

# Splitting a Vertex

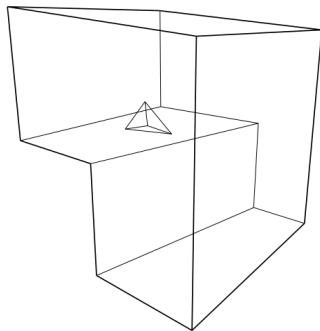
**Franz Aurenhammer, Daniel Lederer,  
Institute of Theoretical Computer Science**

10 - 13 October, 2022

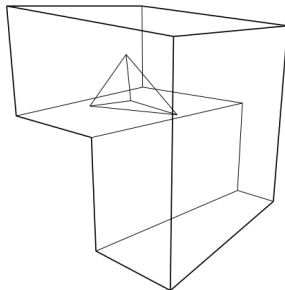
# Introduction

- We are interested in straight skeletons of (non-convex) polytopes in  $\mathbb{R}^3$
- Straight skeleton structure is defined by a mitered boundary offsetting process
- Shrinking a polytope in a self-parallel way until it vanishes
- Each component of the polytope traces out a certain component of the skeleton

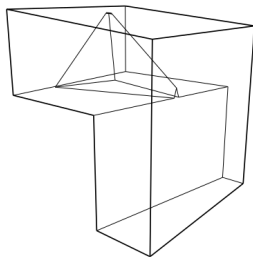
# Example



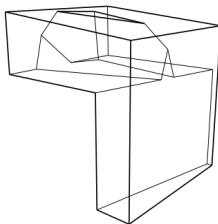
# Example



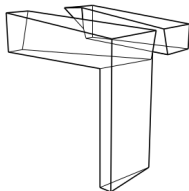
# Example



# Example



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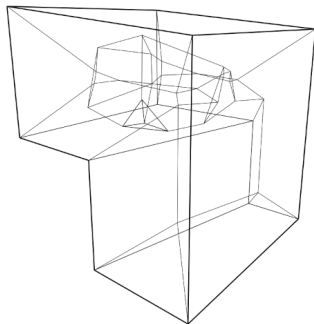


# Example





# Example

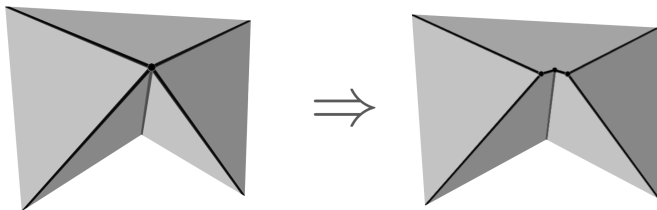


# Offsetting polyhedral surface in $\mathbb{R}^3$

- Polytope vertices of degree  $\geq 4 \Rightarrow$  split into degree-3 vertices

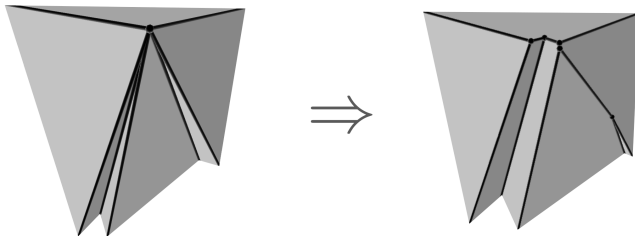
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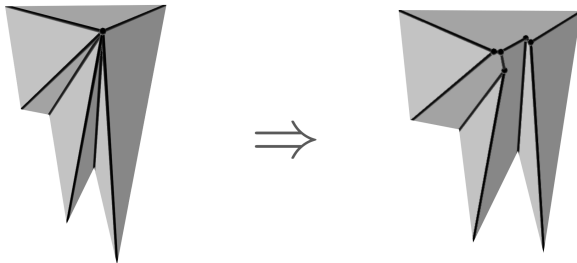
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# Offsetting polyhedral surface in $\mathbb{R}^3$

- Polytope vertices of degree  $\geq 4 \Rightarrow$  split into degree-3 vertices
- Initially, all (high-degree) vertex splittings will happen simultaneously (= initial events)
- Later, during shrinking process  $\Rightarrow$  only low-degree vertices, in generic case (= non-initial events)
  - Handled in the same way as initial events

# Offsetting polyhedral surface in $\mathbb{R}^3$

- Consider each vertex separately
- Vertex  $v$  of degree  $k \Rightarrow k$  incident facets
- The  $k$  planes supporting these facets are offset by 1 unit towards the interior of the polytope
- Locally build a new *valid* surface from these offset planes

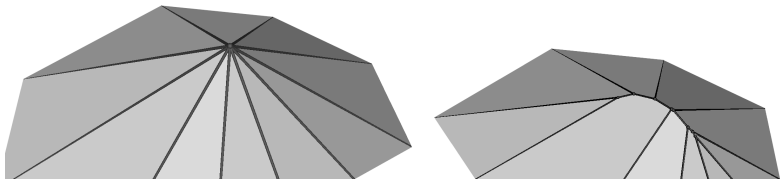
# Vertex types

- In general,  $v$  can have a complex neighbourhood



# Vertex types

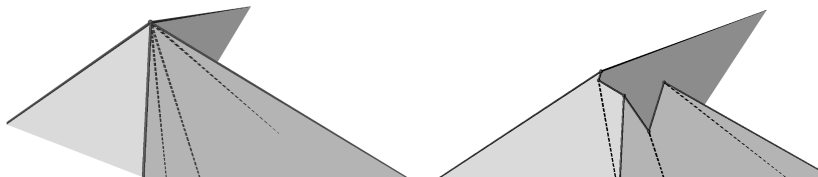
- Convex case (easiest case): all incident edges of  $v$  are convex



A degree-10 convex vertex and its offset surface

# Vertex types

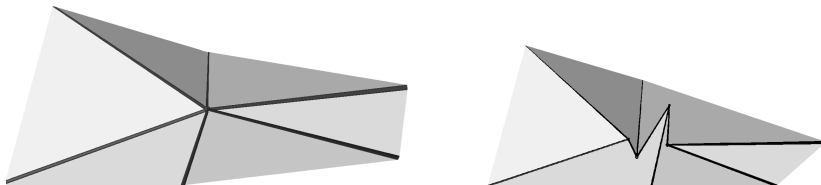
- Pointed case:  $v$  can be cut off from the polytope by a single plane



A degree-7 pointed vertex and its offset surface

# Vertex types

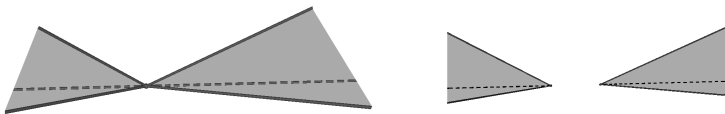
- Saddle point case: incident edges of  $v$  span 3-space



A degree-6 saddle vertex and its offset surface

# Vertex types

- Touching case:  $\epsilon$ -sphere centered at  $v$  intersects polytope boundary in disconnected set



A degree-6 touching vertex and its offset surface

# Vertex types

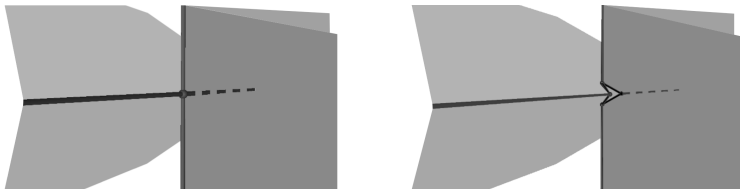
- Touching case:  $\epsilon$ -sphere centered at  $v$  intersects polytope boundary in disconnected set



A degree-4 touching vertex and its offset surface

# Vertex types

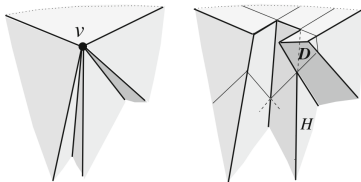
- Touching case:  $\epsilon$ -sphere centered at  $v$  intersects polytope boundary in disconnected set



A degree-4 touching vertex and its offset surface

# Valid offset surface

- Computing an offset surface is highly non-trivial
- What is a *valid* offset surface?
  - (1) Its facets must come from the  $k$  offset planes
  - (2) It must *fit* to the shrunk polytope
  - (3) Each of its facets must be fully visible from  $v$



Conditions (1) and (2) are obviously necessary. Condition (3) is needed, too, because certain facets would move to the exterior of the polytope, otherwise.

# Valid offset surface

- Not unique in general
- There are exponential many valid offset surfaces, in  $k$
- All valid offset surfaces are contained in the so-called offset arrangement  $\mathcal{A}(v)$

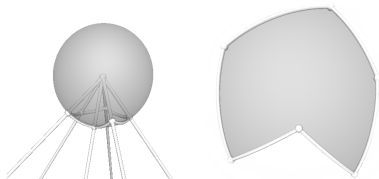


## Recap: Offset arrangement $\mathcal{A}(v)$

- Dissection of the space by the  $k$  offset planes for  $v$
- Representation of intersections: Vertices, edges, facets, cells (*see slides from last time for more details*)
- Combinatorial structure of  $\mathcal{A}(v)$  is independent from the offset distance
- $\mathcal{A}(v)$  can be used to prove that a valid offset surface always has to exist:

# Existence proof for a valid offset surface

- Arrangement cell is *relevant*  $\Leftrightarrow$  its radial projection from  $v$  fully lies within the *spherical polygon*  $S$  for  $v$
- $S$  is created by intersecting a (small) sphere, centered at  $v$ , with the polytope
- *See slides from last time for more details*



# Existence proof for a valid offset surface

- Take all relevant unbounded cells of  $\mathcal{A}(v)$
- If boundary of their union contains **unbounded** facets only  $\Rightarrow$  valid offset surface (everything visible from  $v$ )
- Otherwise, surface contains bounded facets (**orphan facets**)
  - Add bounded cells that fit to such orphans until all facets become unbounded  $\Rightarrow$  valid offset surface
  - This is always possible by the structure of  $\mathcal{A}(v)$

# Algorithmic viewpoint

- Proof above gives an algorithm for constructing valid offset surfaces:
  - For a vertex  $v$  with degree  $> 3$ , compute all cells of  $\mathcal{A}(v)$
  - Merge all relevant unbounded cells
  - If resulting surface contains orphan facets, then add (relevant) bounded cells until no orphan facets remain

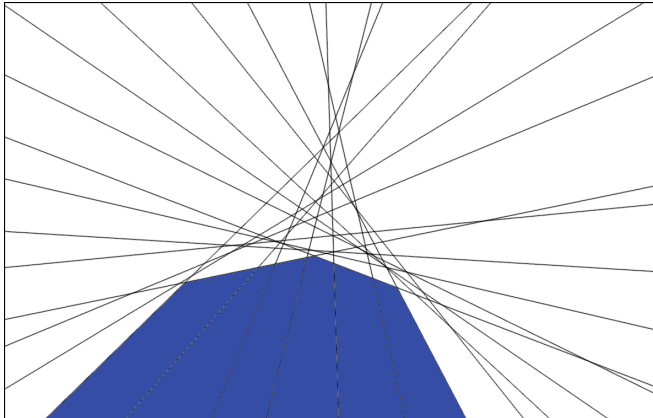
# Software demonstration

- In the following examples, the cell adding process stops when the first valid offset surface is found:
  - `saddle_3.obj`
  - `kiev_17.obj`
  - `saddle_20.obj`
  - `convex_spinning_tops.obj`
  - `convex_spinning_tops_inverse.obj`

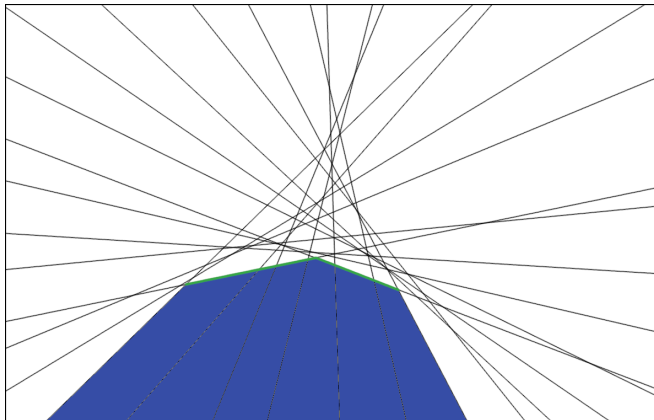
## Problem: Cell Adding Process

- **Order** of adding cells matters
- If cell order is chosen unluckily
  - We cannot get rid of orphan facets
  - Non-valid offset surface
- The higher the degree of  $v$ , the more cell candidates there can be
  - Higher chance for wrong cell adding order

# Problem example in $\mathbb{R}^2$

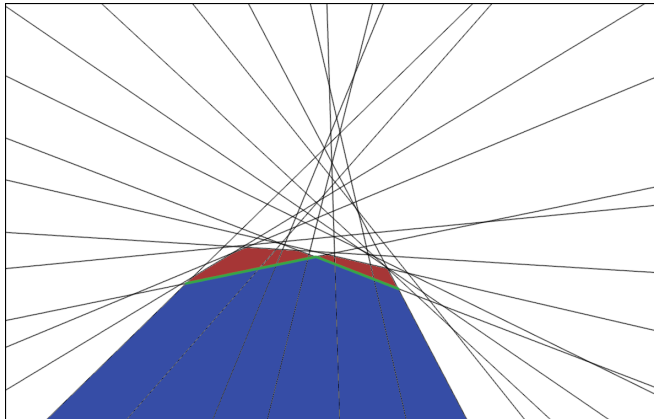


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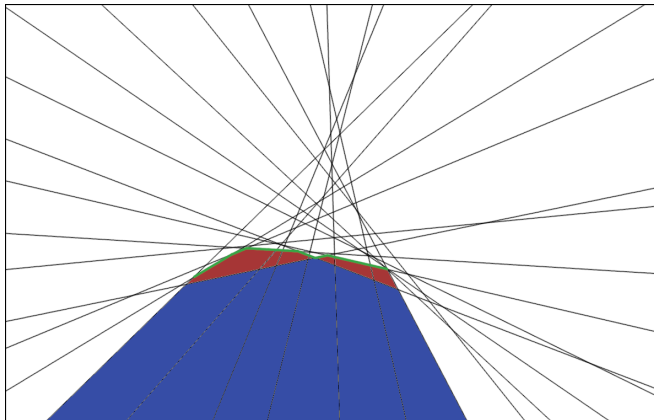




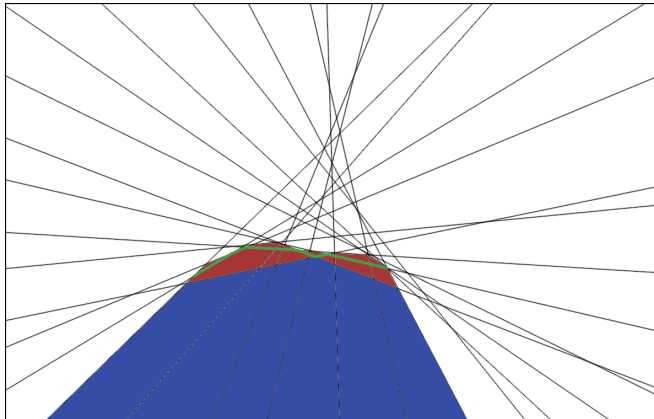
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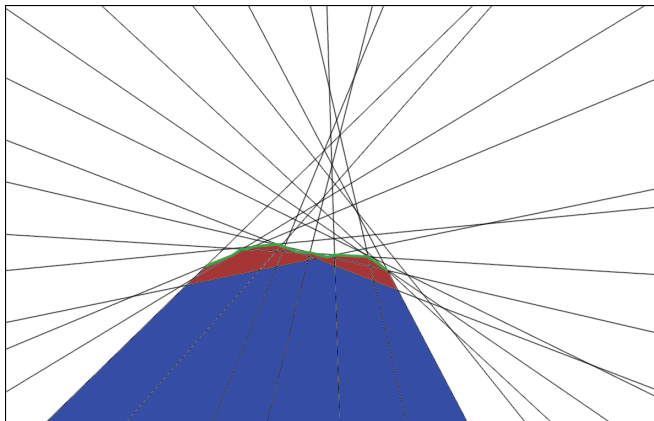
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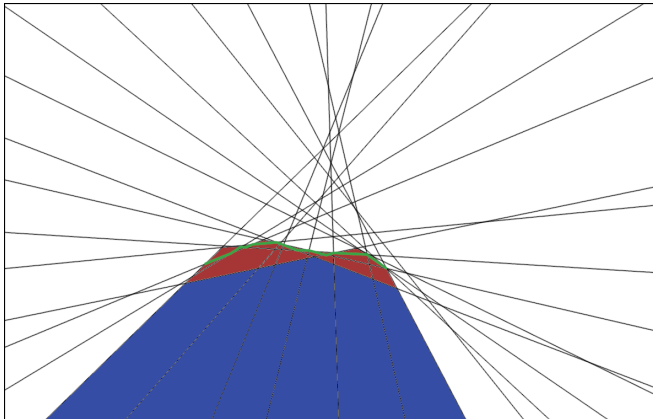
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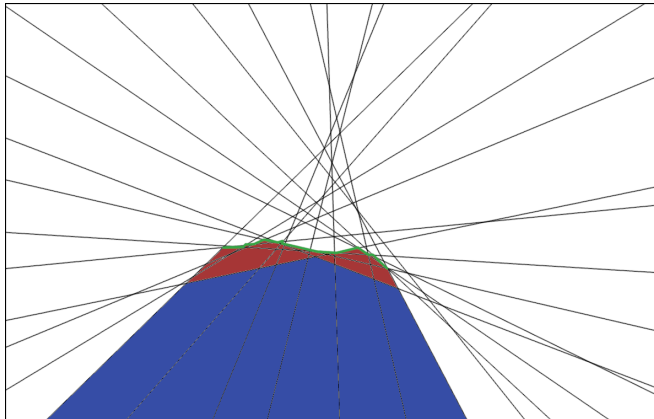
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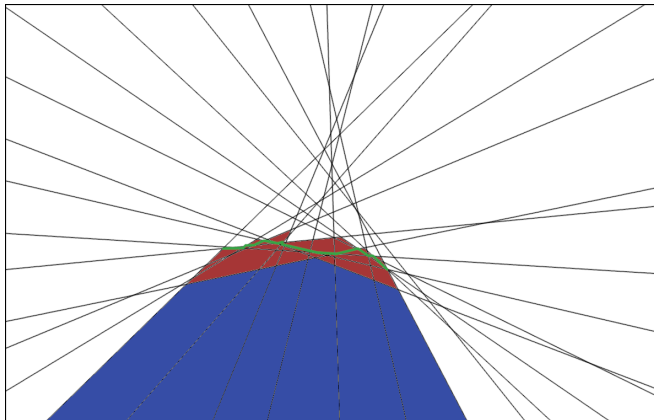
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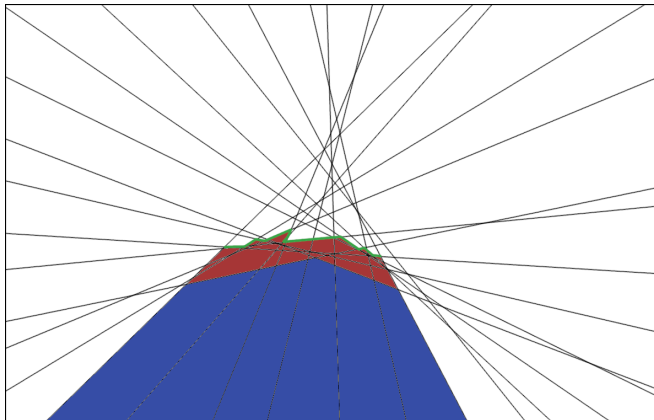
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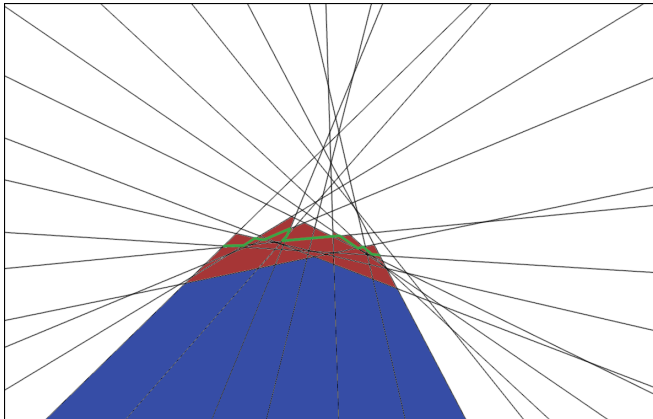


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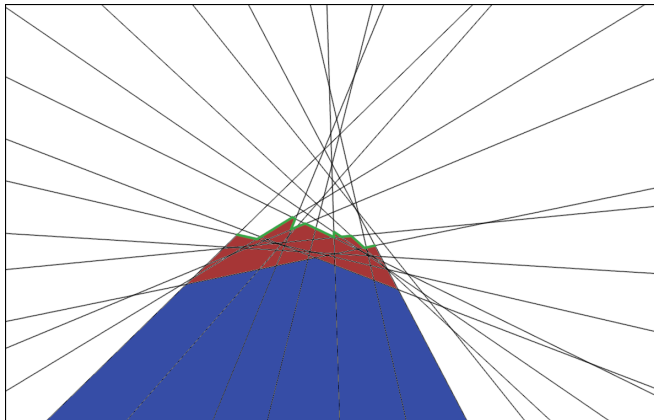




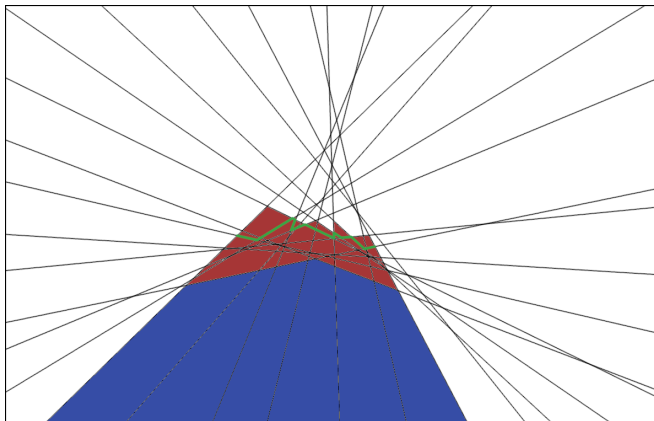
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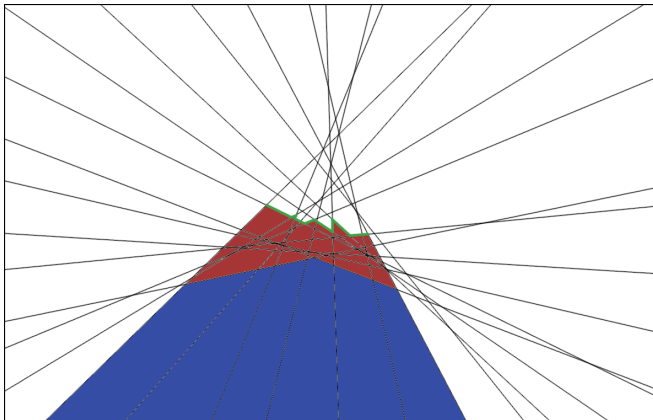
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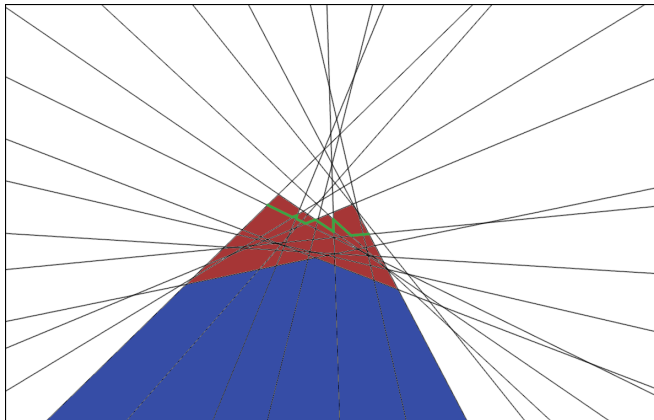
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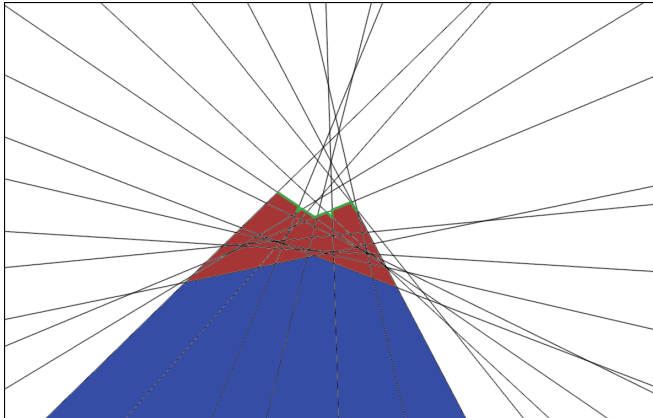
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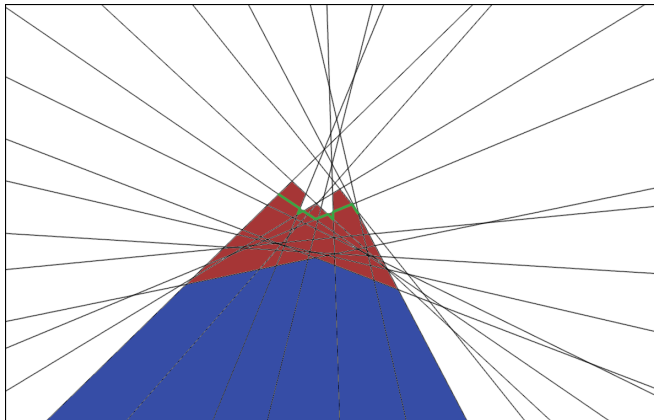
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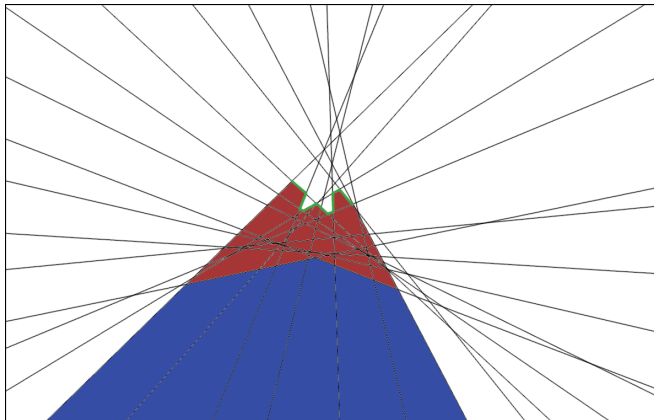
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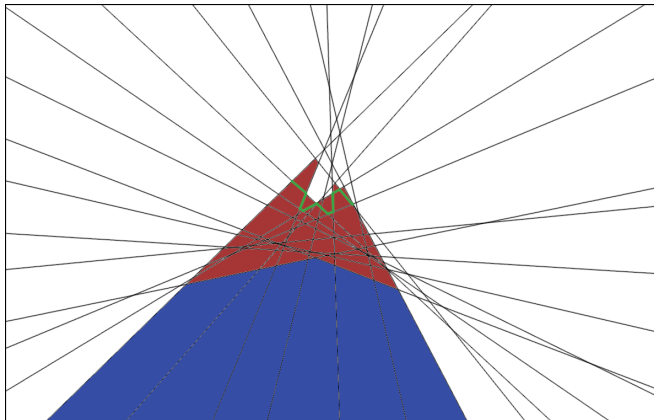


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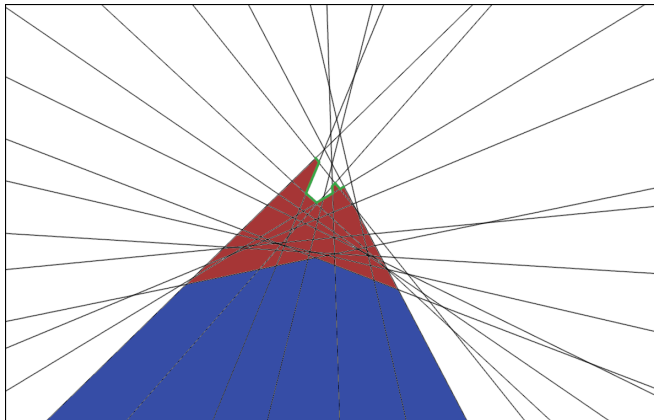




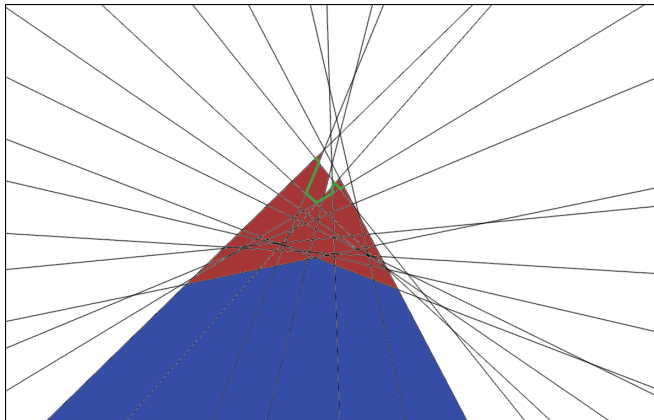
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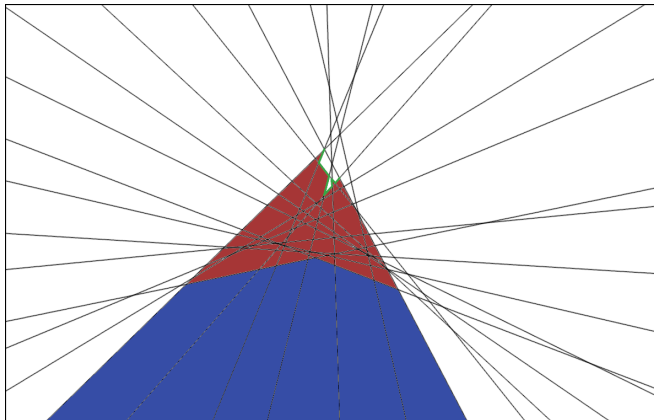
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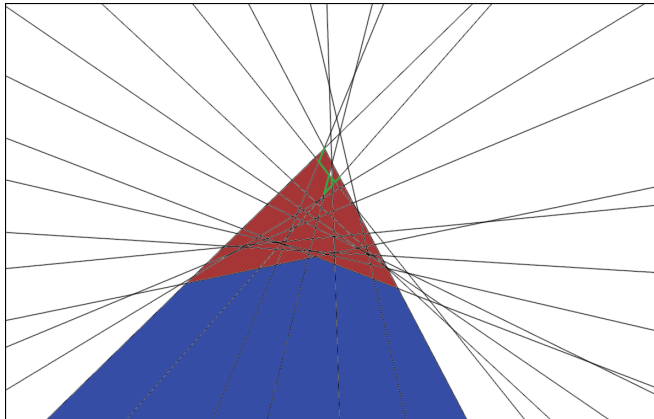
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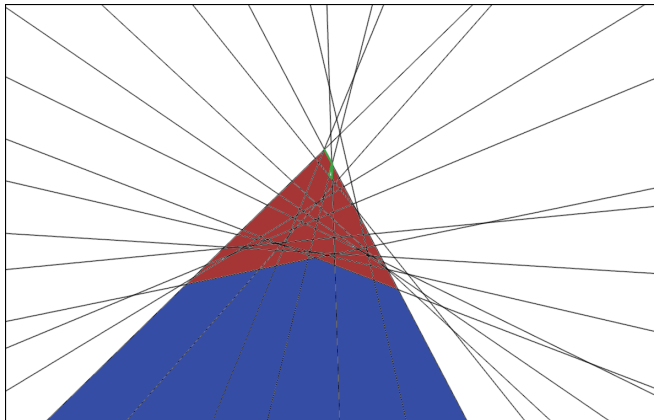
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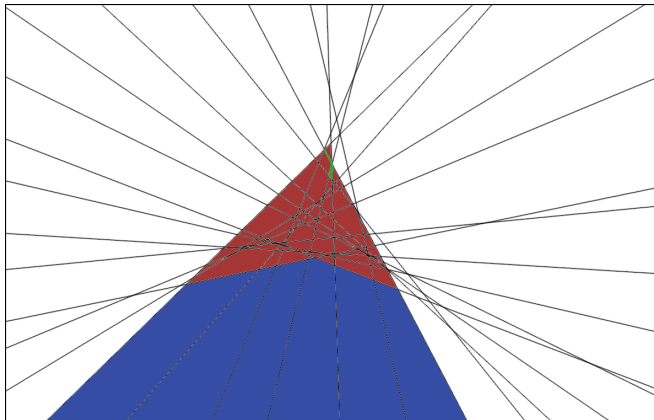
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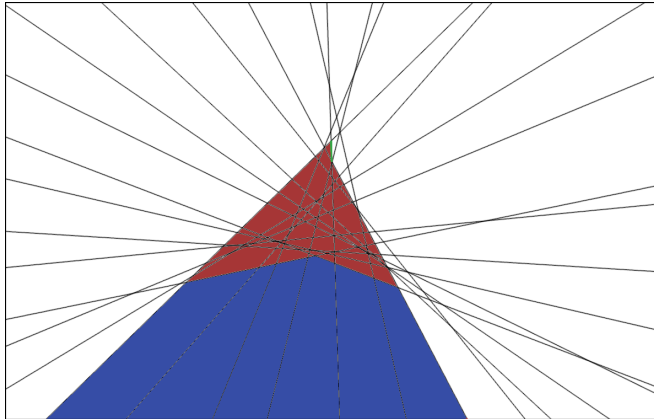
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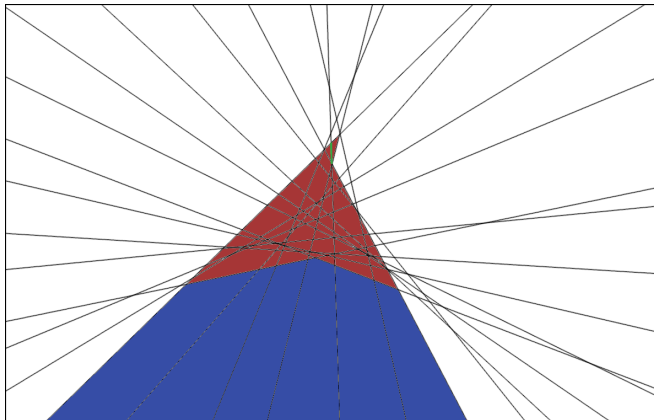


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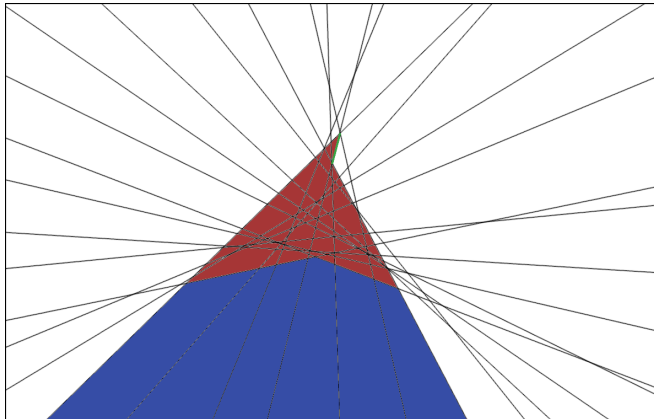




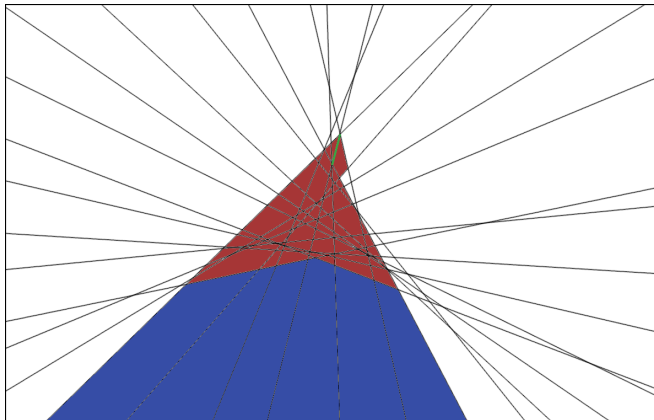
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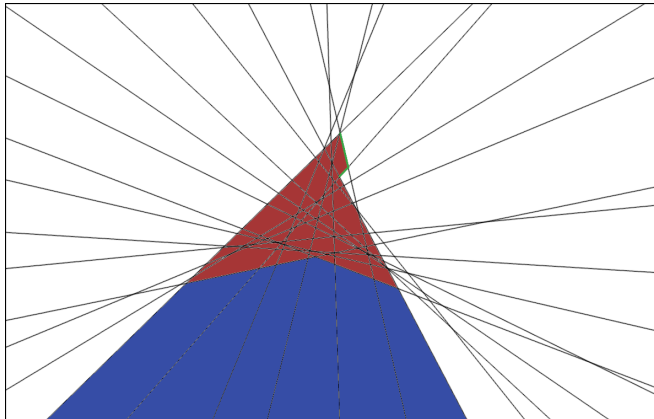
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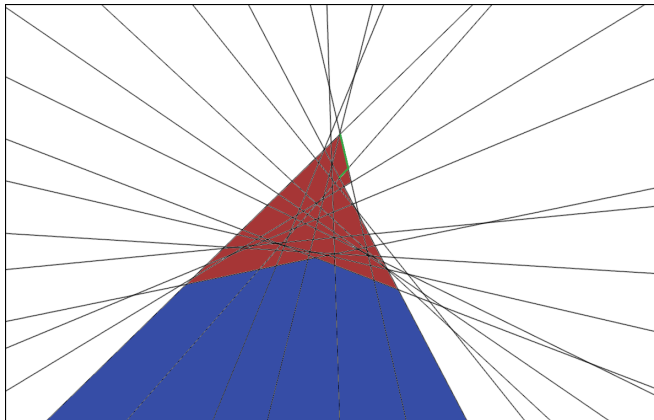
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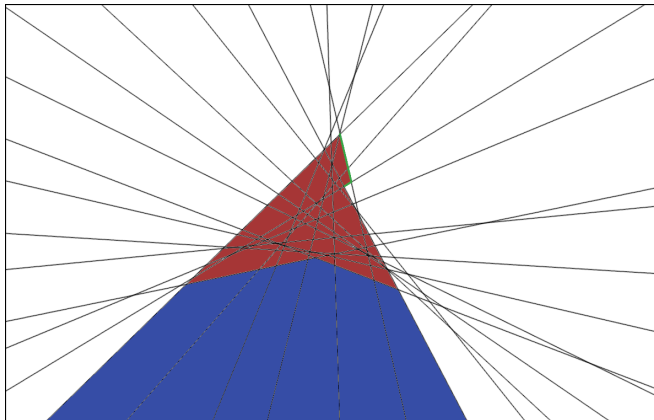
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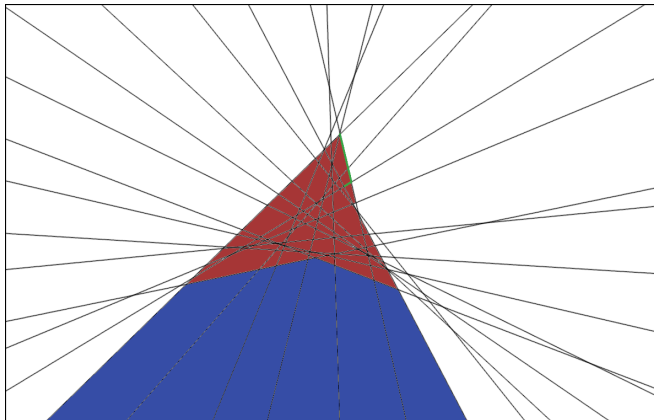
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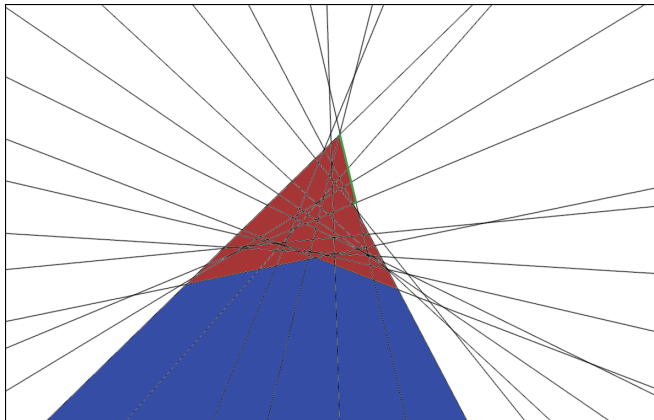
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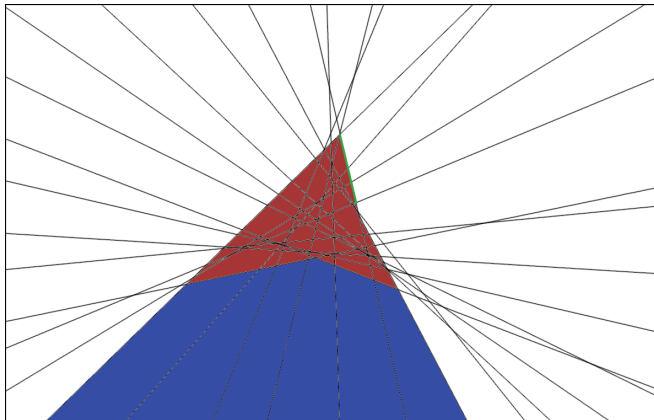


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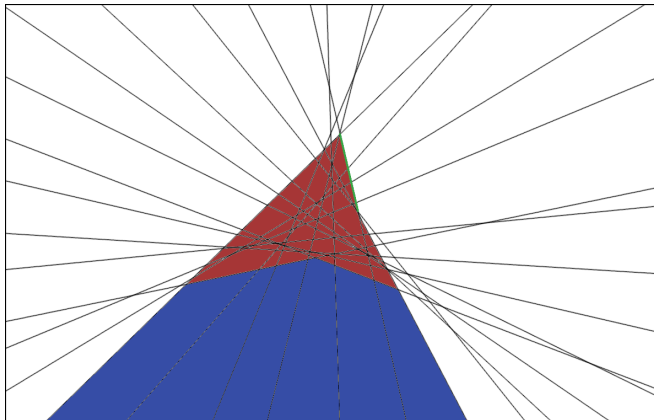




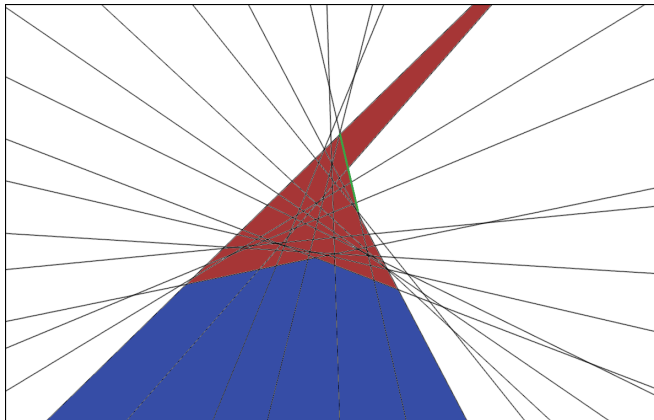
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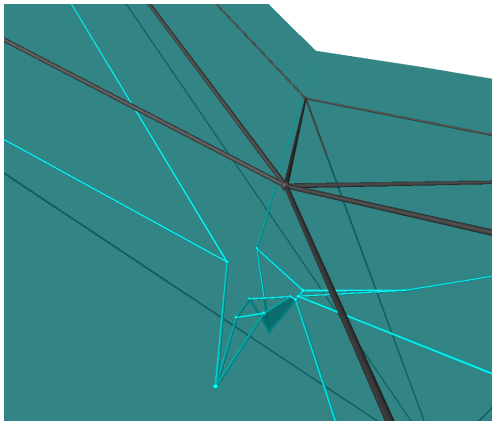
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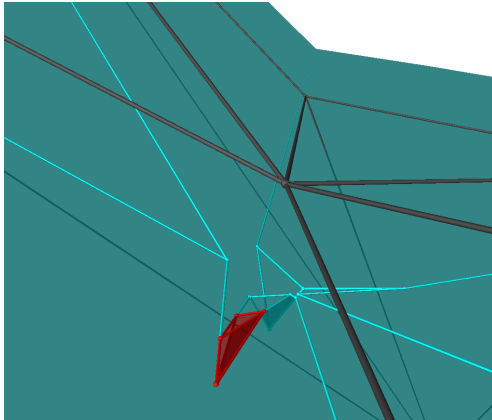
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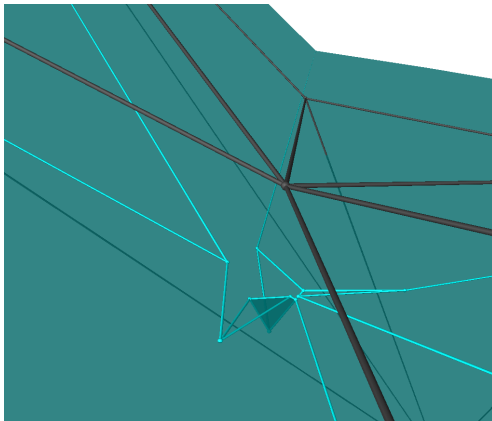
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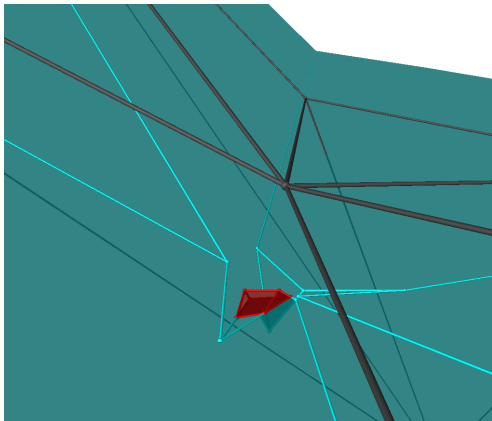
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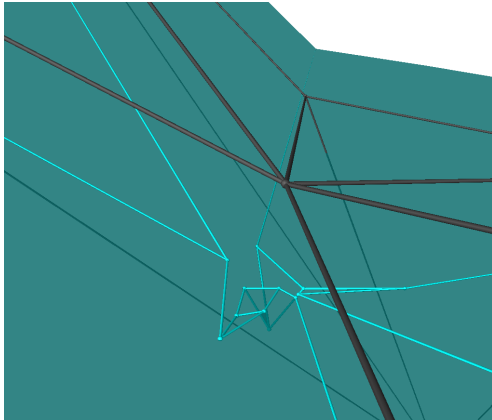
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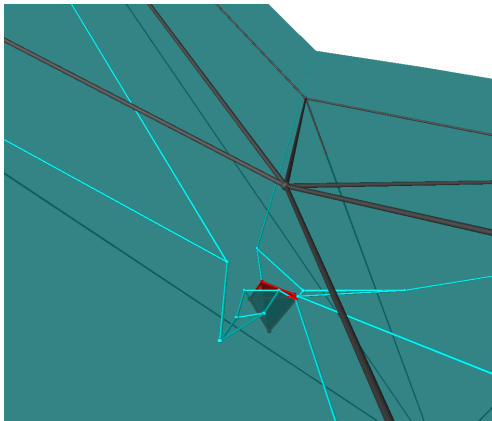


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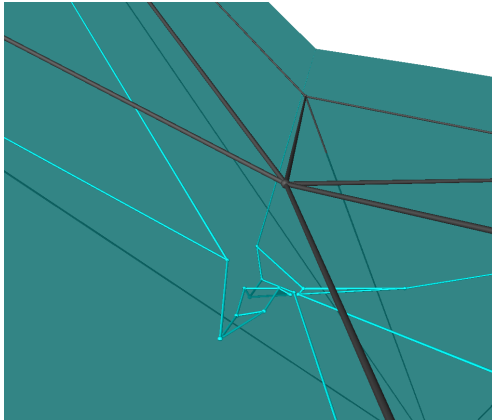




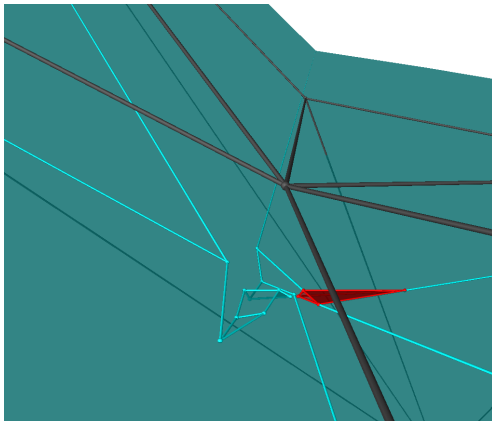
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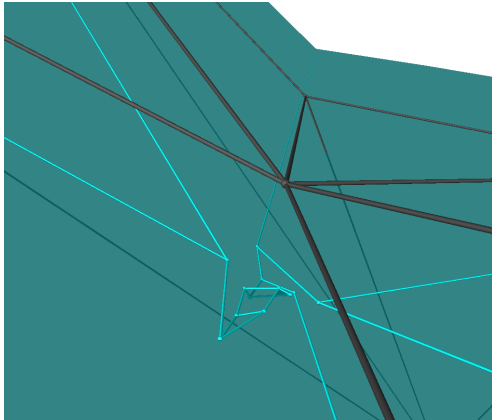
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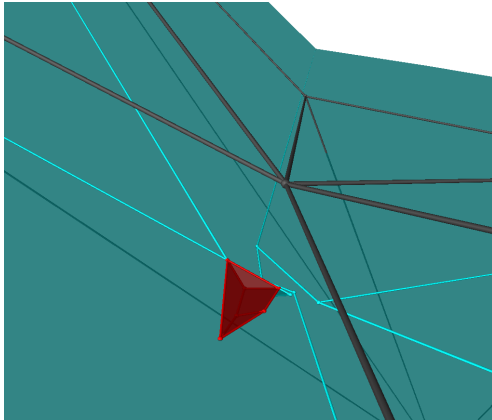
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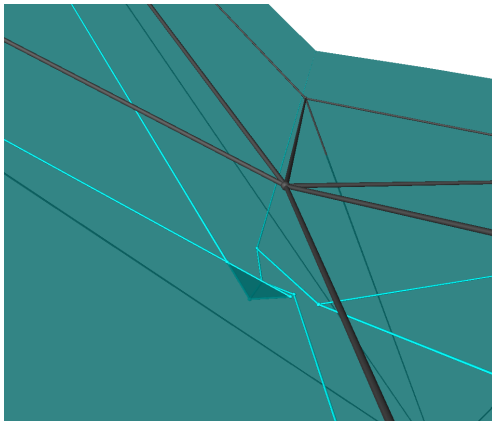
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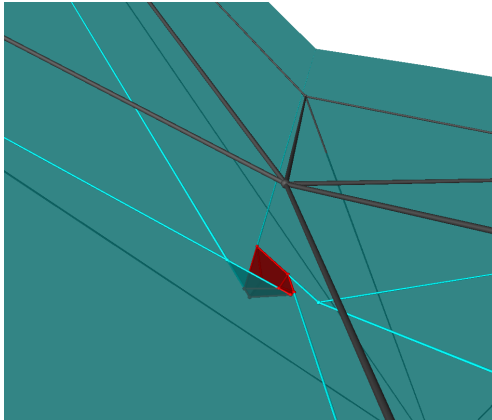
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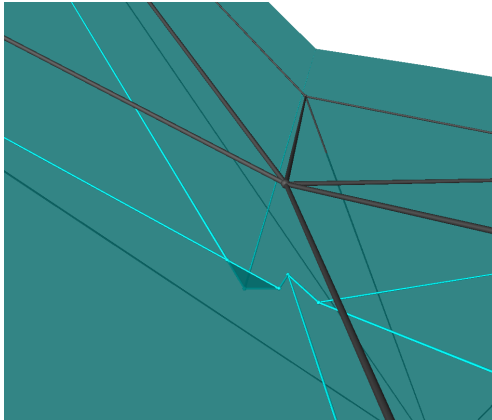
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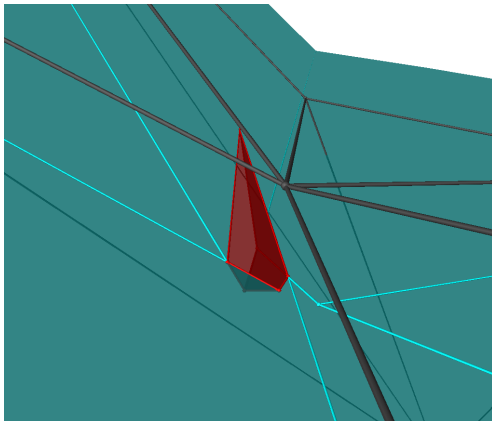


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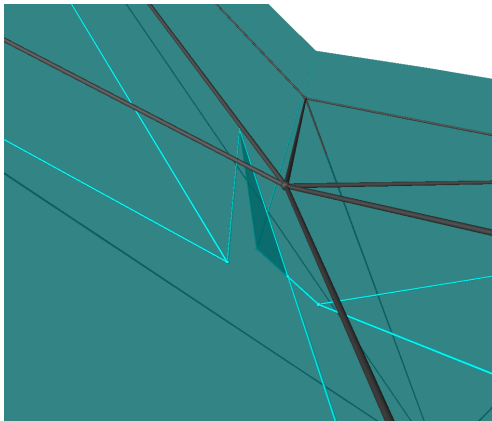




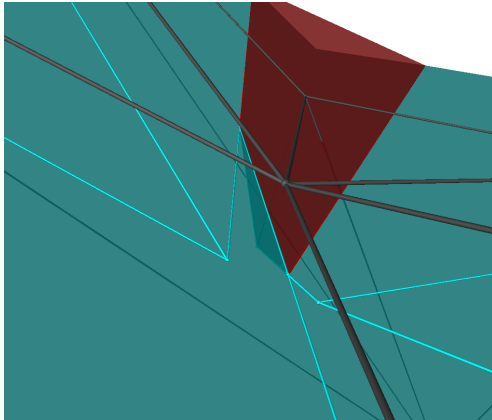
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## Way out

- Try random order, start again when fail
- Works for all vertices of our various test polytopes
- May take longer time for very high-degree vertices
- Nice byproduct: Many valid surfaces
  - We can choose the one with minimum number of convex/reflex edges
  - Optimize other criteria

# Implementation perspective

- Software solution using C++
- All algorithmic steps are implemented
- With the developed software, one can find a valid offset surface for a given event vertex
- Implementation was tested with many polytopes (several 100)
- Implementation is numerically robust

# Software runtime: computing $\mathcal{A}(v)$

- In theory,  $\Theta(n^3 \log n)$ , where  $n$  is the number of unique offset planes ( $\leq$  facet-degree of  $v$ )
  - Implementation runs rather fast (on my machine 😊):
    - 10 Planes:  $< 0.05$  s
    - 20 Planes:  $< 0.5$  s
    - 30 Planes:  $\approx 1$  s
    - 40 Planes:  $\approx 2.4$  s
    - 50 Planes:  $\approx 6$  s
- }  $n > 10$  rare in practice

# Software runtime: Single splitting

- Theoretical runtime still needs to be investigated
- Depends on  $k$ , number of merged unbounded and bounded cells
- A few examples:
  - `convex_vertex_7.obj`: < 0.05 s
  - `kiev_7.obj`: < 0.05 s
  - `saddle_10.obj`: < 0.2 s

## Software runtime: Initial splittings

- Algorithm is applied for each eligible vertex on the polytope
- A few examples:
  - `journal_verworrtakelt.obj` (66 split vertices):  $\approx 0.8$  s
  - `journal_lion.obj` (85 split vertices):  $\approx 1.2$  s
  - `journal_venus.obj` (142 split vertices):  $\approx 1.8$  s
  - `journal_bunny.obj` (144 split vertices):  $\approx 2.2$  s



## Future work

- Glue the offset surfaces for the vertices to the polytope
- Speed up event detection later during the shrinking process
  - Initially, the event detection is just checking the degree of vertices
- Find a method of generating a provably successful cell adding order