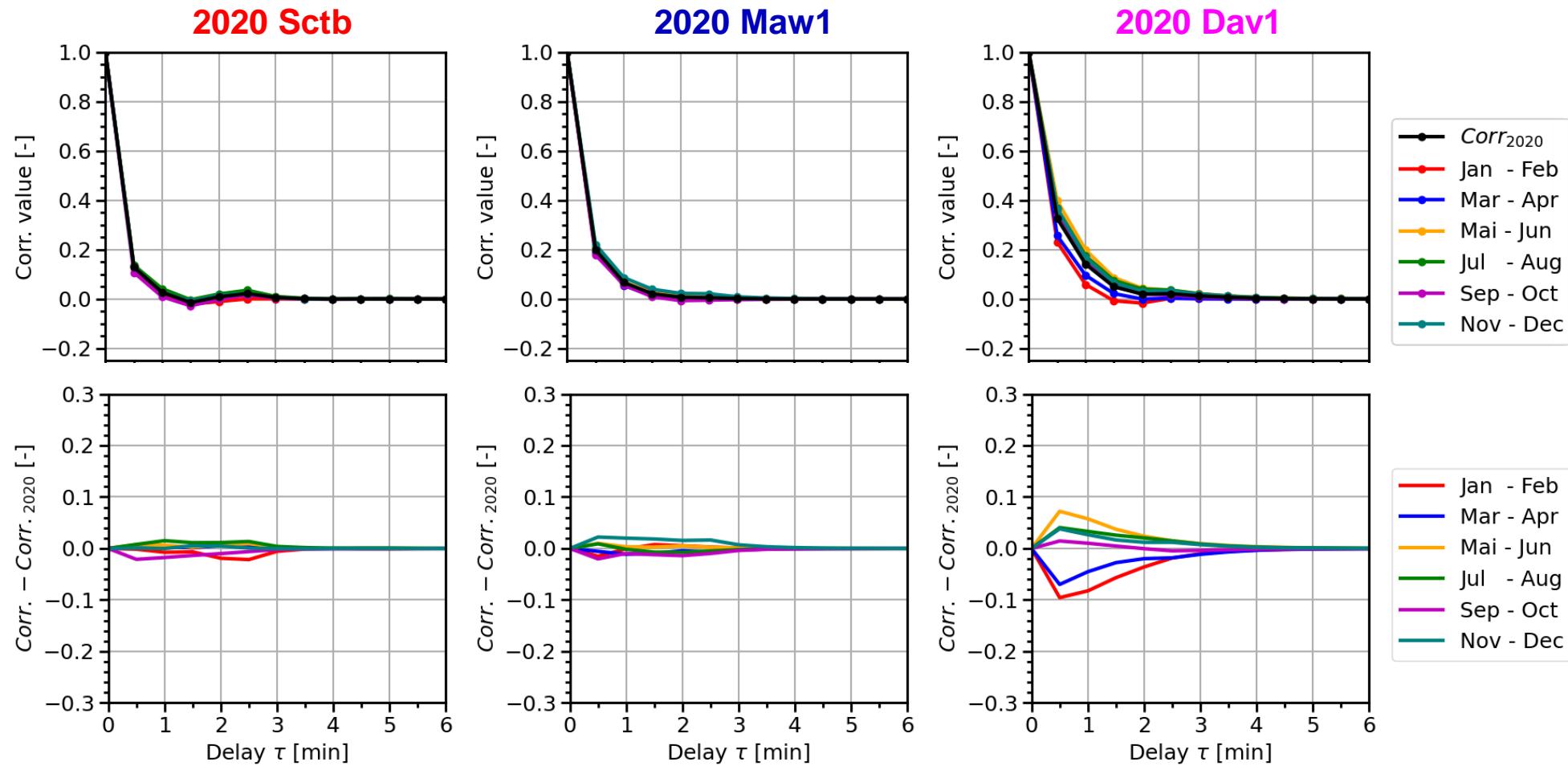
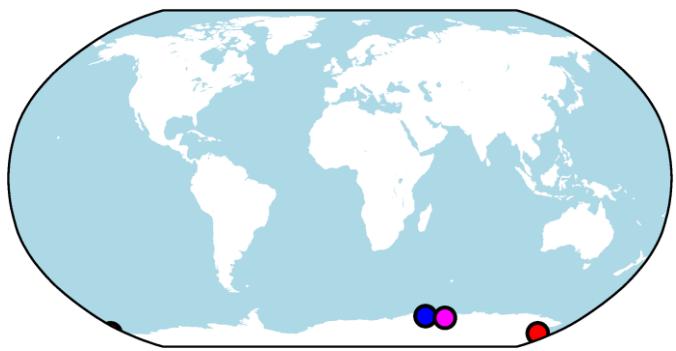
# Estimated L1 Temporal correlations Australia 2020



# Estimated L1 Temporal correlations South America 2020



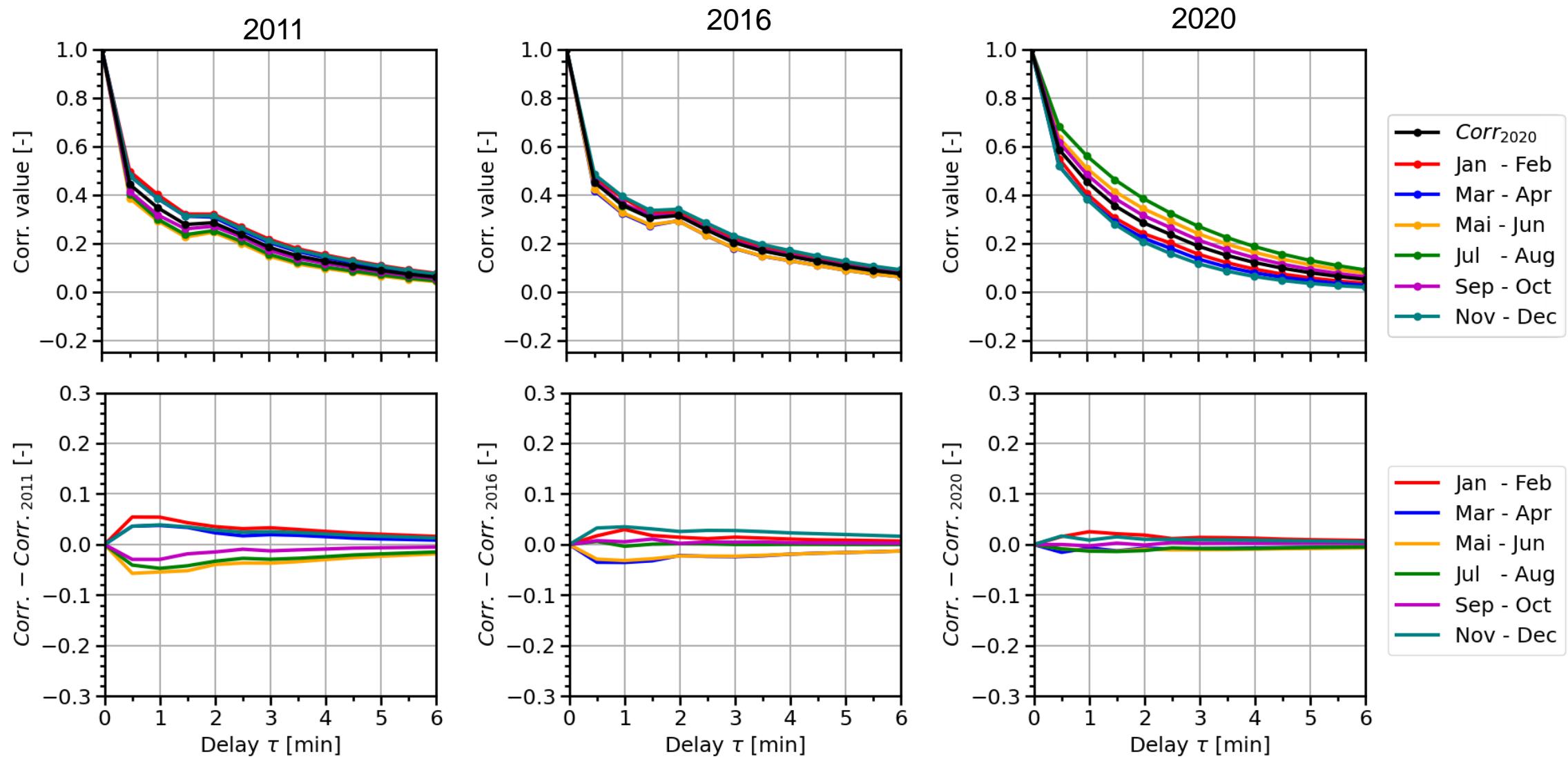
# Estimated L1 Temporal correlations Far South 2020



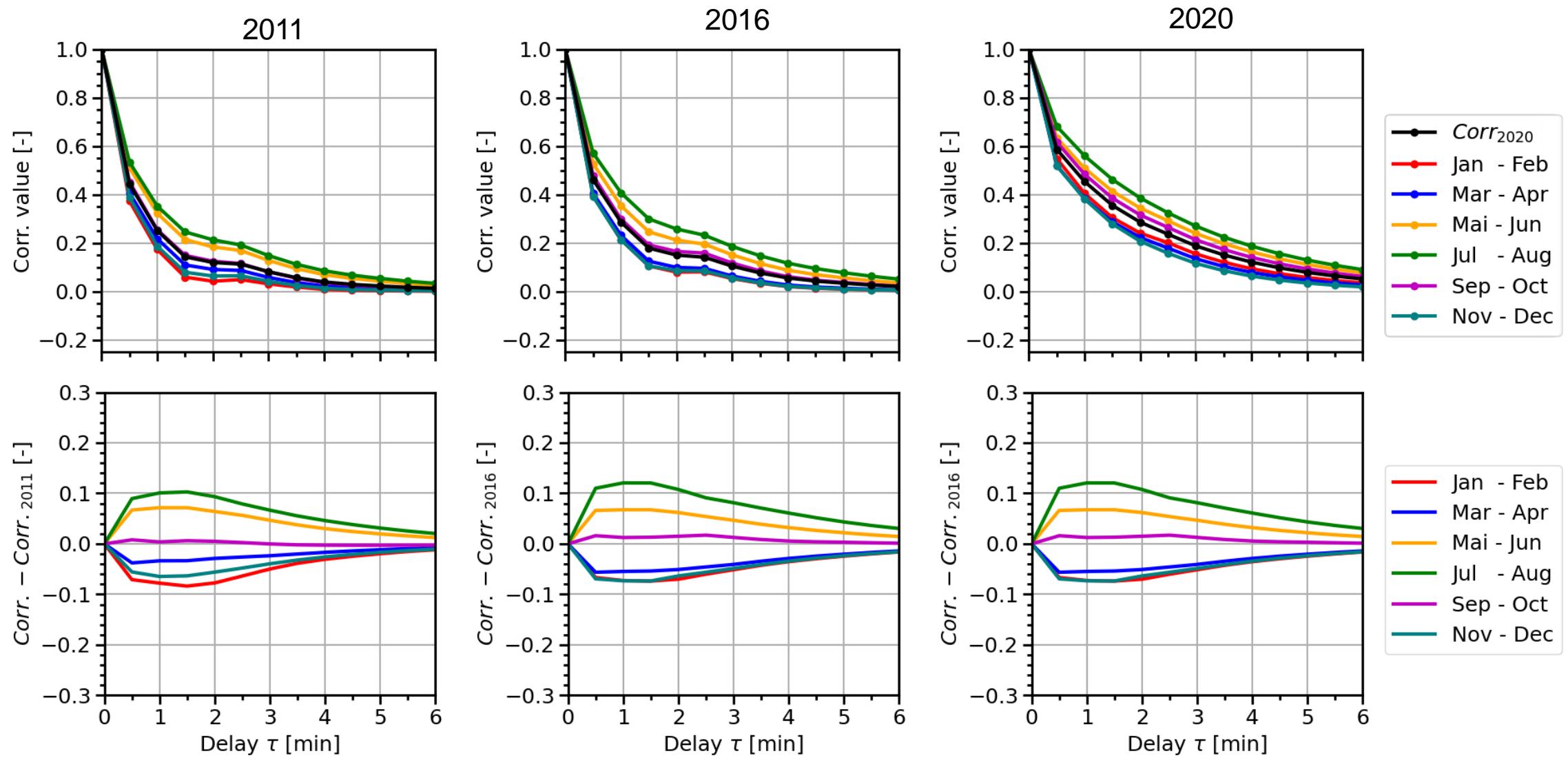
# Estimated L1 temporal correlation differences 2011, 2016, 2020

## Selected stations

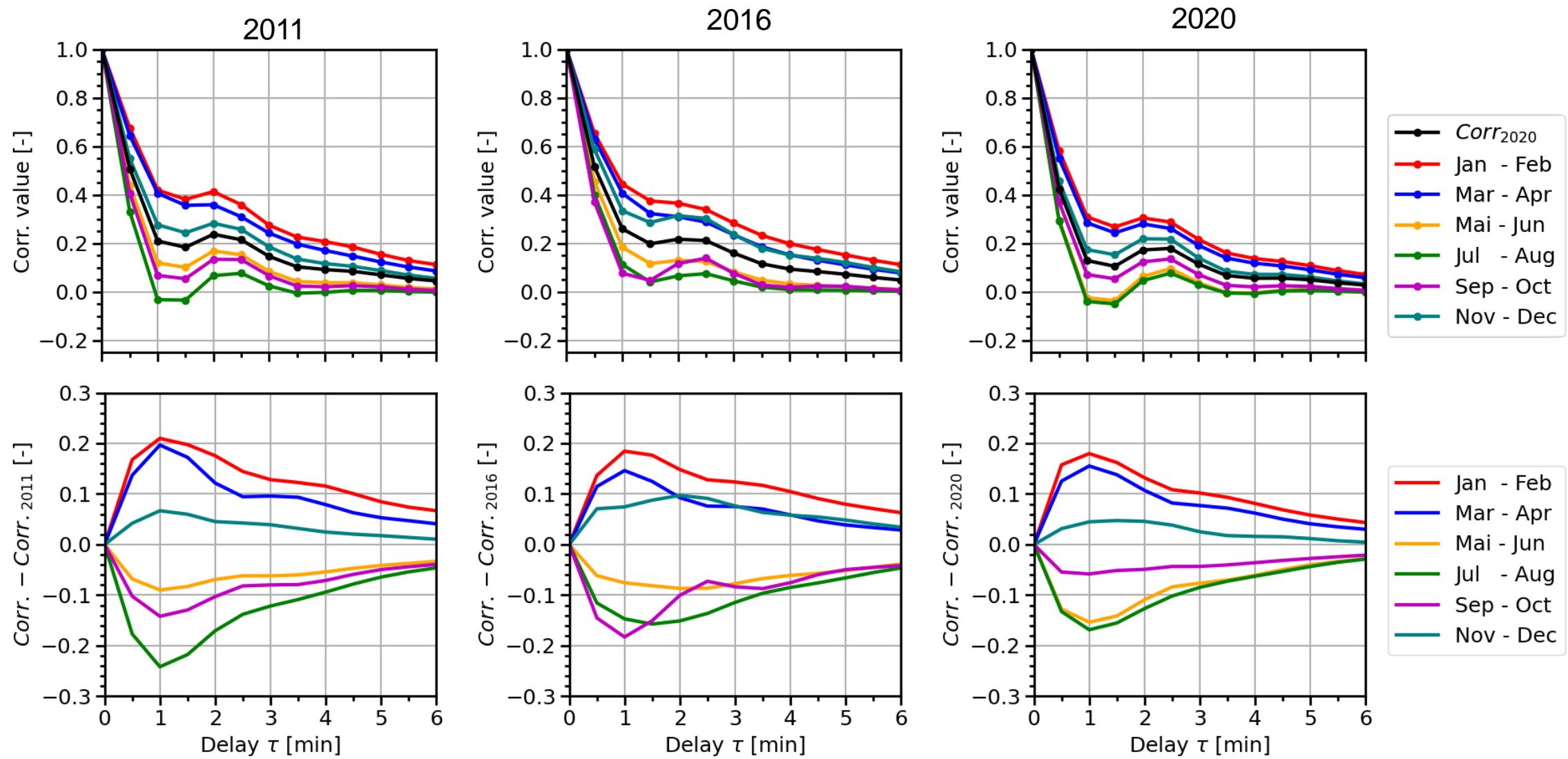
# Estimated L1 temporal correlations Reyk



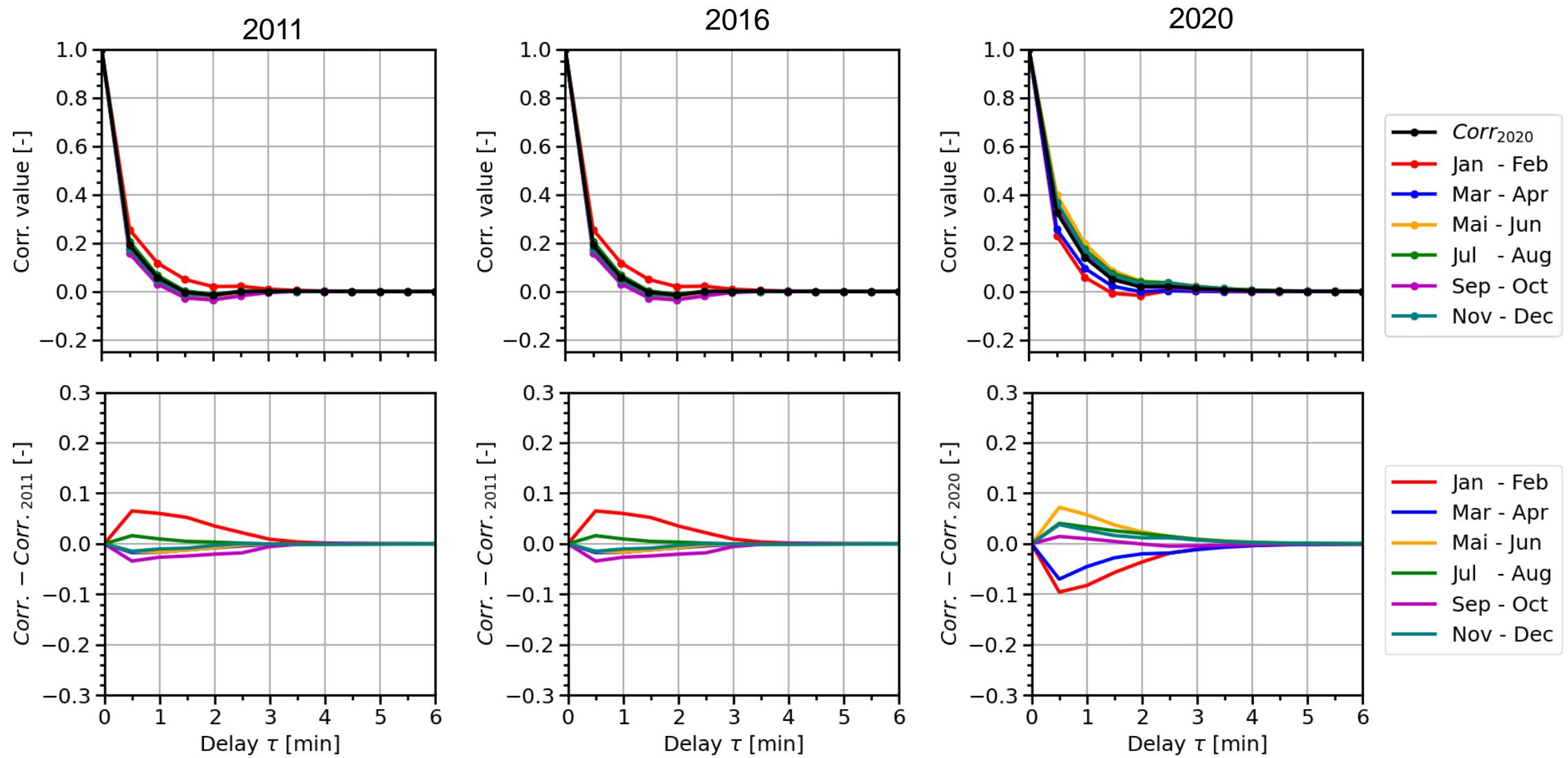
# Estimated L1 temporal correlations Graz



# Estimated L1 temporal correlations Wind

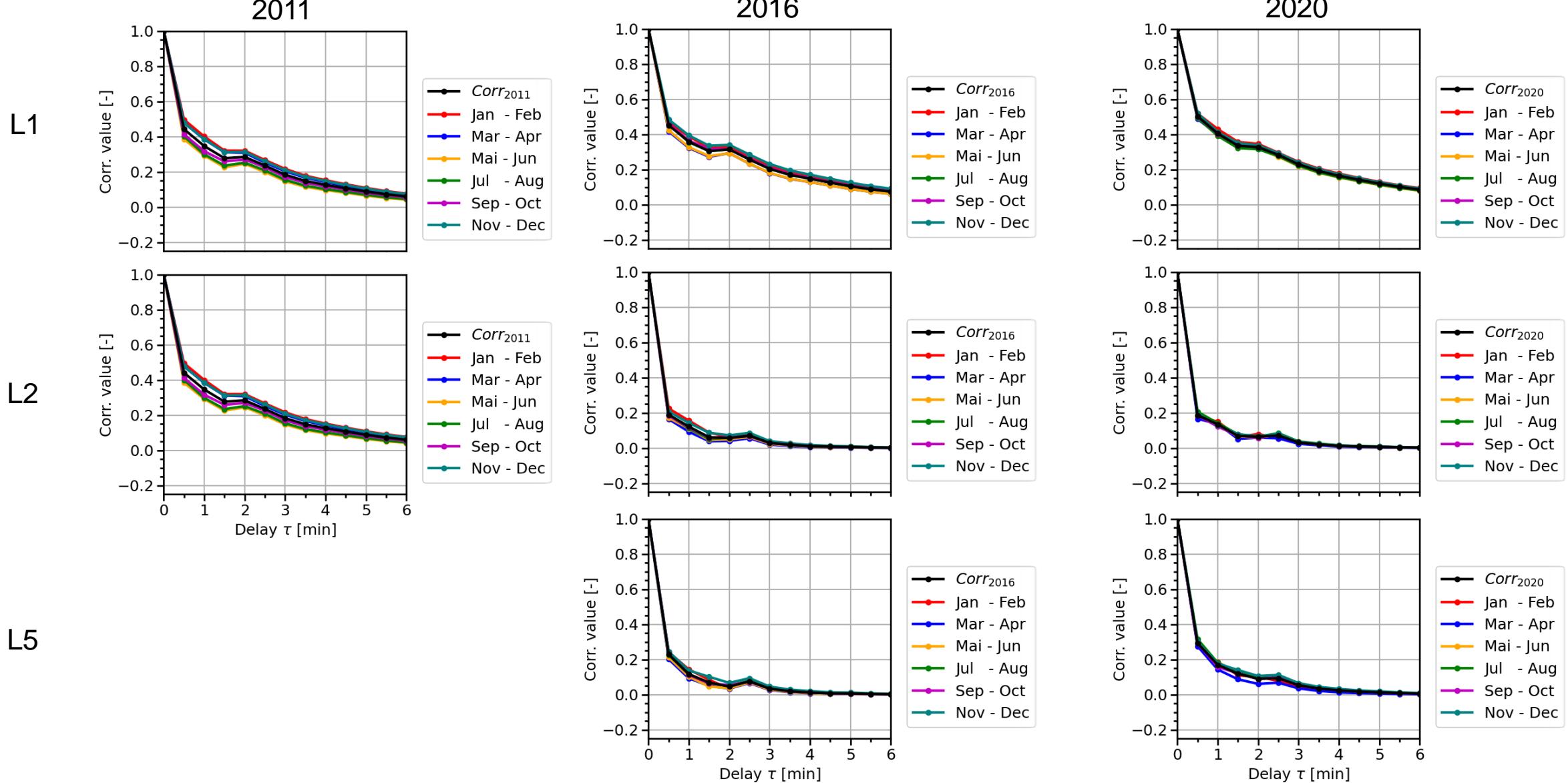


# Estimated L1 temporal correlations Dav1

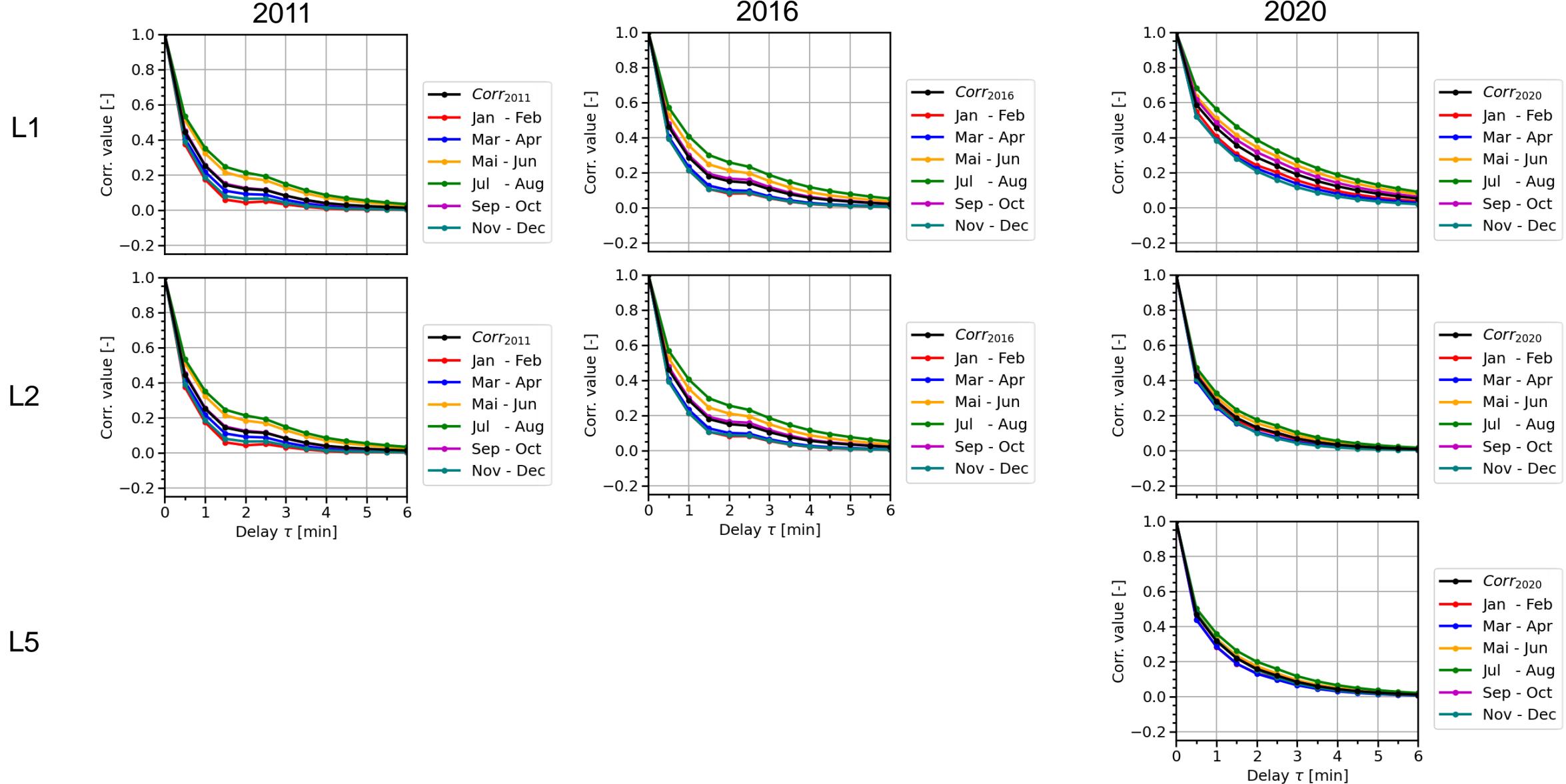


# Comparison of temporal correlations for different centre frequencies 2011, 2016, 2020 Selected stations

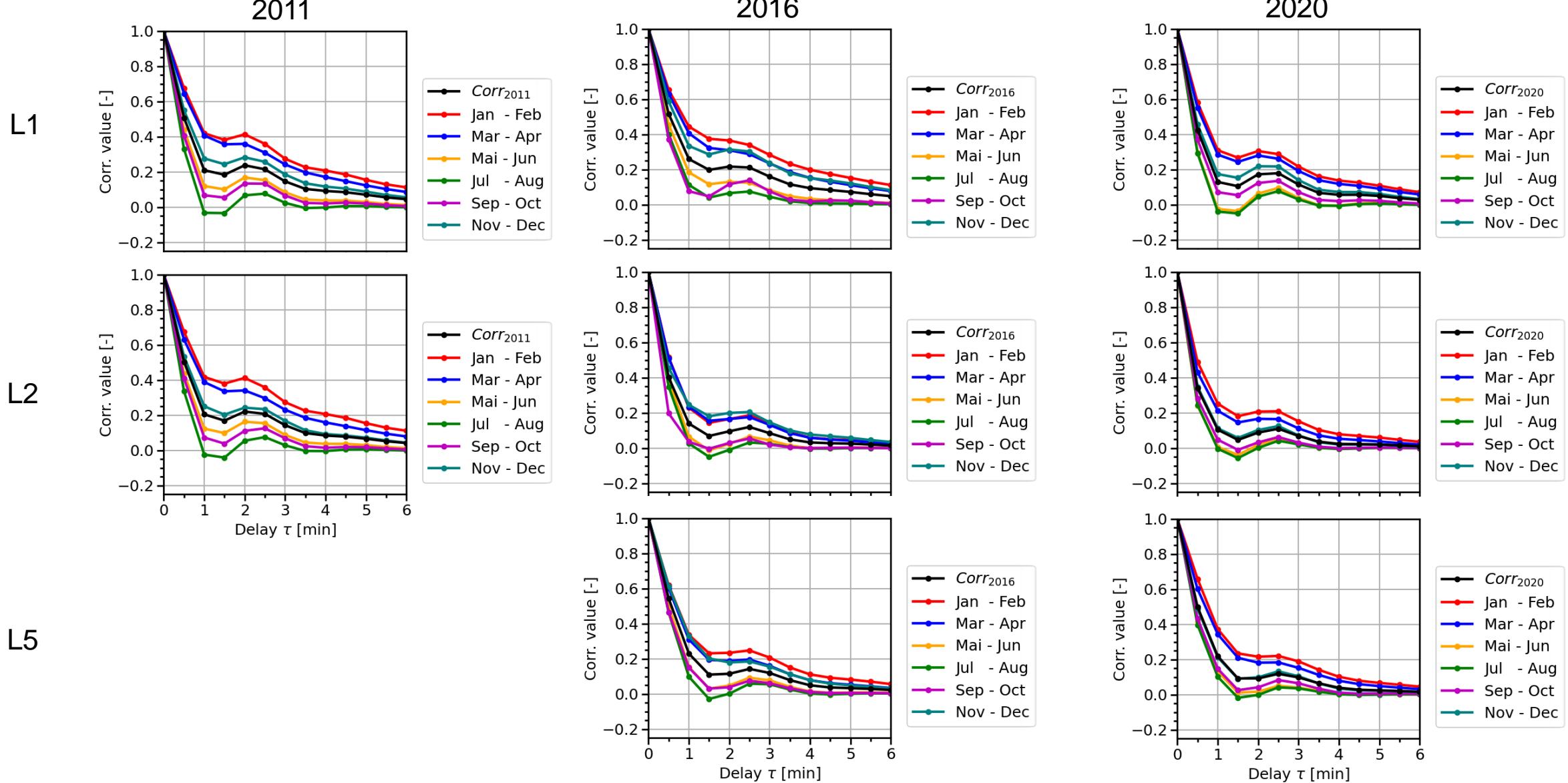
# Comparison of phase observations Reyk



# Comparison of phase observations Graz



# Comparison of phase observations Wind



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